

# Engineering Requirements for High-Assurance Applications

Axel van Lamsweerde

University of Louvain

B-1348 Louvain-la-Neuve

[avl@info.ucl.ac.be](mailto:avl@info.ucl.ac.be)

SecappDev '08, Leuven, March 2008

# High-Assurance Applications (HA)

McLean'95

Applications where *compelling evidence* is required that the system delivers its *services* in a manner that satisfies certain critical properties such as:

*safety,*

*security,*

*survivability,*

*fault tolerance*

## High-Assurance Applications (2)

**Survivability:** ability of a system to fulfill its mission in a timely manner even in the presence of (external) incidents or attacks

**Fault tolerance:** ability to avoid or mitigate failure even in case of fault

**Fault:** (internal) cause of failure

**Failure:** deviation between actual & specified behavior

# HA applications: problems & challenges

- ◆ The later software defects are found, the more expensive & dangerous they are ...



- Start caring for high assurance *early*, i.e. at requirements engineering time
- Preserve high assurance at every transition to downstream artefacts (architecture, test data, code)

## HA applications: problems & challenges (2)

- ◆ A posteriori detection & fix of software defects may endlessly generate other defects ...



- Adopt a constructive approach where high assurance is granted *by construction*

## HA applications: problems & challenges (3)

- ◆ High assurance requires much stronger level of confidence ...



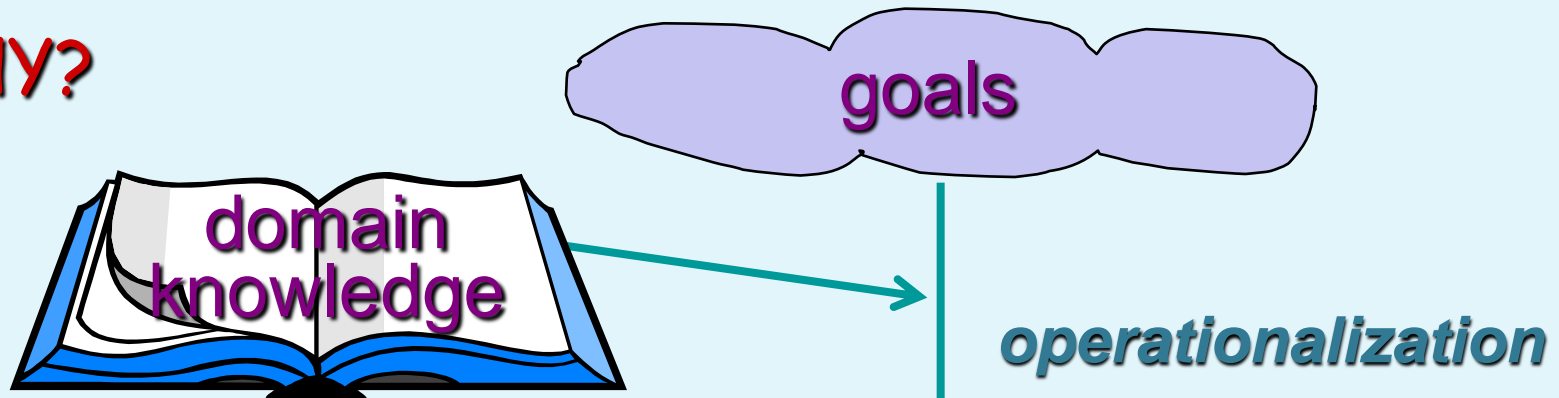
- *Stronger confidence* requires more **formal** elaboration & analysis (supported by tools)
- *Usability* at requirements engineering time requires **lightweight** techniques

# Requirements engineering for HA applications: problems & challenges

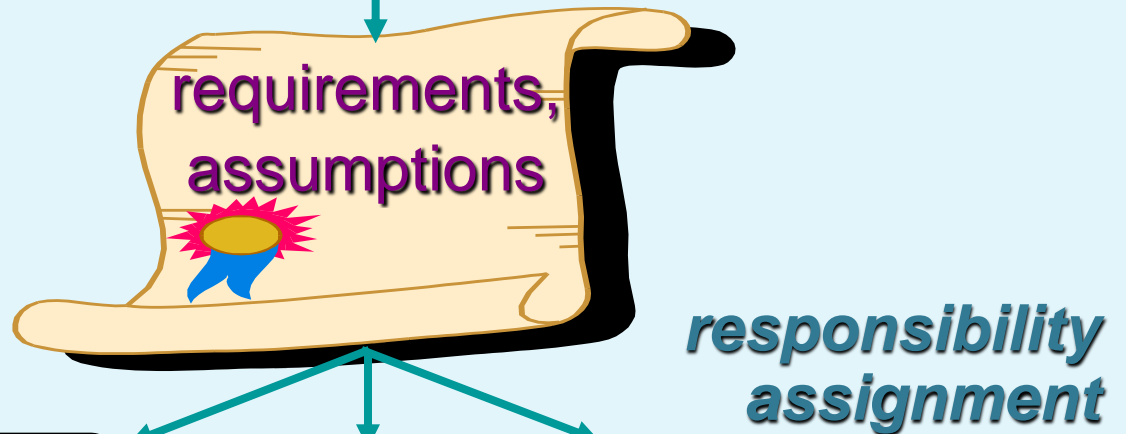
- ◆ Requirements Engineering (RE) ≠  
translating informal requirements into  $\pm$  formal model
- ◆ Requirements are not there, you need to ...
  - elicit them,
  - evaluate them,
  - structure & document them,
  - analyze them,
  - modify them

# RE: the WHY, WHAT, WHO dimensions

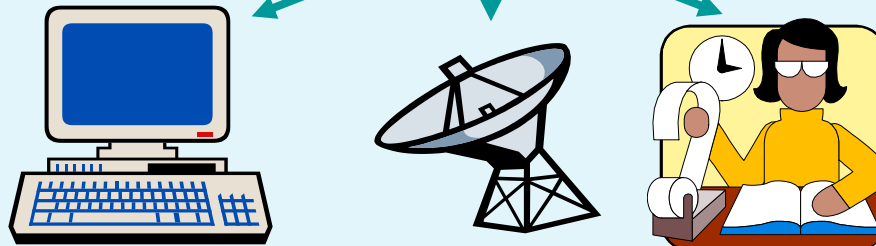
WHY?



WHAT?

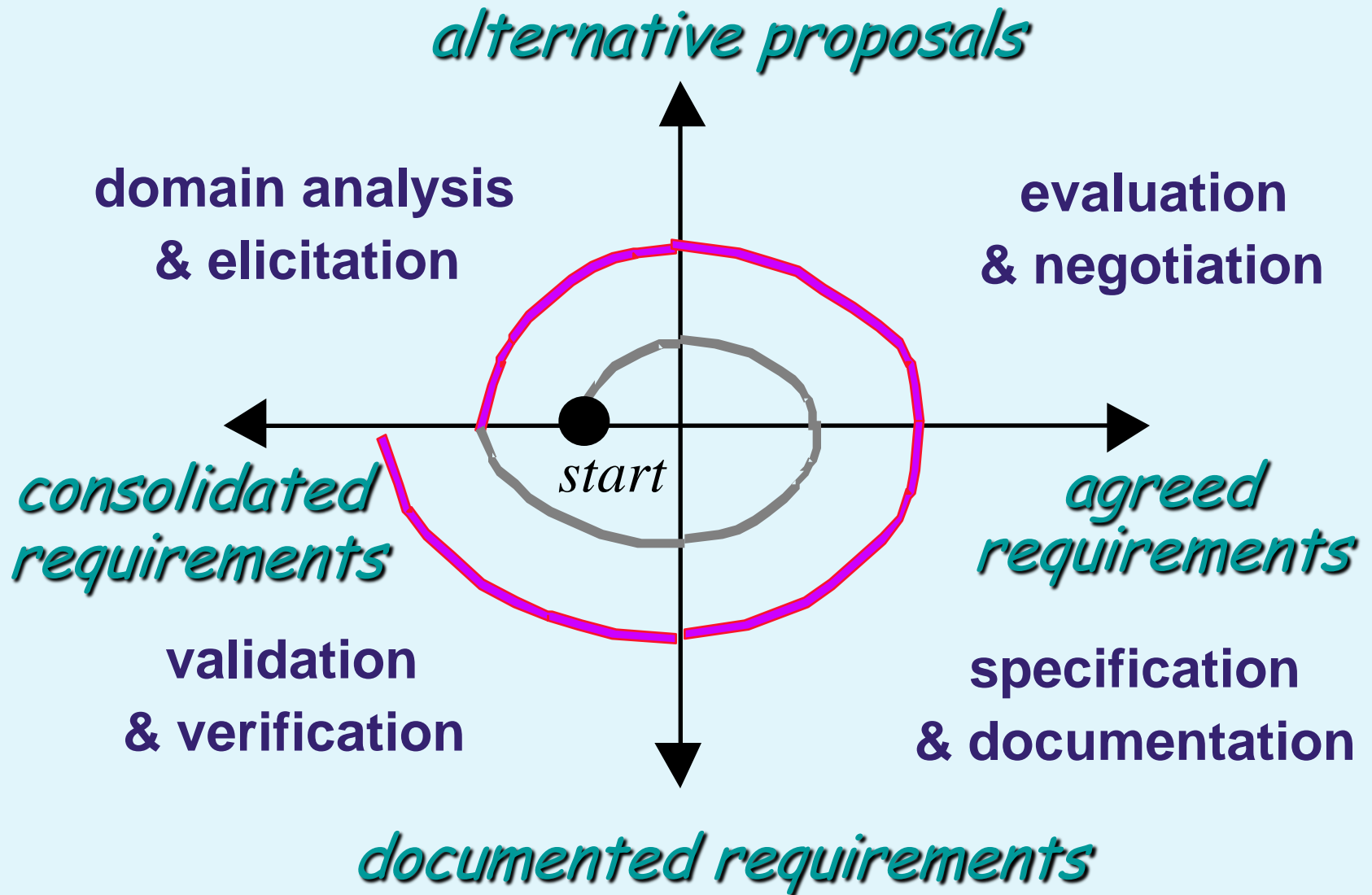


WHO?





# RE: an iterative process





## Requirements engineering is hard ...

- ◆ System = software + environment (possibly malicious)
- ◆ Involves 2 systems: system-as-is, system-to-be
- ◆ Ranges from high-level, strategic objectives to detailed, technical requirements
- ◆ Requires evaluation of alternatives
- ◆ Raises conflicting concerns
- ◆ Requires anticipation of unexpected behaviors (for requirements completeness, system robustness)

# Security engineering: problem space vs. solution space

## Software layers

*e-shopping*

Application



*remote file access, SSH, SSL, ...*

System / Languages

*authentication, key exchange*

Protocols

*encryption, signature*

Crypto

## Security guarantee

Applic

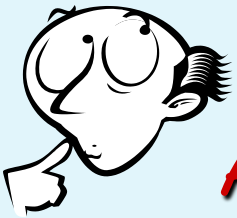
Syst / Lang

Protocols

Crypto

# Focus of these lectures

- ◆ Critical properties in HA systems
- ◆ *In particular: security at upper, application layer*
- ◆ Application is secure iff it satisfies a “complete” set of security goals
  - about confidentiality, integrity, availability, privacy, ...
- ◆ Necessary condition for application security:  
*security goals must be made explicit, precise, complete, adequate, non-conflicting*



## A RE method for HA applications should be ...

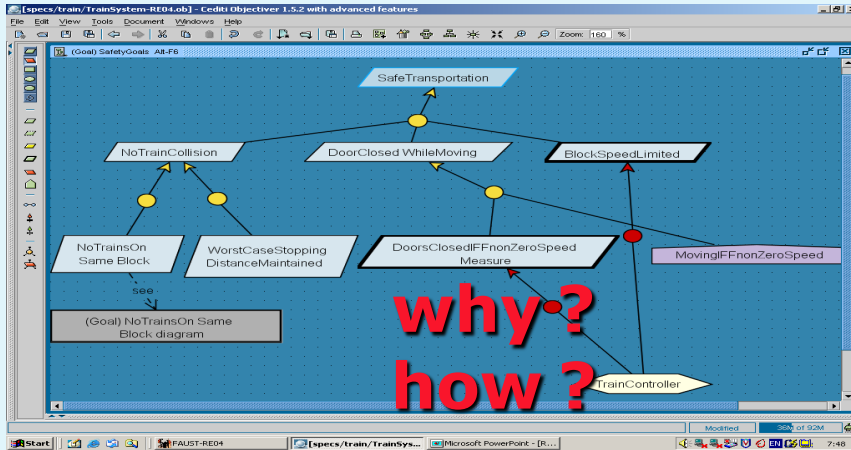
- **Goal-oriented:** to ensure that requirements satisfy system objectives -- notably, *safety, security goals*
- **Incremental:** for *early* analysis of partial models
- **Constructive:** for analyst guidance & confidence
- **Model-based:** for abstraction & structure
  - Multiple models:* for capturing multiple facets
- **Mix declarative and operational** styles as needed
- **Formal when and where needed, but *lightweight***

# Course outline

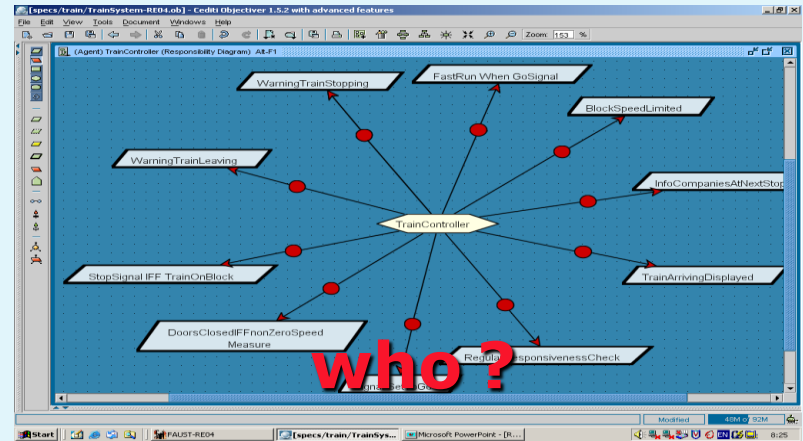
- ◆ Goal-oriented RE for high-assurance applications
  - Modeling goals, objects, agents, operations, behaviors
  - A goal-oriented model building method in action
  - Obstacle analysis for high assurance
  - Formal reasoning about models
- ◆ Engineering security requirements
  - Security goals and their specification
  - Threat analysis for model consolidation
  - Analyzing conflicts among security goals
  - Model checking against confidentiality requirements

# What models ?

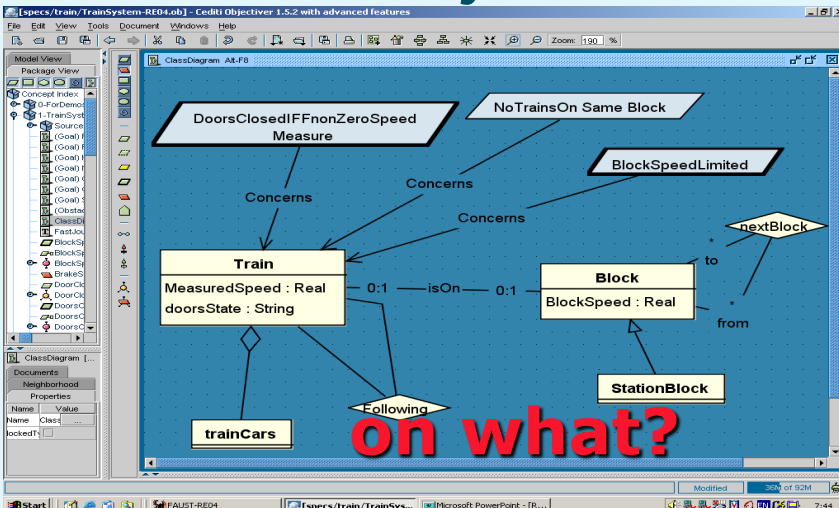
## Goals



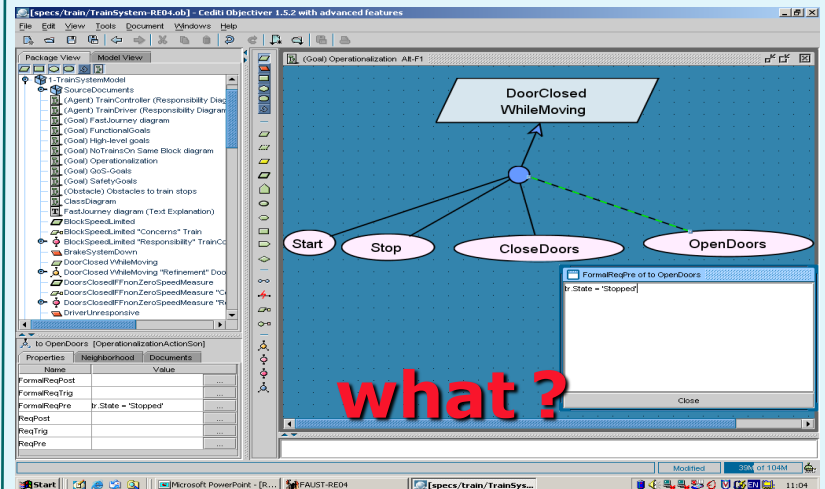
## Agents, responsibilities



## Objects

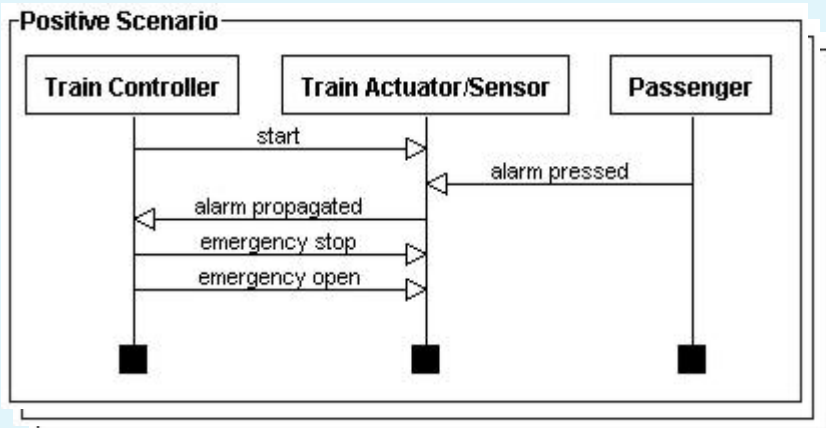


## Operations

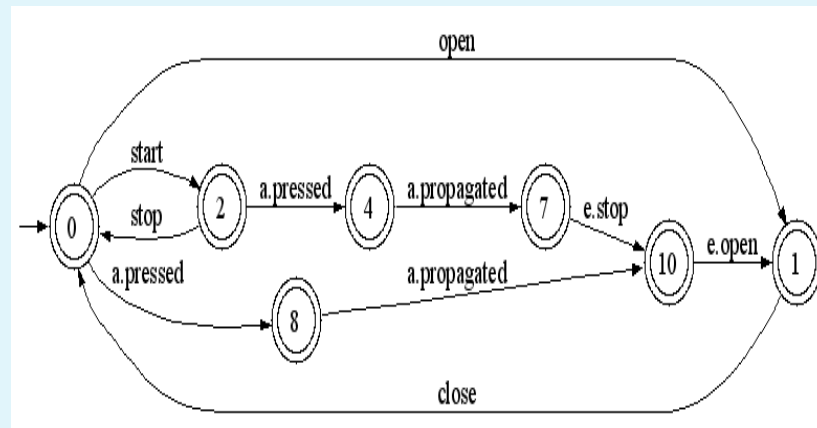


# What models ? (2)

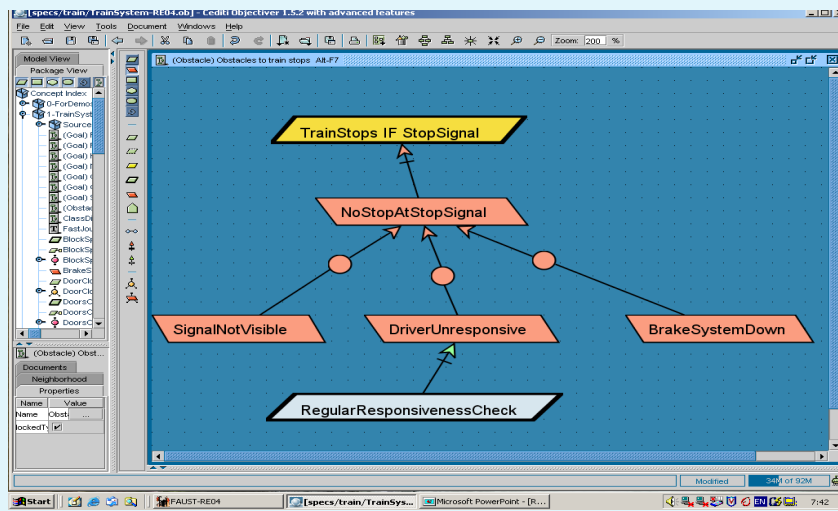
## Interaction scenarios



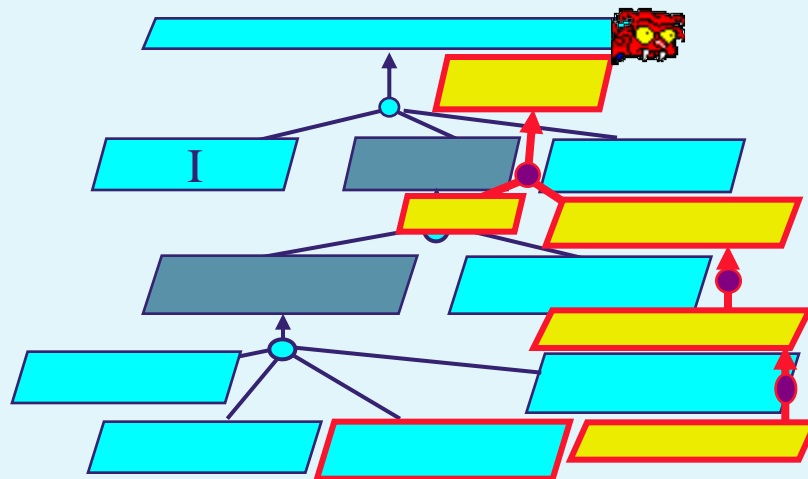
## Behaviors



## Hazards



## Threats







# The goal model

- ◆ Intentional view of the system being modeled
- ◆ Goal = objective to be achieved by *system* ...
  - *prescriptive* statement of intent about system
  - system (as-is, to-be) = software + environment
    - “E-money shall be paid only if sufficient e-purse balance”
- ◆ ... unlike domain property ...
  - *descriptive* statement about environment
    - “Paid money is no longer in purse”



# Goals in a goal model have different granularities & abstraction levels

- ◆ Higher-level, coarser-grained goals ...  
strategic, global, business-specific

“Cash-free payment supported anywhere anytime”

- ◆ Lower-level, finer-grained goals ...  
technical, local, design-specific

“E-purses shall have a max capacity of  $X$  euros”



## Goals in a goal model are of different types

- ◆ Behavioral goals prescribe maximal sets of admissible system behaviors

*Achieve [TargetCondition]:*

if CurrentCondition then sooner-or-later TargetCondition

Achieve [E-moneyMovedAsNeeded]

*Maintain [GoodCondition]:*

always (if CurrentCondition then GoodCondition)

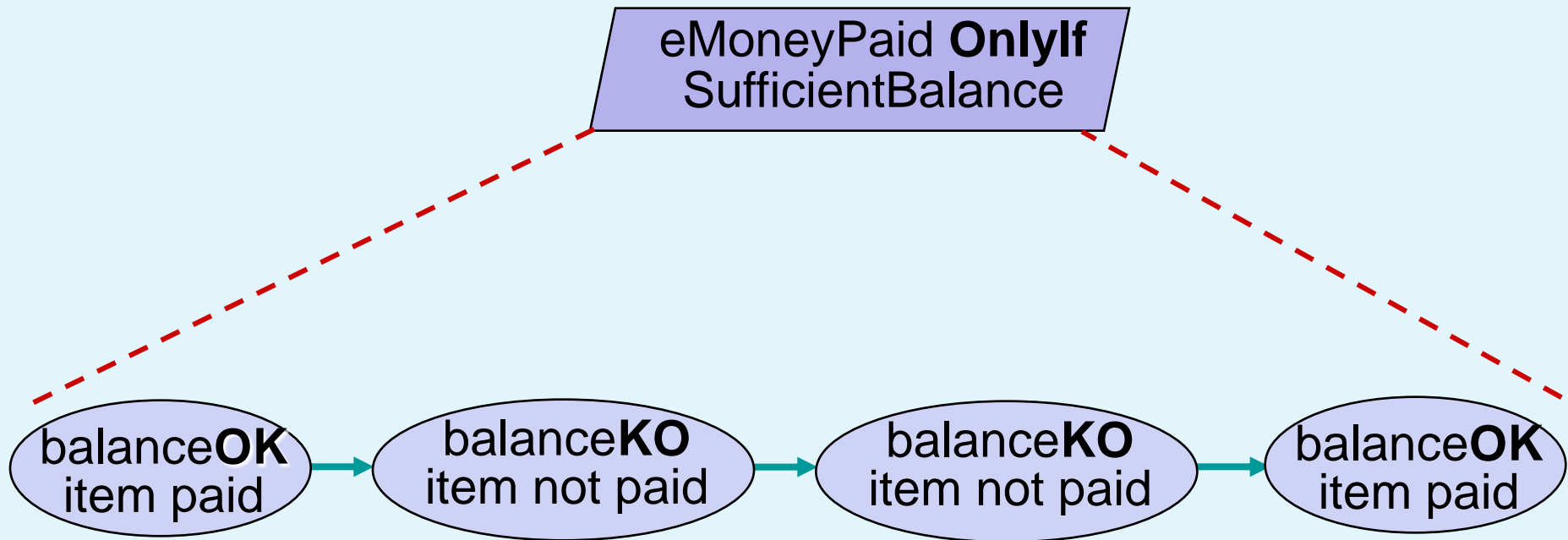
Maintain [E-moneyAccuratelyStored]

*Avoid [BadCondition]:*

never (if CurrentCondition then BadCondition)

Avoid [E-purseBalanceDisclosedToNonOwners]

# Behavioral goals prescribe intended behaviors declaratively





## Goals in a goal model are of different types (2)

- ◆ Soft goals prescribe preferences among alternative system behaviors
  - cannot be established in a clear-cut sense
  - used to *compare alternative options*

*Improve, Increase, Reduce, ... [TargetCondition]*

Reduce [BankClerkWorkload]



Achieve [ePurseLoadedAtATM]

*preferred over*

Achieve [ePurseLoadedAtBank]



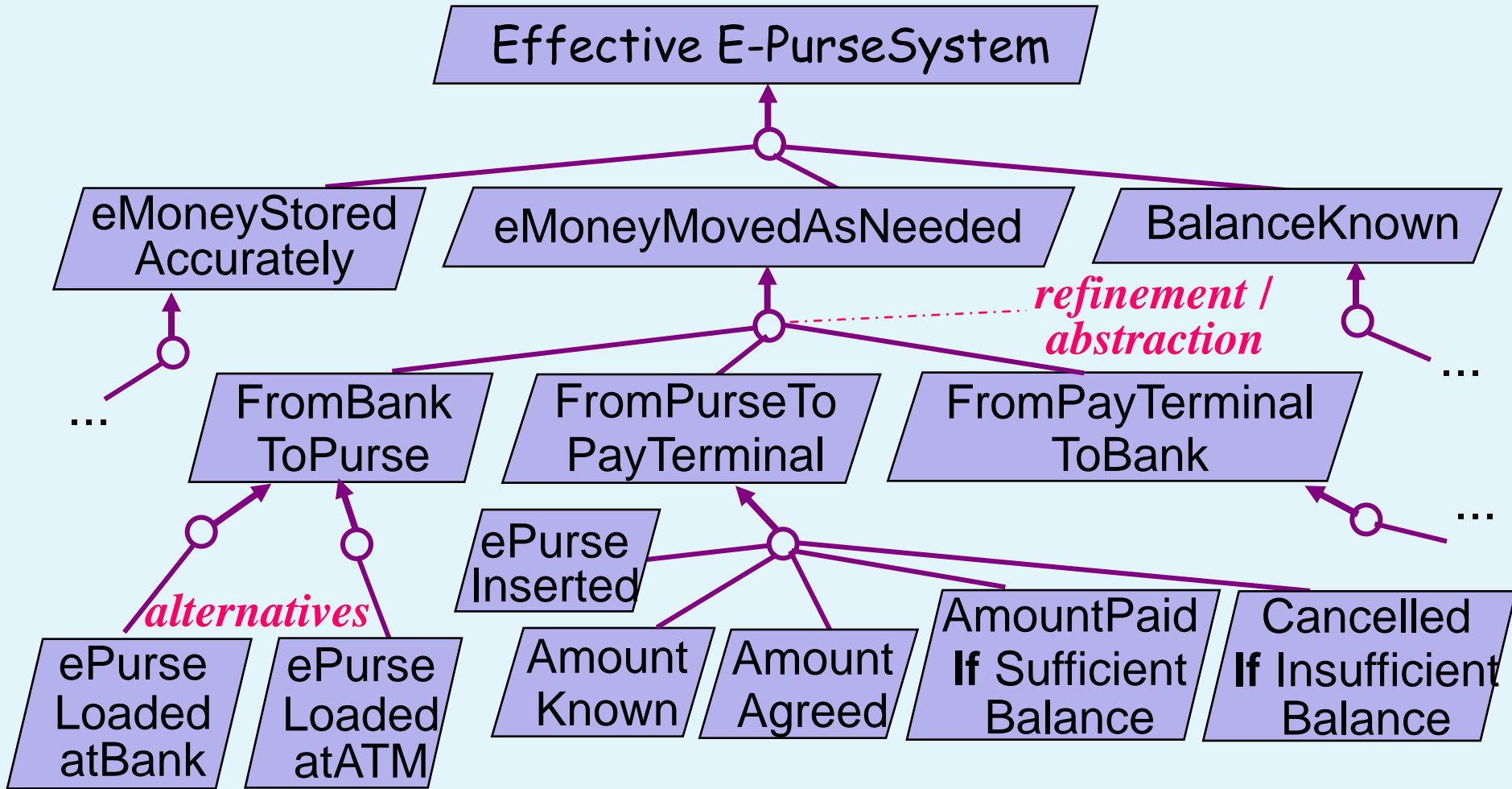
## Goals in a goal model are of different categories

- ◆ **Functional** goals state intent behind system services
  - Used to build operational models: use cases, state machines, task workflows, ...

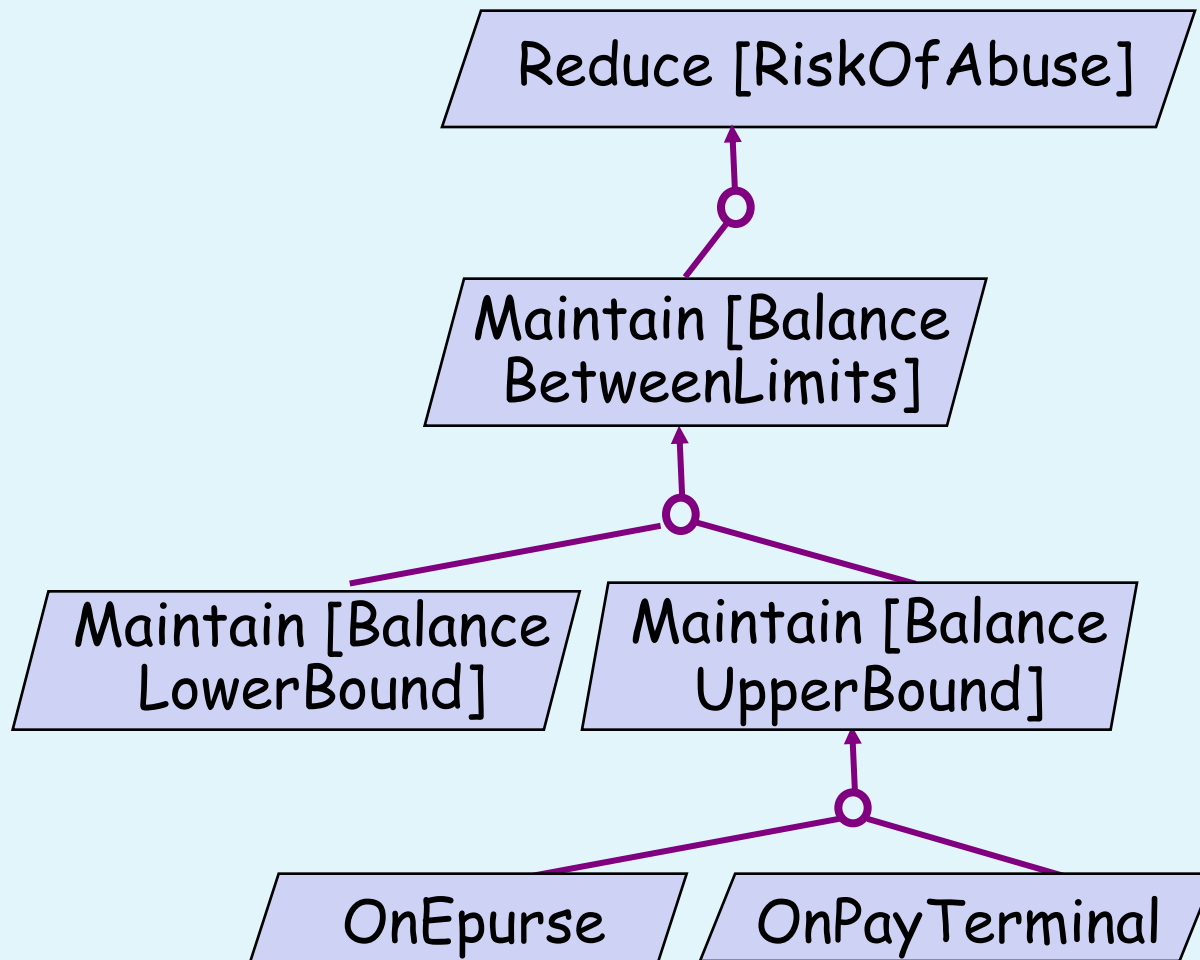
`EmoneyMovedFromEpurseToPayTerminal`

- ◆ **Quality** goals constrain quality of service ("non-functional goals")
  - About **security**, **safety**, **accuracy**, usability, cost, performance, interoperability, etc.
    - Maintain [`eMoneyStoredAccurately`], Improve [`PurseUsability`]
  - Some are softgoals (e.g. "ility" goals)
  - Often conflicting

# The goal model shows contribution links



# Refining a security soft goal into behavioral goals







# Goal specifications annotate the goal model

## Goal *Achieve* [AmountPaid If SufficientBalance]

**Def** *A payment shall be done for some input amount through e-purse debit and pay terminal credit if the amount is OK-ed by the payer and the e-purse balance is higher or equal to this amount*

[ **FormalSpec**  $\forall ep: e\text{-Purse}, pterm: PayTerminal, p: Payer$   
Inserted ( $ep, p, pterm$ )  $\wedge$  OK ( $pterm.InputAmount, p$ )  
 $\wedge pterm.InputAmount \leq ep.Balance$   
 $\Rightarrow \circ (pterm.Balance = \bullet pterm.Balance + pterm.InputAmount$   
 $\wedge ep.Balance = \bullet ep.Balance - pterm.InputAmount)$  ]

[ Priority Highest ]

...

Optional formalization in *real-time temporal logic*

("next", "always", "sooner-or-later", ...) for formal reasoning



## Goal satisfaction requires agent cooperation

- ◆ Agent = role (rather than individual)  
responsible for goal satisfaction

Achieve [eMoneyMovedFromPurseToPayTerminal] ↔

Payee, Payer, ePurse, PayTerminal

- ◆ Agent types:

- software  
(software-to-be, legacy software, COTS components,  
foreign components)
- devices (sensors, actuators, ...)
- humans playing specific roles



## Goal satisfaction requires agent cooperation (2)

- ◆ Finer-grained goal  $\Rightarrow$  fewer agents required for goal satisfaction

- ◆ Requirement = goal assigned to single agent in *software-to-be*

Achieve [AmountDebitedIfSufficientBalance]

$\leftrightarrow$  ePurse

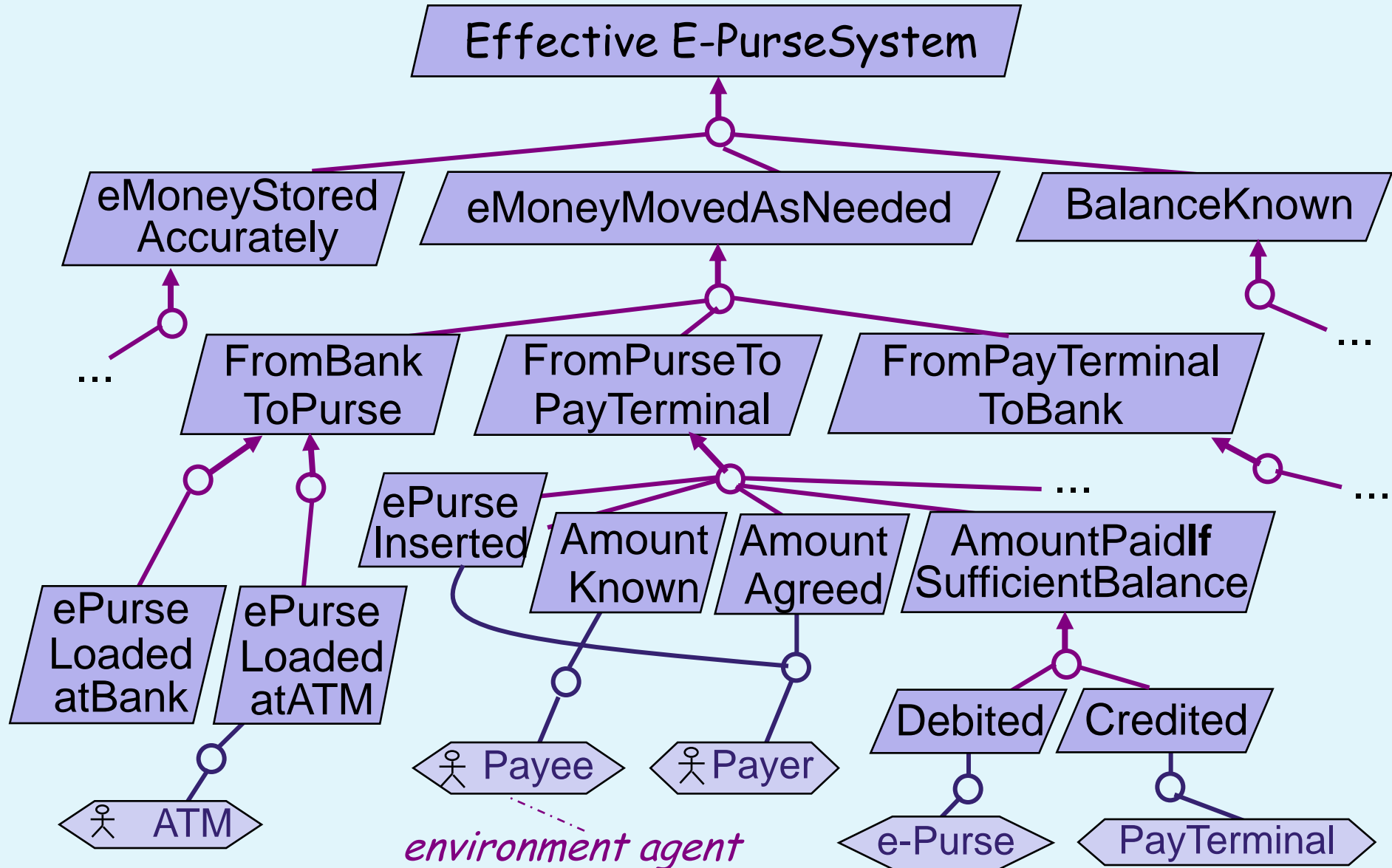
Achieve [AmountCreditedIfDebited]

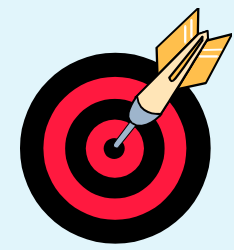
$\leftrightarrow$  PayTerminal

- ◆ Expectation = goal assigned to single agent in *environment*

Achieve [AmountAgreed]  $\leftrightarrow$  Payer

# Goals are refined until single responsibilities can be assigned





## WHY are goals so important ?

- ◆ Abstraction level for strategic stakeholders (decision makers)
- ◆ Force environment assumptions to be made explicit
- ◆ Criterion for requirements **completeness**

REQ is complete **if** for all  $G$ :

$\{REQ, EXPECT, Dom\} \models G$

- ◆ Criterion for requirements **relevance**

$r$  in REQ is pertinent **if** for some  $G$ :

$r$  is used in  $\{REQ, EXPECT, Dom\} \models G$

# High assurance requires satisfaction arguments

- ◆ Informal argument at least, formal argument at best

$$R, E, D \vdash G$$

“ in view of properties  $D$  of the domain,  
the requirements  $R$  will achieve goals  $G$   
under expectations  $E$  ”

$R_1$ : amount debited from e-purse

$R_2$ : same amount credited to pay terminal

$D$ : amount paid if debited from e-purse and credited to terminal

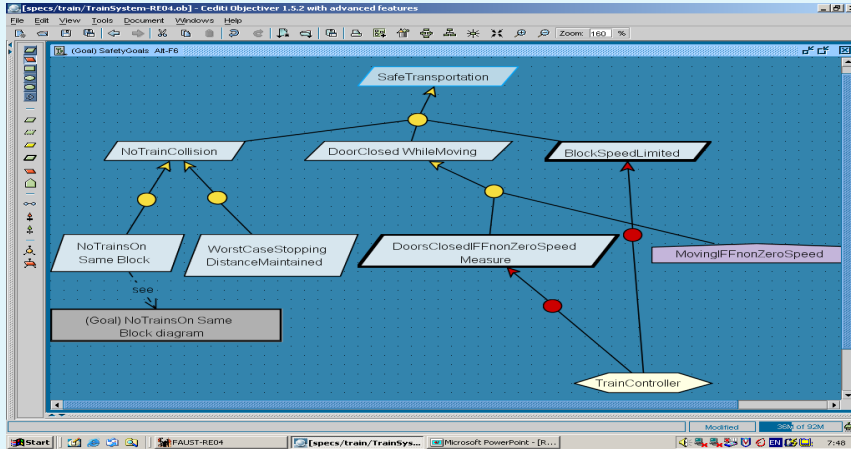
$E$ : amount agreed by payer

$\vdash G$ : amount agreed and paid

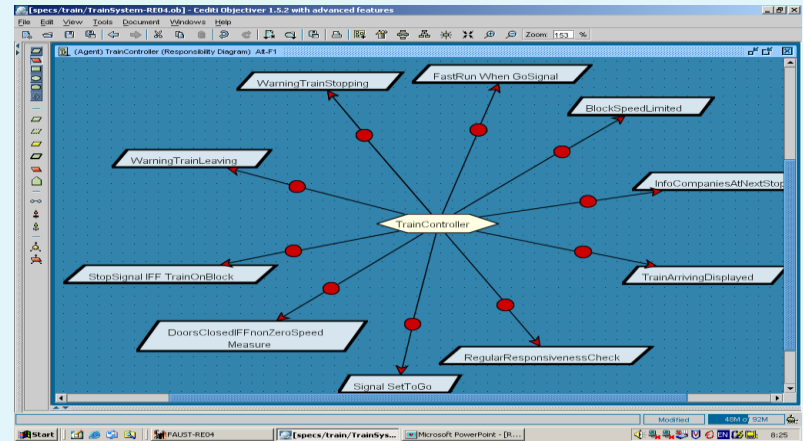
- ◆ A goal model supports satisfaction arguments & traceability links for free

# What models ?

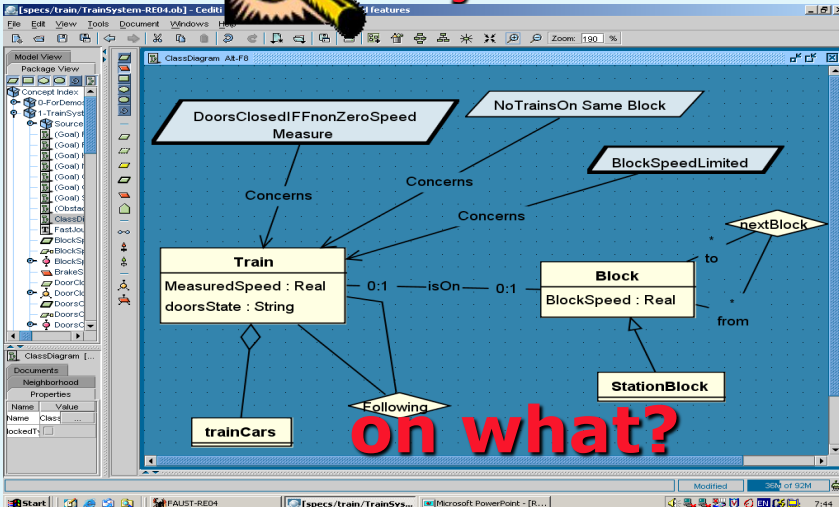
## Goals



## Agents & responsibilities

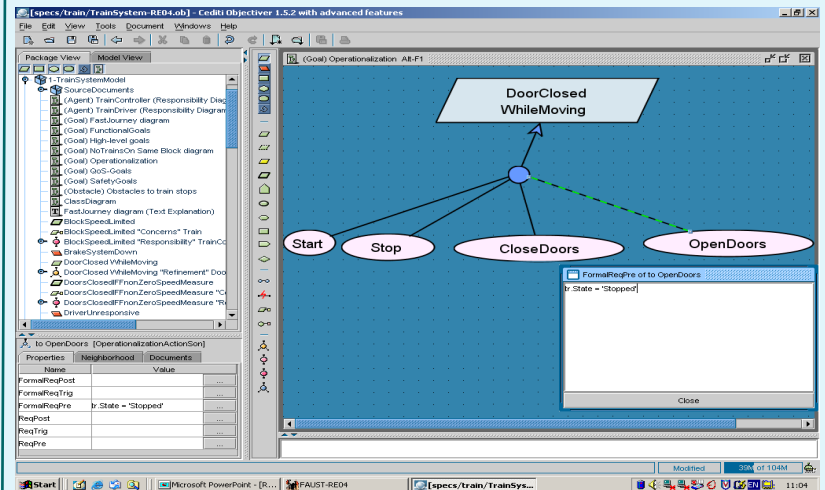


## Objects



on what?

## Operations

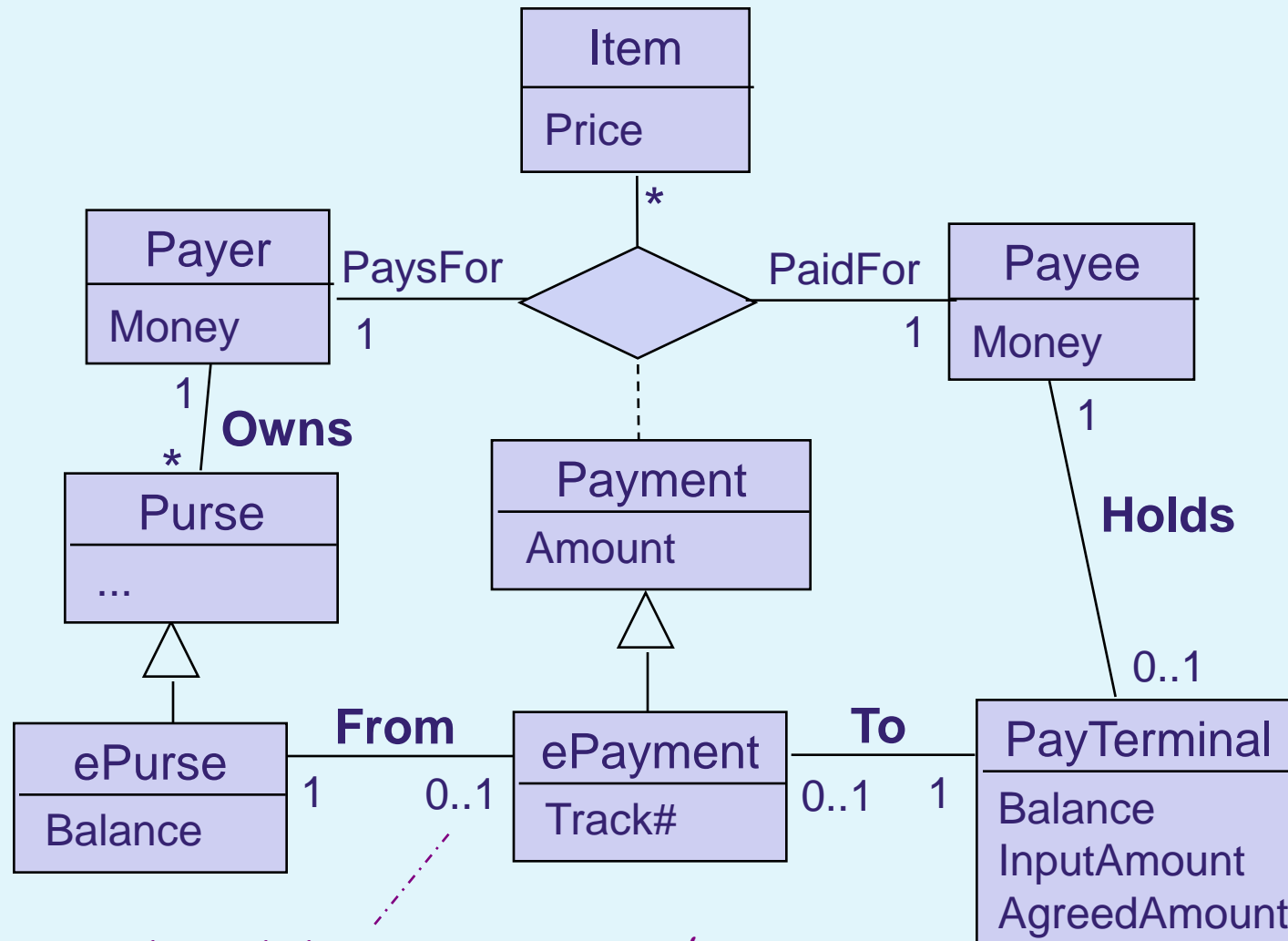


# Modeling objects

- ◆ Structural view of the system being modeled
- ◆ Object = thing of interest in the system  
whose instances ...
  - share similar features (attributes, associations)
  - can be distinctly identified
  - have specific behavior from state to state
- ◆ Object attributes/associations yield state variables
- ◆ Object specializations (at meta level):
  - entity: autonomous object
  - association: object dependent on objects it links
  - event: instantaneous object
  - agent: active object, controls behaviors



# The structure of objects is modeled using UML



*in any system state, an e-purse may be involved in at least 0 and at most 1 e-payment*

# Object specifications annotate the object model

## Relationship Payment

**Def** *Condition for an item to be sold by a payee to a payer*

**DomInvar** An item is paid if its price is debited from the payee and credited to the payer

[ **FormalSpec**  $\forall$  it: Item, pyr: Payer, pye: Payee

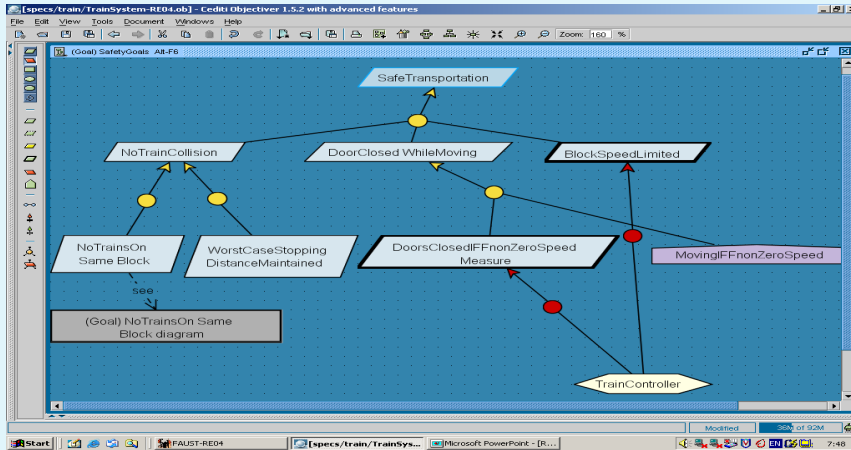
Payment (pyr, pye, it)  $\Rightarrow$  pyr.Money = ● pyr.Money - it.Price

$\wedge$  pye.Money = ● pye.Money + it.Price ]

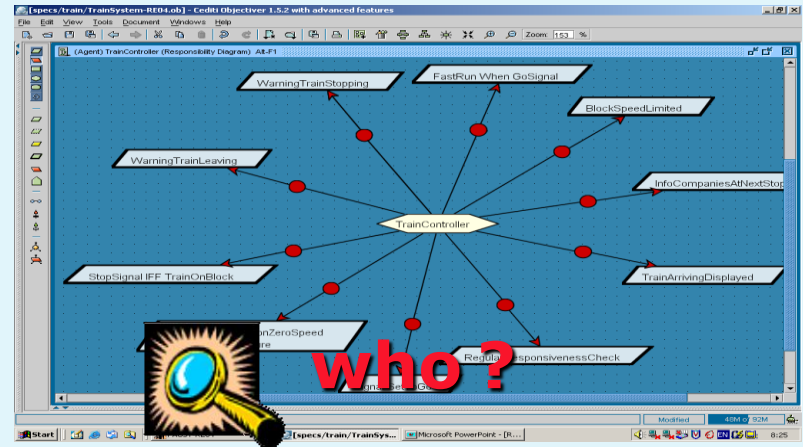
*domain properties*

# What models ?

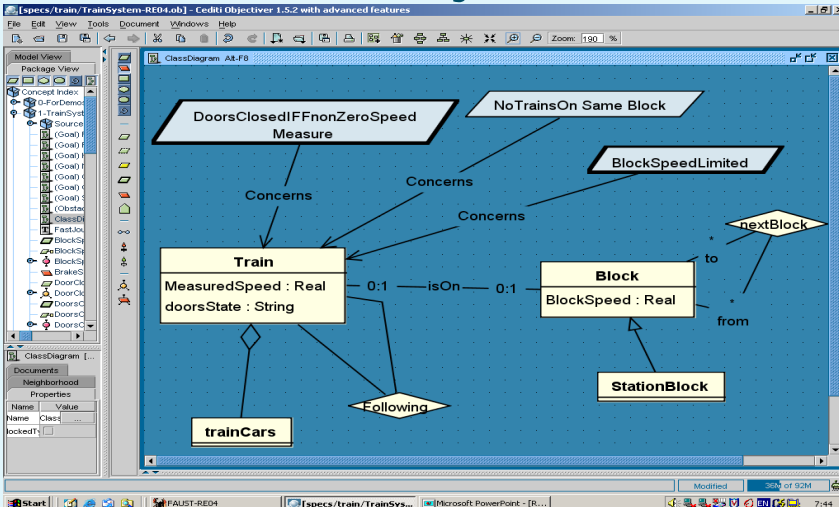
## Goals



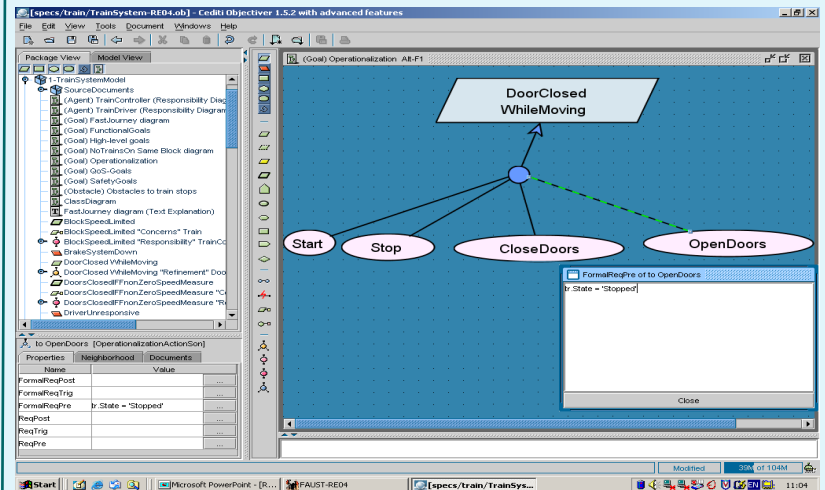
## Agents & responsibilities



## Objects



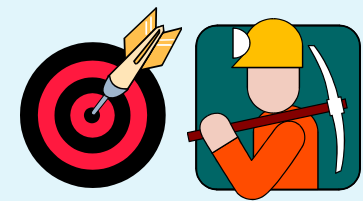
## Operations





# Modeling agents

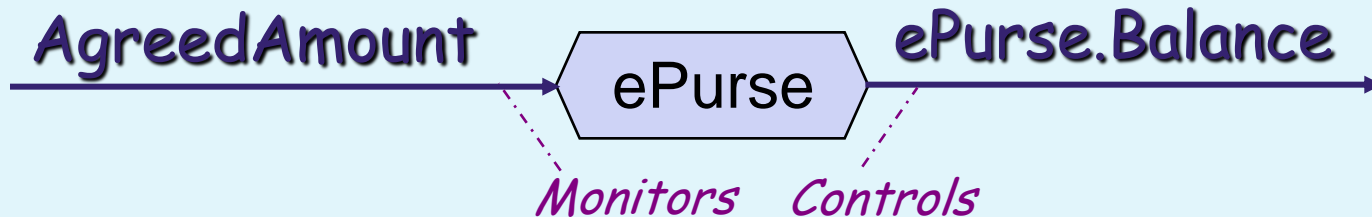
- ◆ Responsibility view of the system being modeled:  
who is in charge of what
- ◆ Agent :
  - (Role rather than individual -- software, device, human)
  - Active object: *monitors & controls* state variables  
(through *operations* on attrib, assoc)
  - Runs concurrently with others
  - Agent responsible for goal ⇒  
must restrict system behaviors  
goal must be *realizable* by agent



## Goal realizability by an agent

- ◆ A goal is *realizable* by an agent *iff* its *monitoring & control* capabilities enable it/her to satisfy the goal in view of known domain properties (without more restrictions than required by  $G$ )
- ◆ A goal is *unrealizable* by an agent because of ...
  - lack of monitorability of variables to be evaluated
  - lack of controllability of variables to be constrained
  - reference to future
  - conditional unsatisfiability (aka conflict with other goals)
  - unbounded achievement (liveness property)

# Goal realizability & agent capabilities: examples



## Example 1: Realizable by ePurse

$\text{AgreedAmount} \leq \text{ep.Balance} \Rightarrow \text{ep.Balance} = \dots - \dots$

ePurse

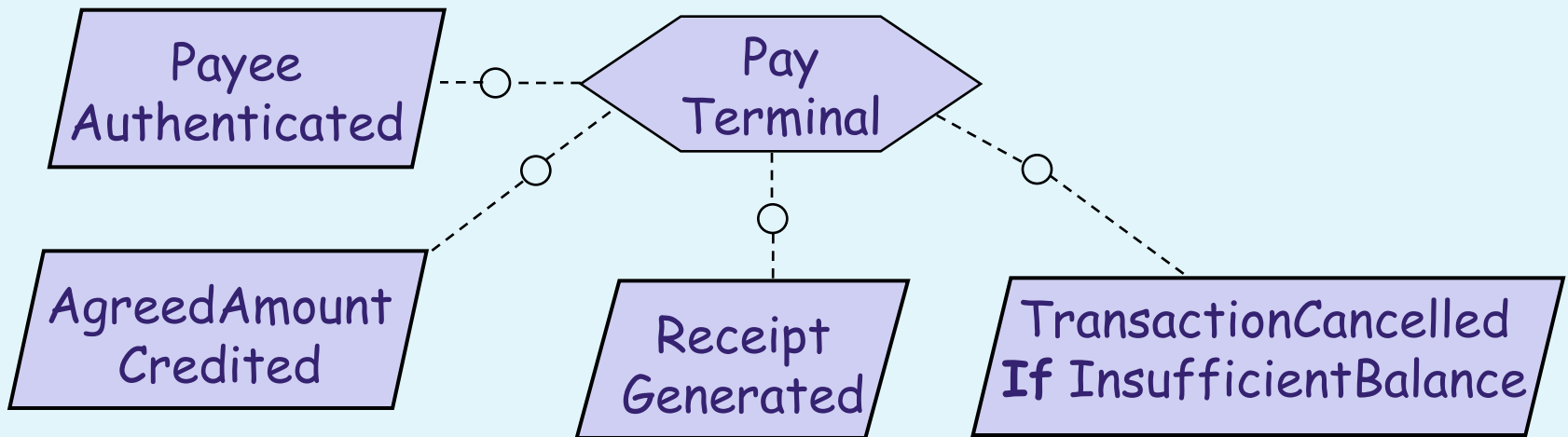
## Example 2: Not realizable by ePurse

$\text{pterm.InputAmount} \leq \text{ep.Balance}$   
 $\Rightarrow \text{pterm.Balance} = \dots + \dots \wedge \text{ep.Balance} = \dots - \dots$

~~ePurse~~

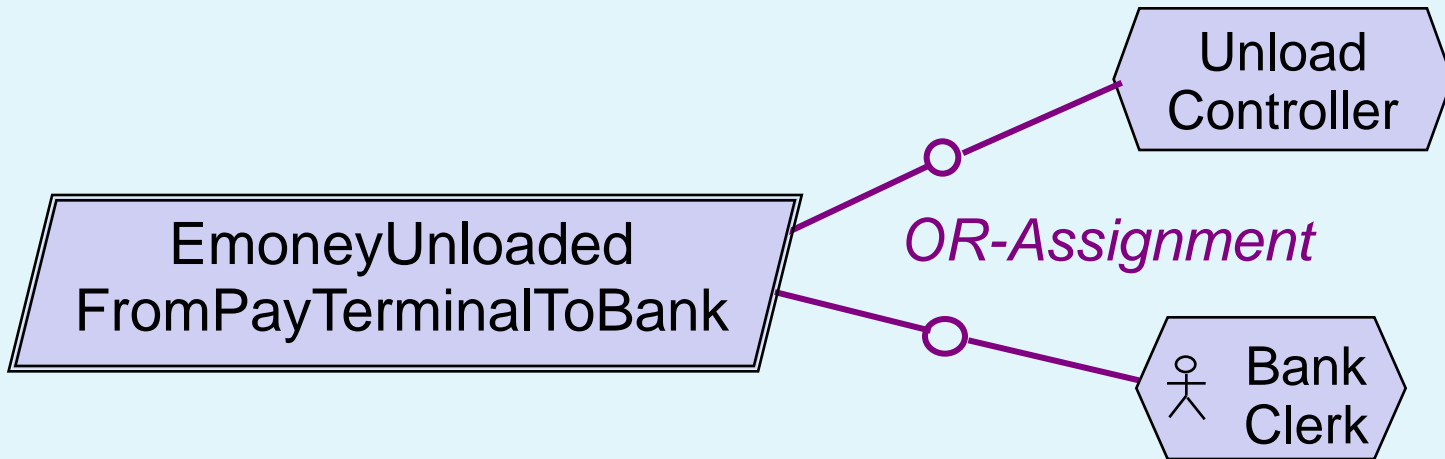


# Modeling agents: responsibility view





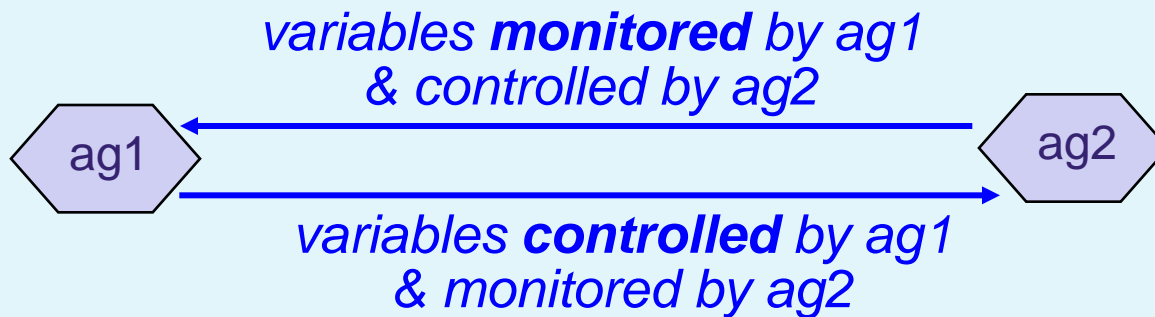
# Alternative agent assignments define alternative system boundaries



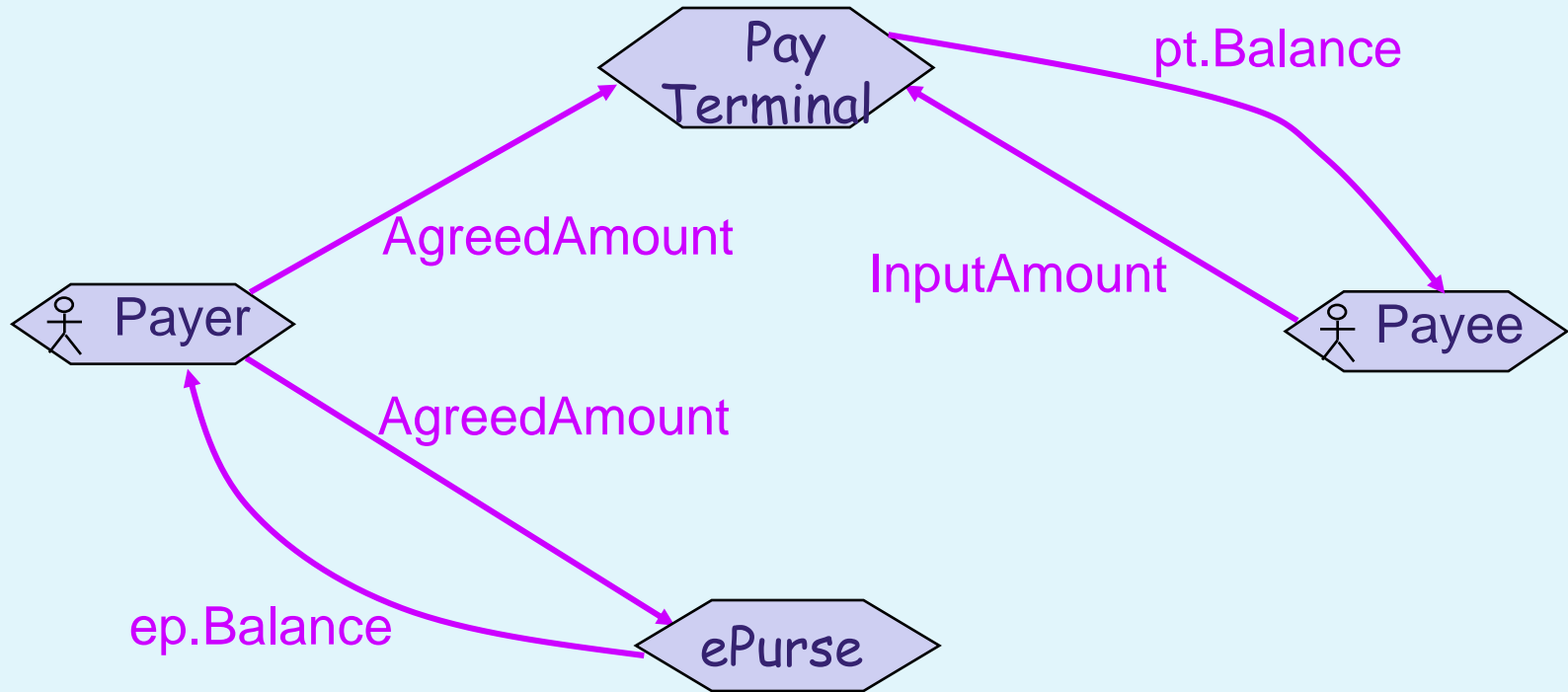


# Modeling agents: interface view

- ◆ Interface among agents =  
monitored/controlled state variables  
(attributes/relationships from object model)
- ◆ Interface view = context diagram

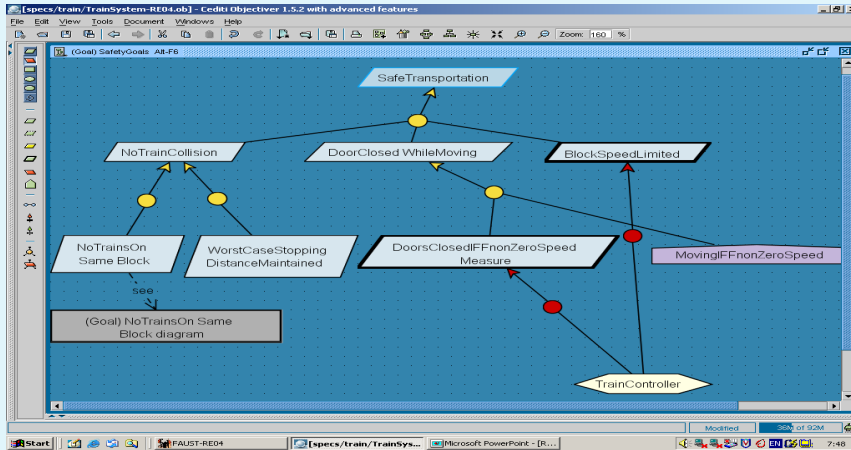


# Context diagram: example

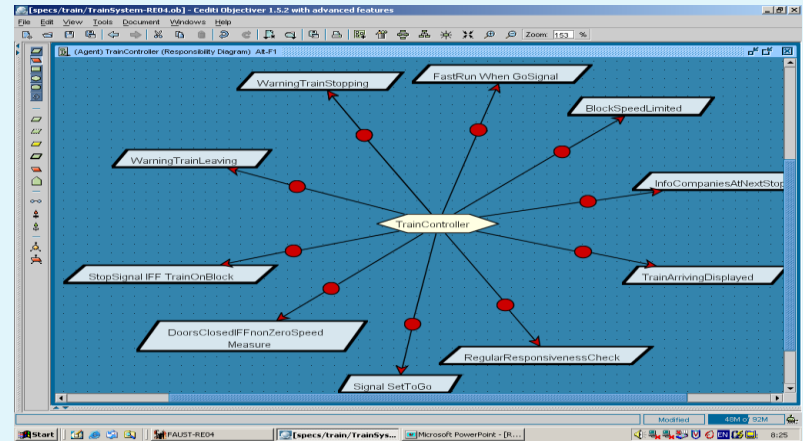


# What models ?

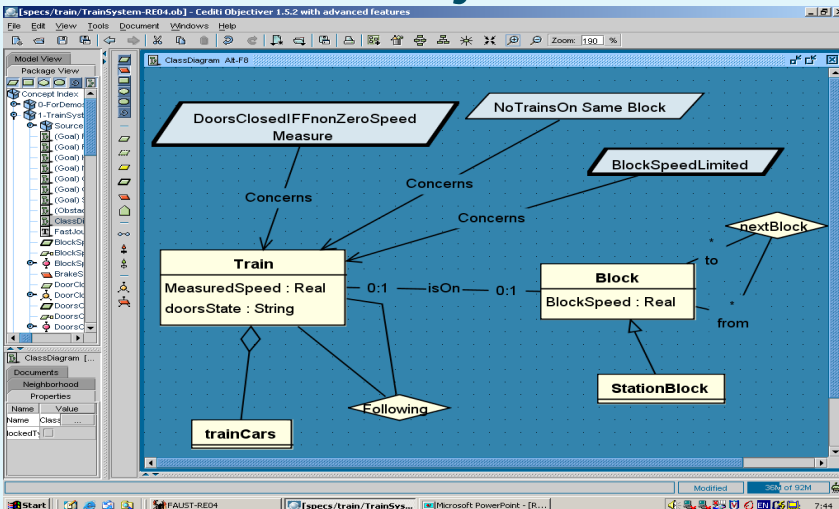
## Goals



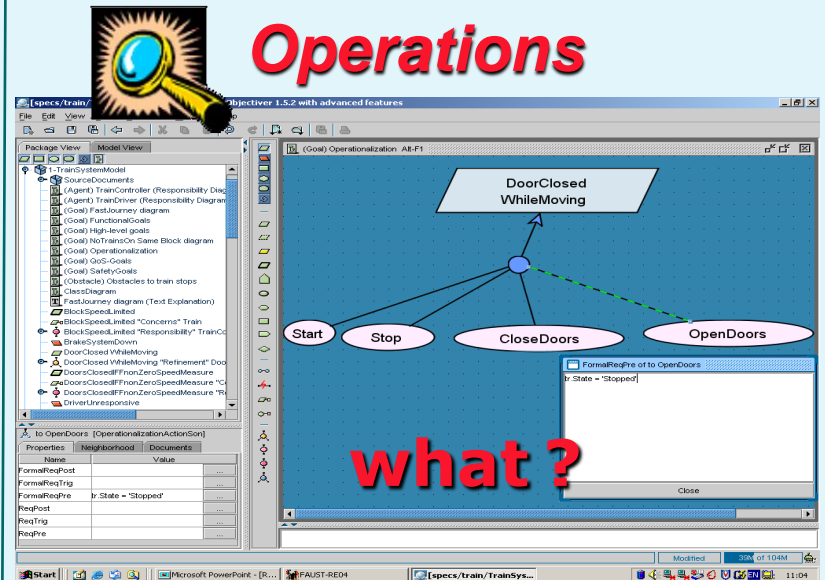
## Agents & responsibilities



## Objects



## Operations



# Modeling operations

- ◆ Functional view of the system being modeled:  
what services are to be provided? (statics)
- ◆ Operation  $Op$ :
  - relation  $Op \subseteq \text{InputState} \times \text{OutputState}$
  - $Op$  must operationalize underlying goals
  - $Op$  applications define state transitions (events) in behavioral model
  - $Op$  applications are concurrent with others
  - $Op$  is atomic: maps to state at next smallest time unit  
(operations with duration: use start/end events)

# Specifying operations

- Name, Def
- DomPre: condition characterizing the class of input states in the domain
- DomPost: condition characterizing the class of output states in the domain
- Links to other models:  
Operationalization (goals), Input/Output (objects),  
Performance (agent)

# Specifying operationalizations

- ◆ An operationalization of  $G$  into  $Op$  is specified by:
  - ReqPre: *necessary* condition on  $Op$ 's input states to ensure  $G$  (permission)
  - ReqTrig: *sufficient* condition on  $Op$ 's input states to ensure  $G$  :  
requires immediate application of  $Op$  provided DomPre holds (obligation)
  - ReqPost: condition on  $Op$ 's output states to ensure  $G$
- ◆ Consistency rule:  $ReqTrig \wedge DomPre \Rightarrow ReqPre$

# Specifying operations: example

## Operation ePay

**Def** *Operation controlling the e-payment for an item*

**Input** ep: ePurse, pt: PayTerminal; **Output** ePayment

**DomPre** There is no ePayment from *ep* to *pt*

**DomPost** There is an ePayment from *ep* to *pt*

**ReqPre For** *AgreedAmountPaidIfSufficientBalance:*

$$pt.AgreedAmount \leq ep.Balance$$

**ReqPost For** *AgreedAmountPaidIfSufficientBalance:*

$$ep.Balance = \bullet ep.Balance - pt.AgreedAmount$$

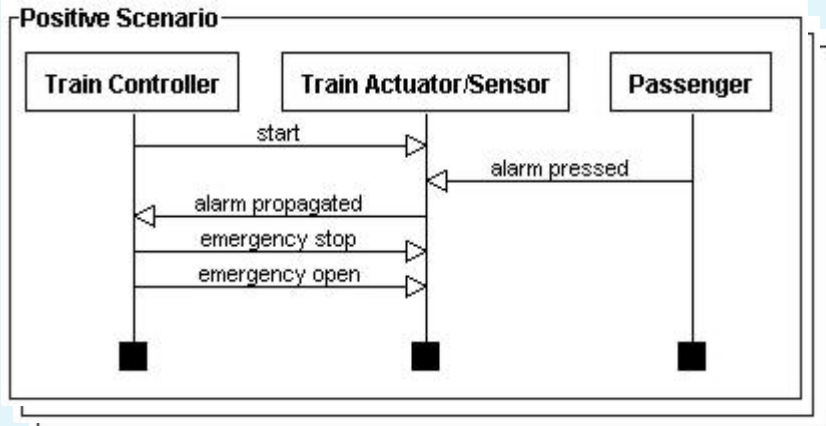
**ReqTrig For** *InstantPaymentUponAgreement:*

*The amount is agreed and the balance is sufficient*

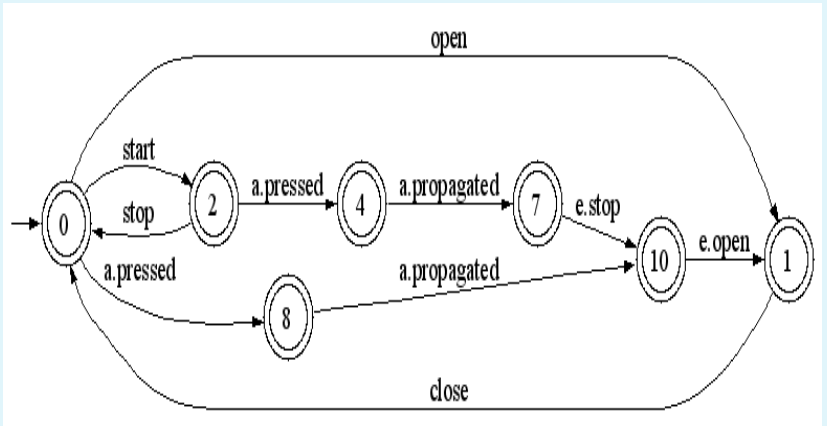
# What models ?



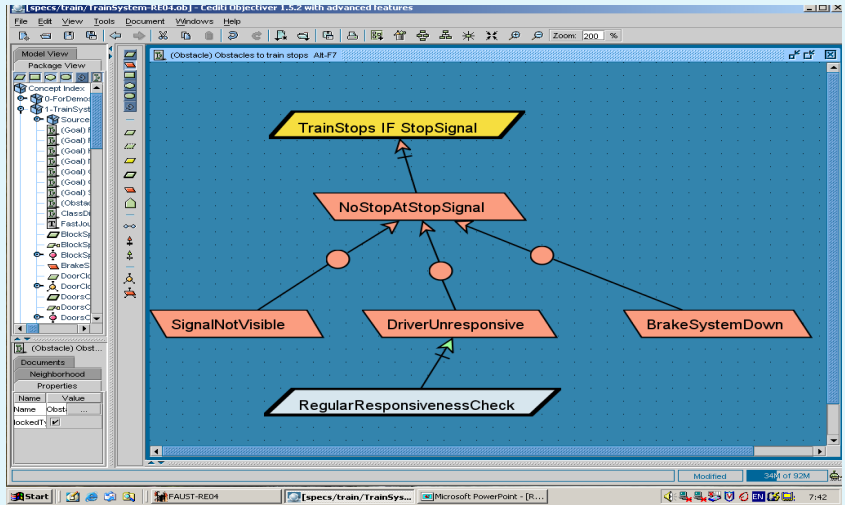
## Interaction scenarios



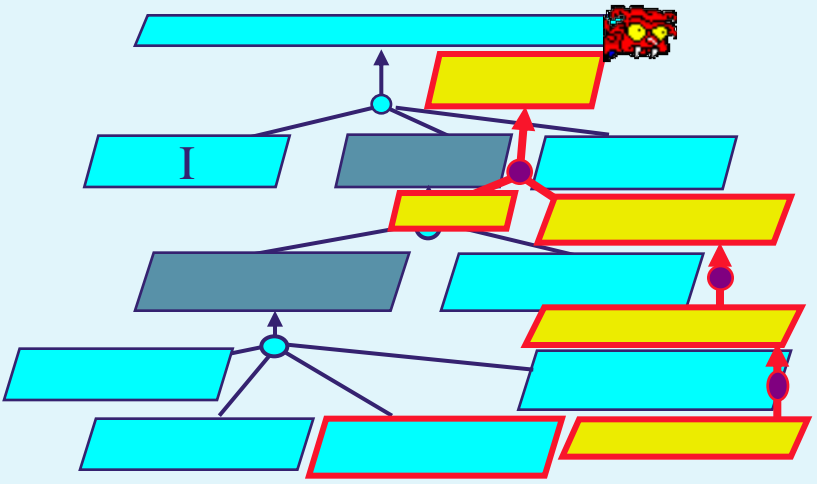
## Behaviors



## Hazards

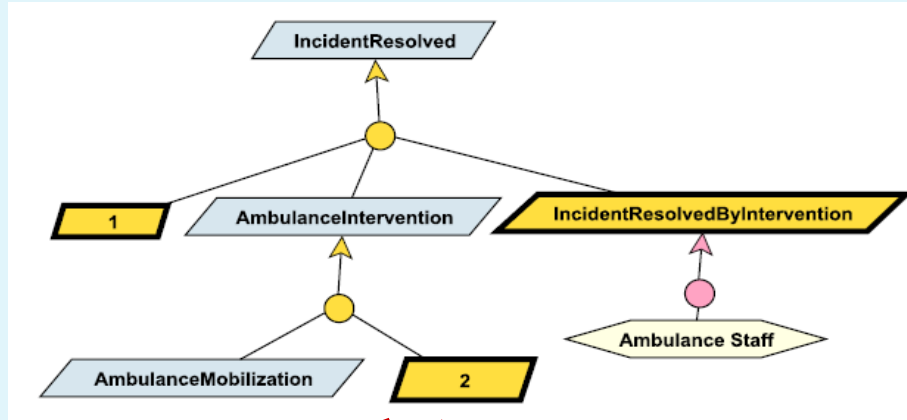


## Threats

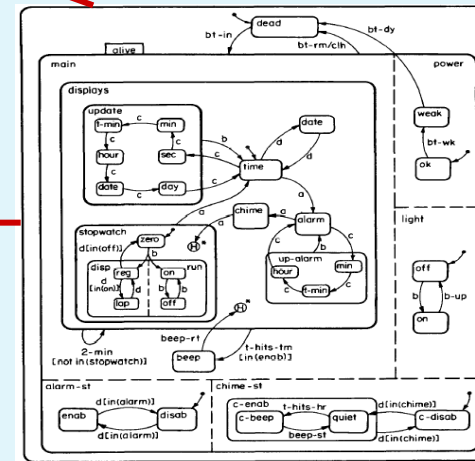
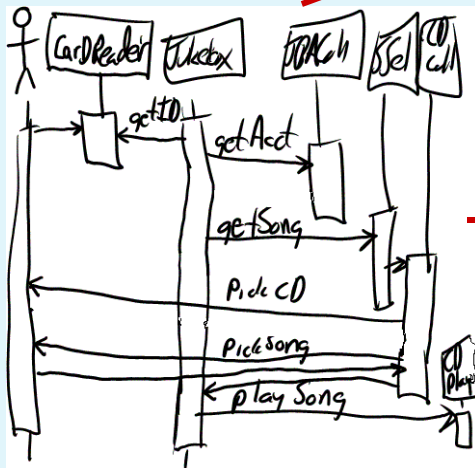




# Goals, scenarios, state machines: win-win partners



- + declarative
- + many behaviors
- too abstract?



- + concrete examples
- partial, few behaviors

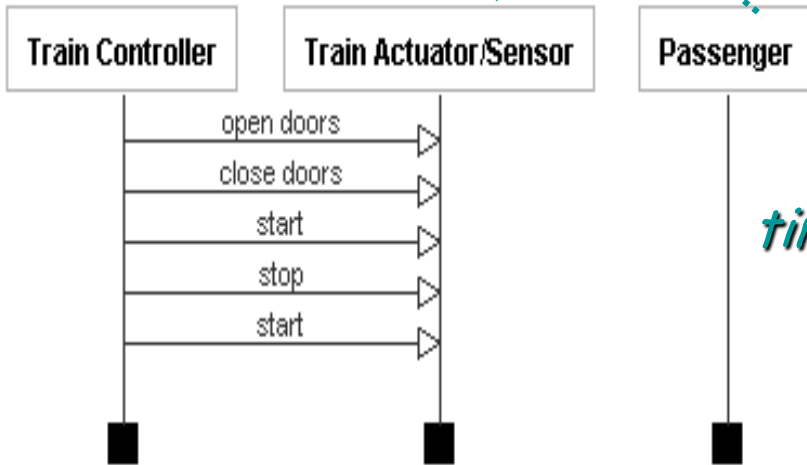
- + model-checkable, executable
- hard to build, understand

# Scenarios as simple MSCs

*agent instance*

*interaction event*

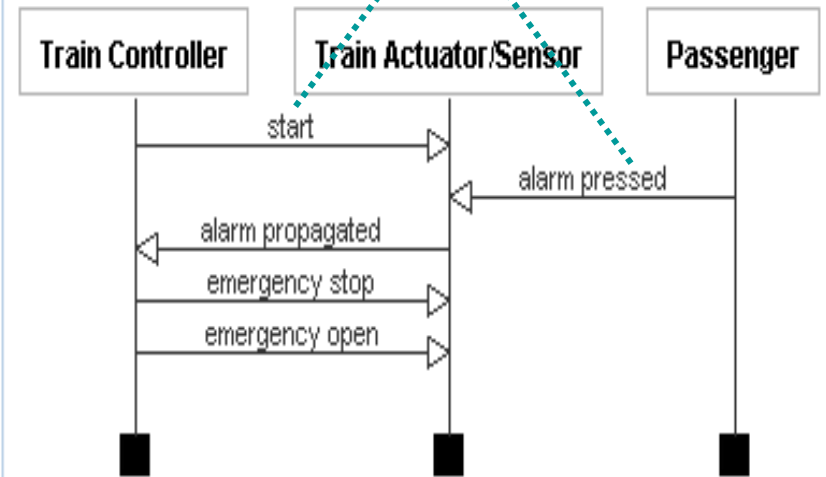
Positive Scenario 1



*time*

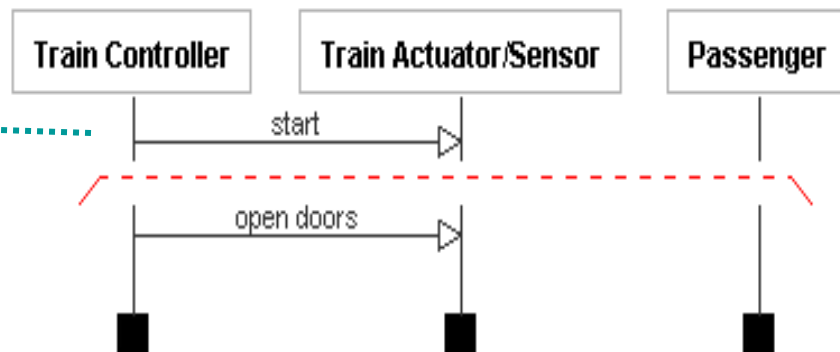
*positive*

Positive Scenario 2



*partial order on events*  
*total order along timeline*

Negative Scenario 1



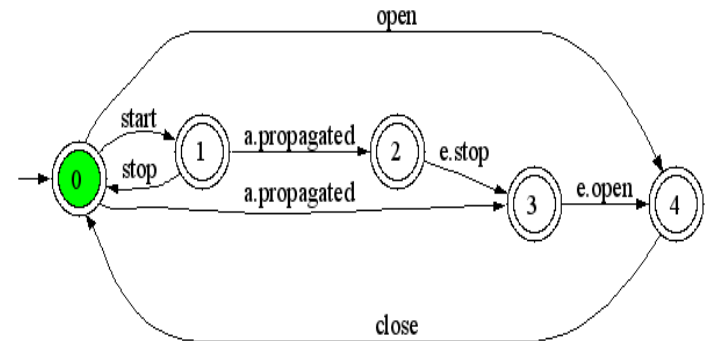
*guard*

*negative*

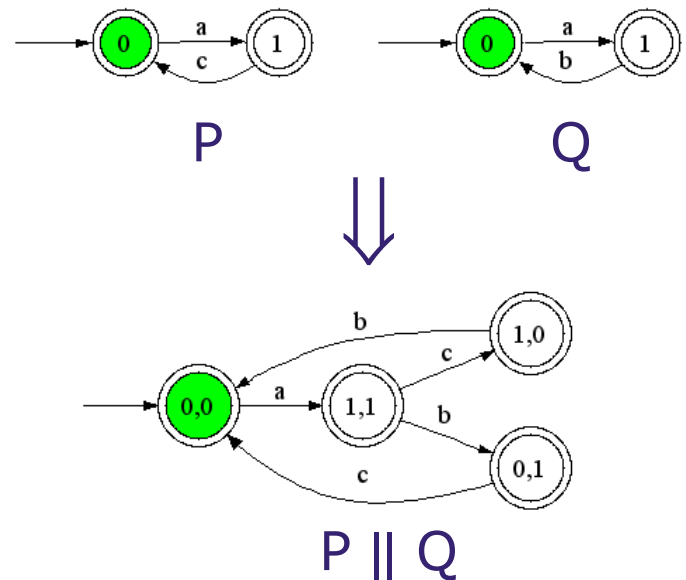
# Modeling behaviors with LTS

- ◆ An agent is modeled as a LTS
- ◆ System behavior = composition of agent behaviors
  - Agents behave asynchronously but synchronize on shared events
  - Composition:  $\parallel$ -operator

Train Controller LTS



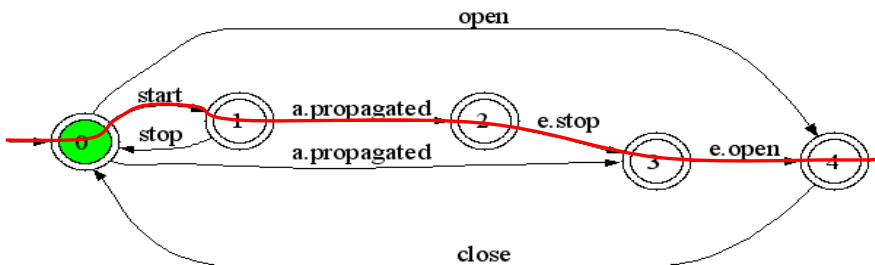
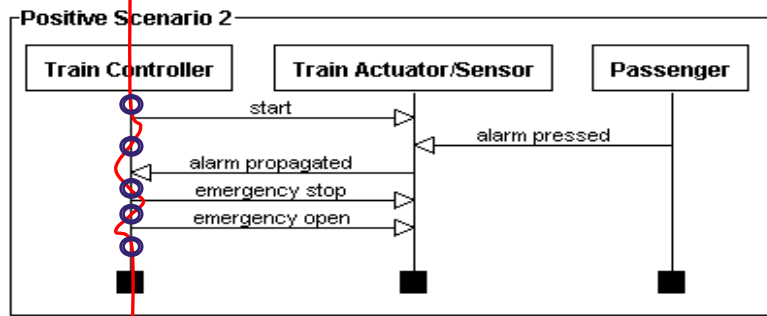
Composition operator  $\parallel$



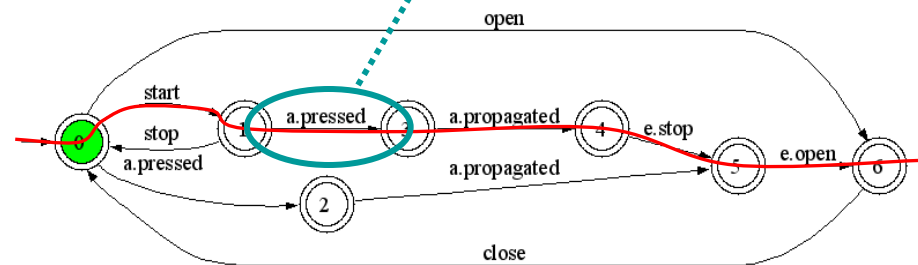
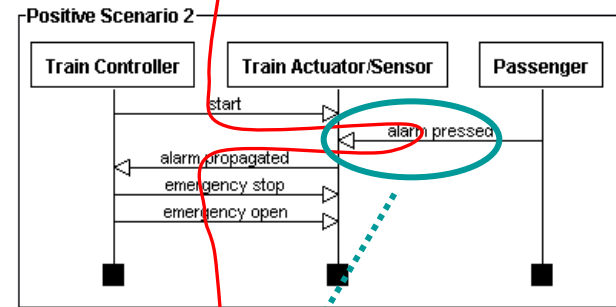
# Scenarios vs. behavior models

- ◆ A scenario defines paths in a behavior model
  - a path in each agent LTS
  - a path in the system's LTS (III)

Train Controller



Composed system

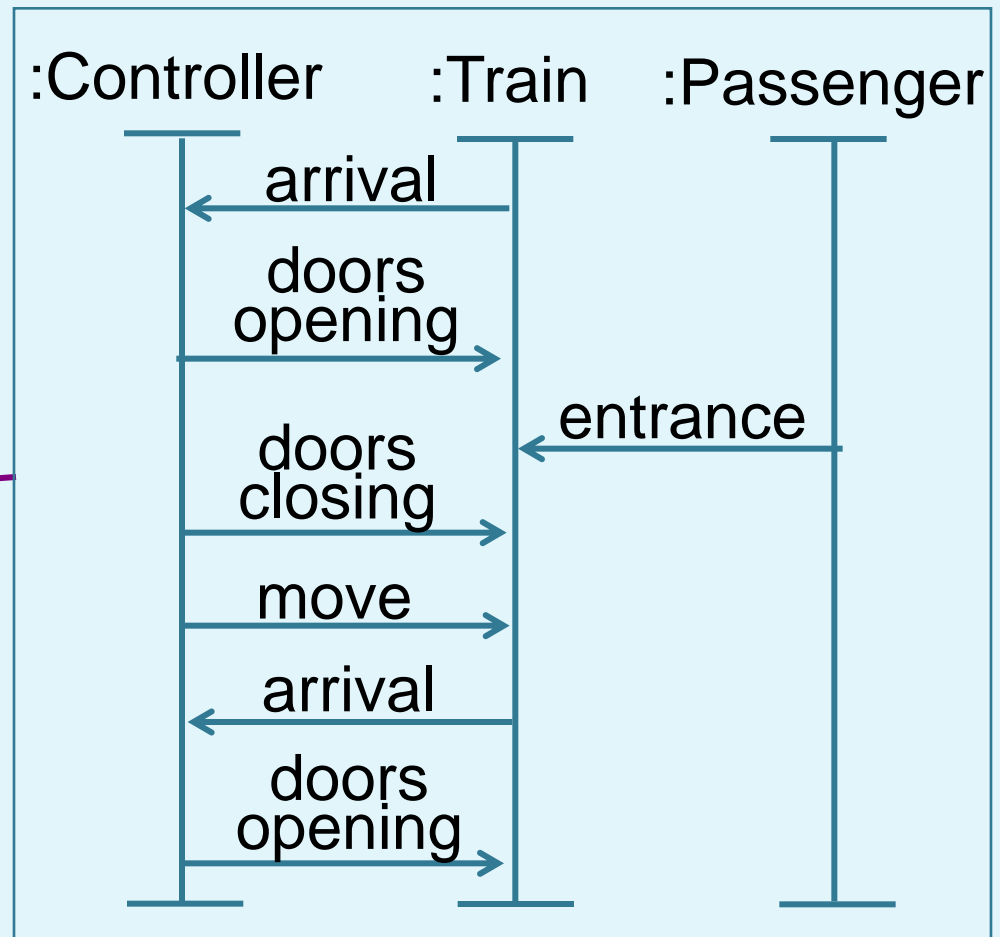


# Goals vs. scenarios

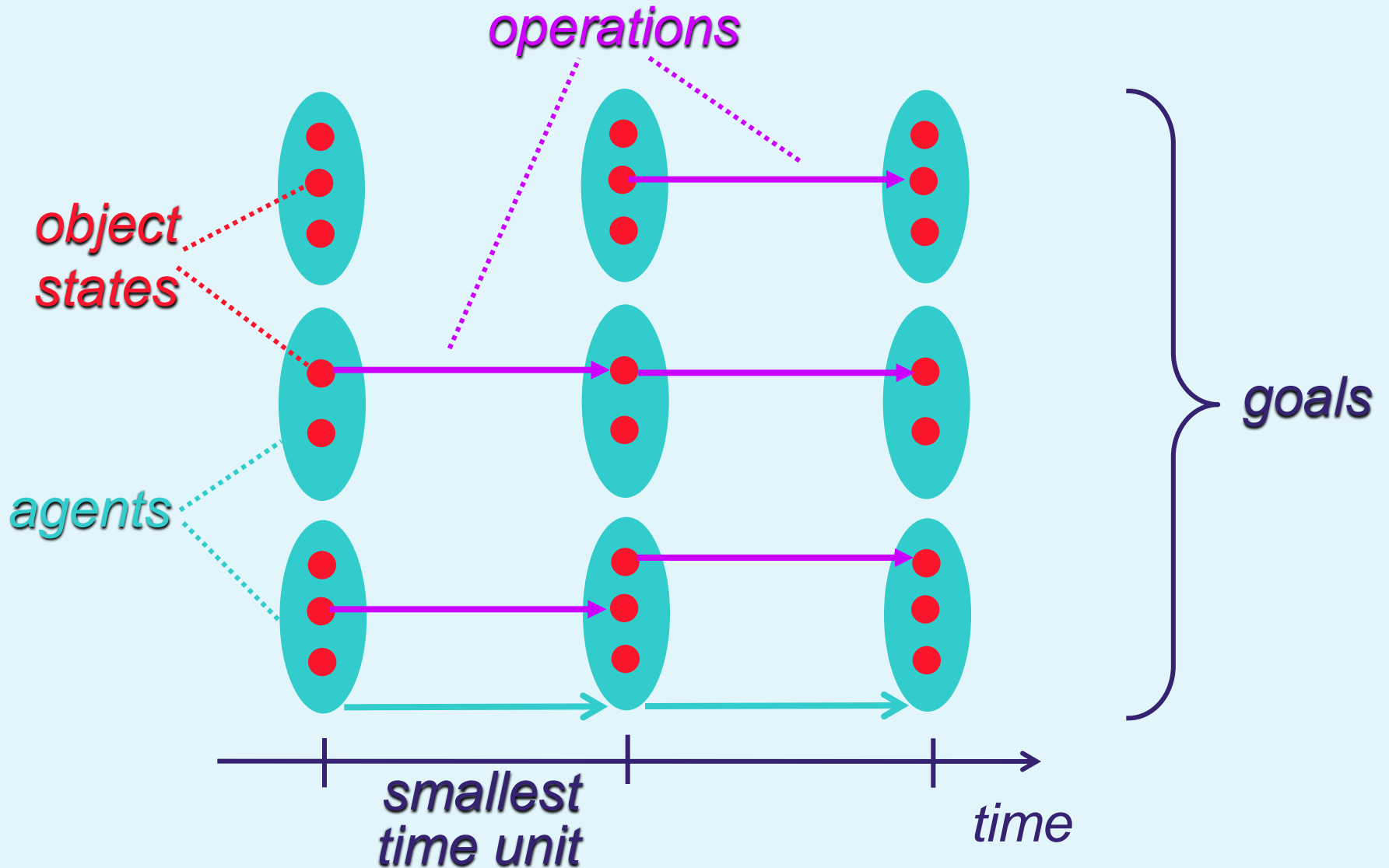
- ◆ A behavioral goal prescribes a set of scenarios

DoorsClosed  
WhileMoving

*Covers*



# Goals, objects, agents, operations: the semantic picture



# Course outline

## ◆ Goal-oriented RE for high-assurance applications

- Modeling goals, objects, agents, operations, behaviors



- **A goal-oriented model building method in action**

- Obstacle analysis for high assurance

- Formal reasoning about models

## ◆ Engineering security requirements

- Security goals and their specification

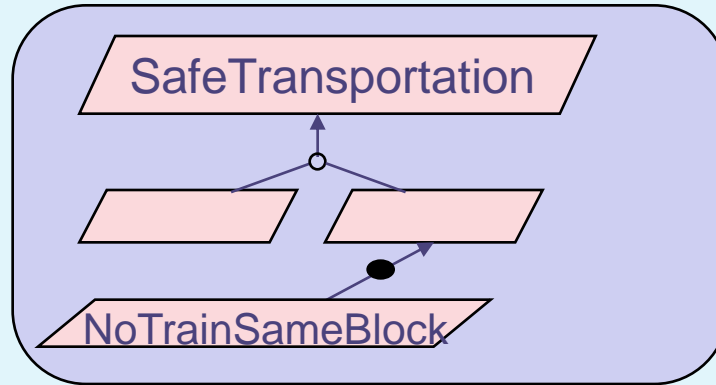
- Threat analysis for model consolidation

- Analyzing conflicts among security goals

- Model checking against confidentiality requirements

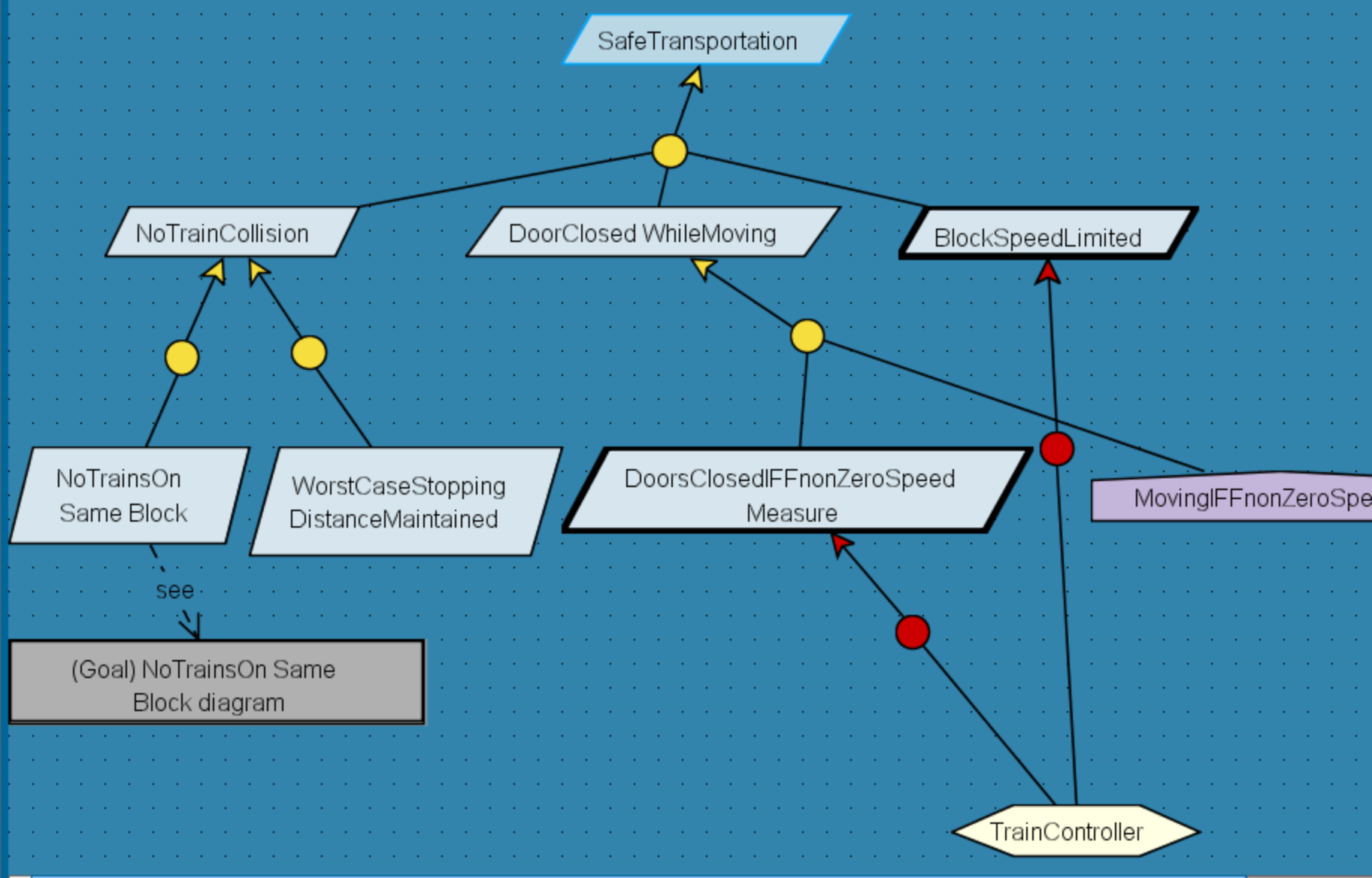
# Model building in KAOS

1. Domain analysis:  
refine/abstract goals





(Goal) SafetyGoals Alt-F6





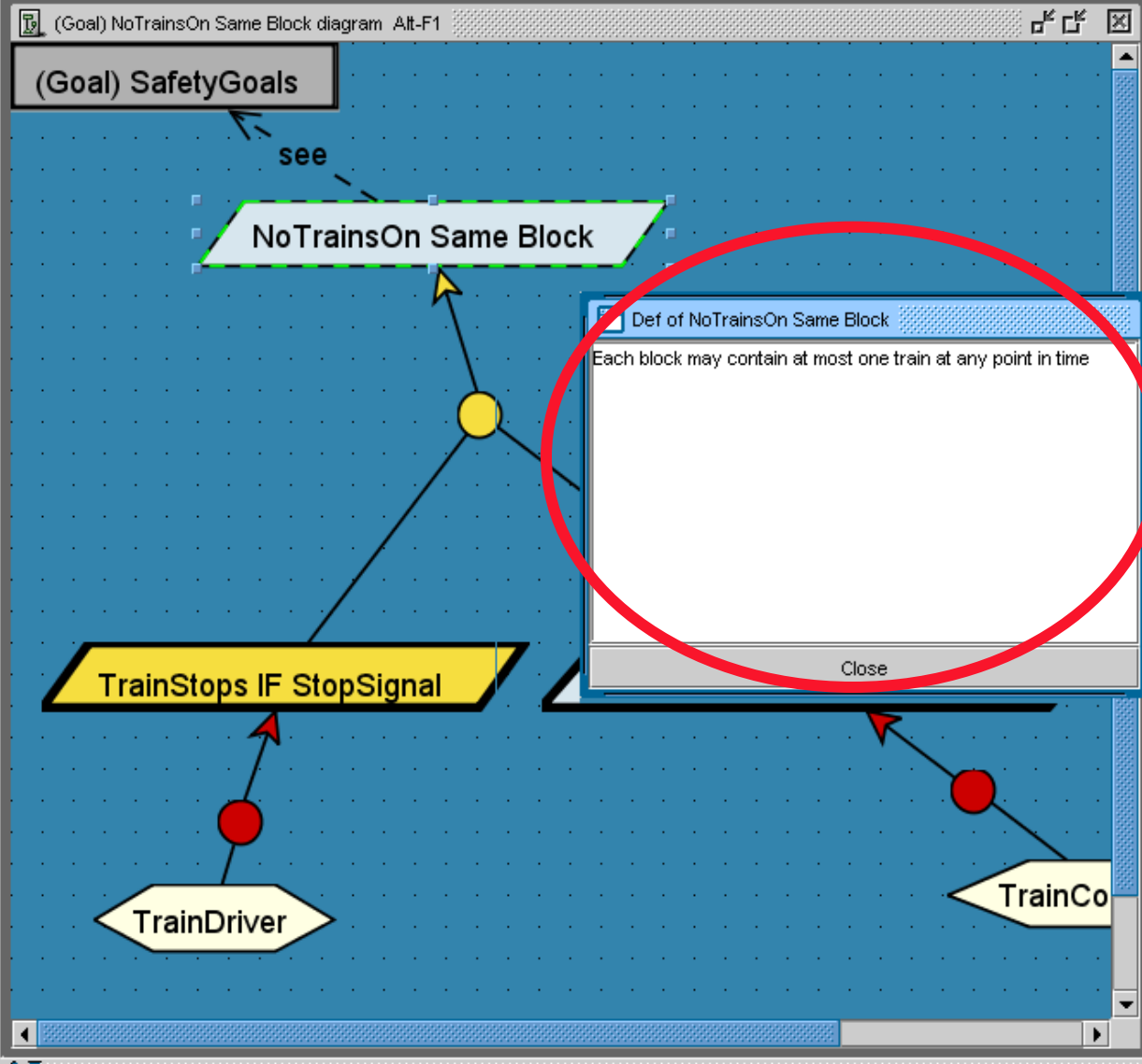
Package View Model View

- 1-TrainSystemModel
  - SourceDocuments
    - (Agent) TrainController (Responsibility Diagram)
    - (Agent) TrainDriver (Responsibility Diagram)
    - (Goal) FastJourney diagram
    - (Goal) FunctionalGoals
    - (Goal) High-level goals
    - (Goal) NoTrainsOn Same Block diagram
    - (Goal) Operationalization
    - (Goal) QoS-Goals
    - (Goal) SafetyGoals
    - (Obstacle) Obstacles to train stops
    - ClassDiagram
    - FastJourney diagram (Text Explanation)
    - BlockSpeedLimited
    - BlockSpeedLimited "Concerns" Train
    - BlockSpeedLimited "Responsibility" TrainContro
    - BrakeSystemDown
    - DoorClosed WhileMoving
    - DoorClosed WhileMoving "Refinement" DoorsCl
    - DoorsClosedIFFnonZeroSpeedMeasure
    - DoorsClosedIFFnonZeroSpeedMeasure "Conce

NoTrainsOn Same Block [Goal]

Properties Neighborhood Documents

Name	Value
Name	NoTrainsOn Same Block
Def	Each block may contain at most
Issue	
Pattern	Avoid
Category	Safety
Priority	High
NormalDef	





# Building a goal model: heuristics & tips

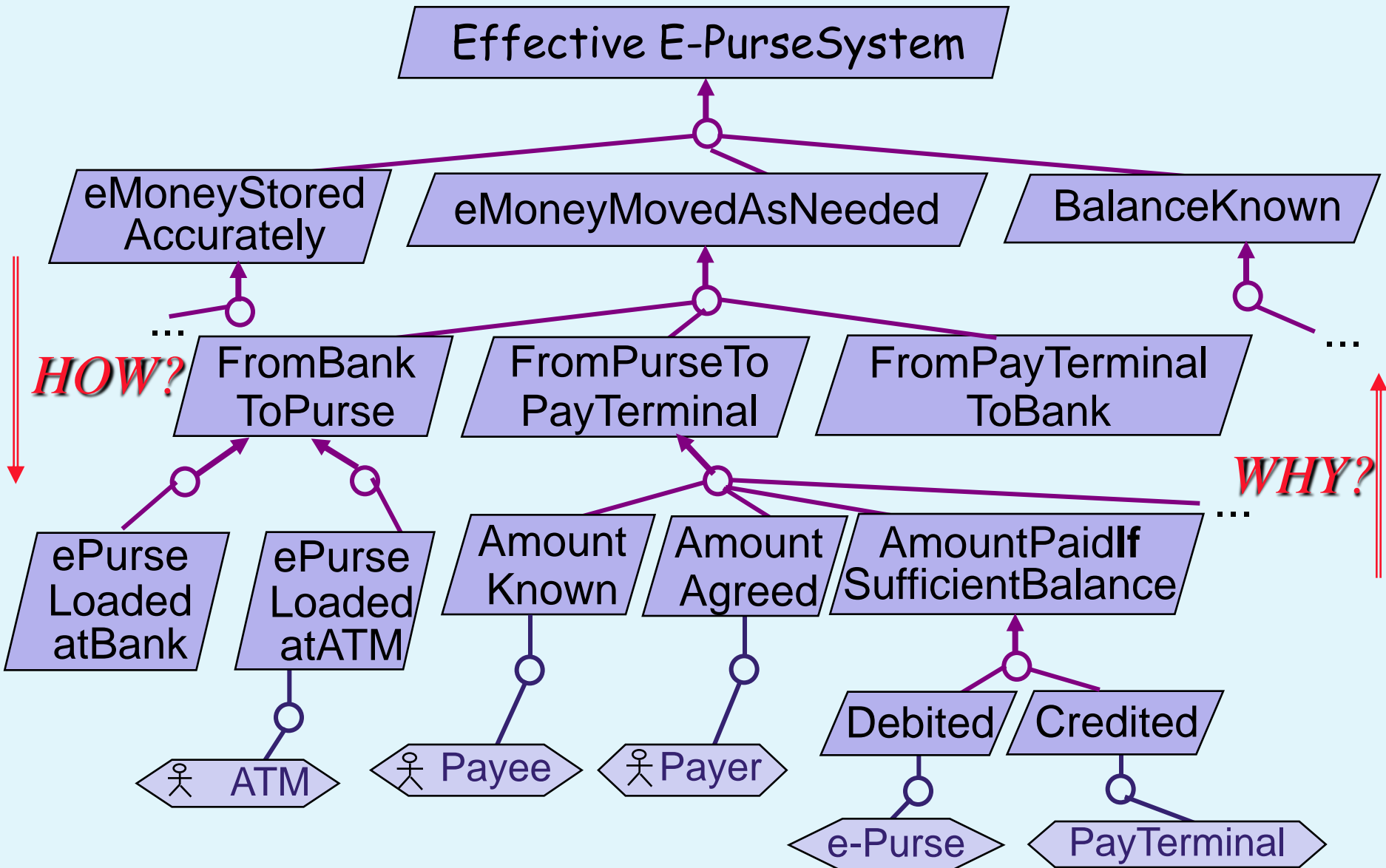
- ◆ Early discovery of goals ...
    - Analysis of system-as-is
      - ⇒ problems, deficiencies, technology opportunities
      - ⇒ goals of S2B: Avoid / Reduce / Improve them
    - Search for *intentional & prescriptive* keywords in documents available, interview transcripts, etc.
      - in order to, so as to, so that, ...
      - has to, must, to be, must be, shall, ensure, want, motivate, expected to, ...
      - purpose, objective, aim, concern, ...
- refinement links:** in order to **X** the system has to **Y**



## Building a goal model: heuristics & tips (2)

- ◆ Later discovery of goals ...
  - by abstraction (bottom-up):
    - asking **WHY?** questions about...
      - lower-level goals
      - interaction *scenarios*
      - other operational material available
  - by refinement (top-down):
    - asking **HOW?** questions about goals available
  - by use of refinement patterns (cf. below)
  - by resolution of obstacles, threats, conflicts (cf. below)

# Building a goal model: HOW / WHY questions





## Building a goal model: heuristics & tips (3)

- ◆ Abstract goals ... until when ?
  - ... until boundary of system capabilities is reached
  - e.g. *MakePeopleHappy* is beyond system's capabilities
- ◆ Refine goals ... until when ?
  - ... until assignable to **single** agents as ...
    - requirement (software agent)
    - expectation (environment agent)

Package View Model View

Concept Index

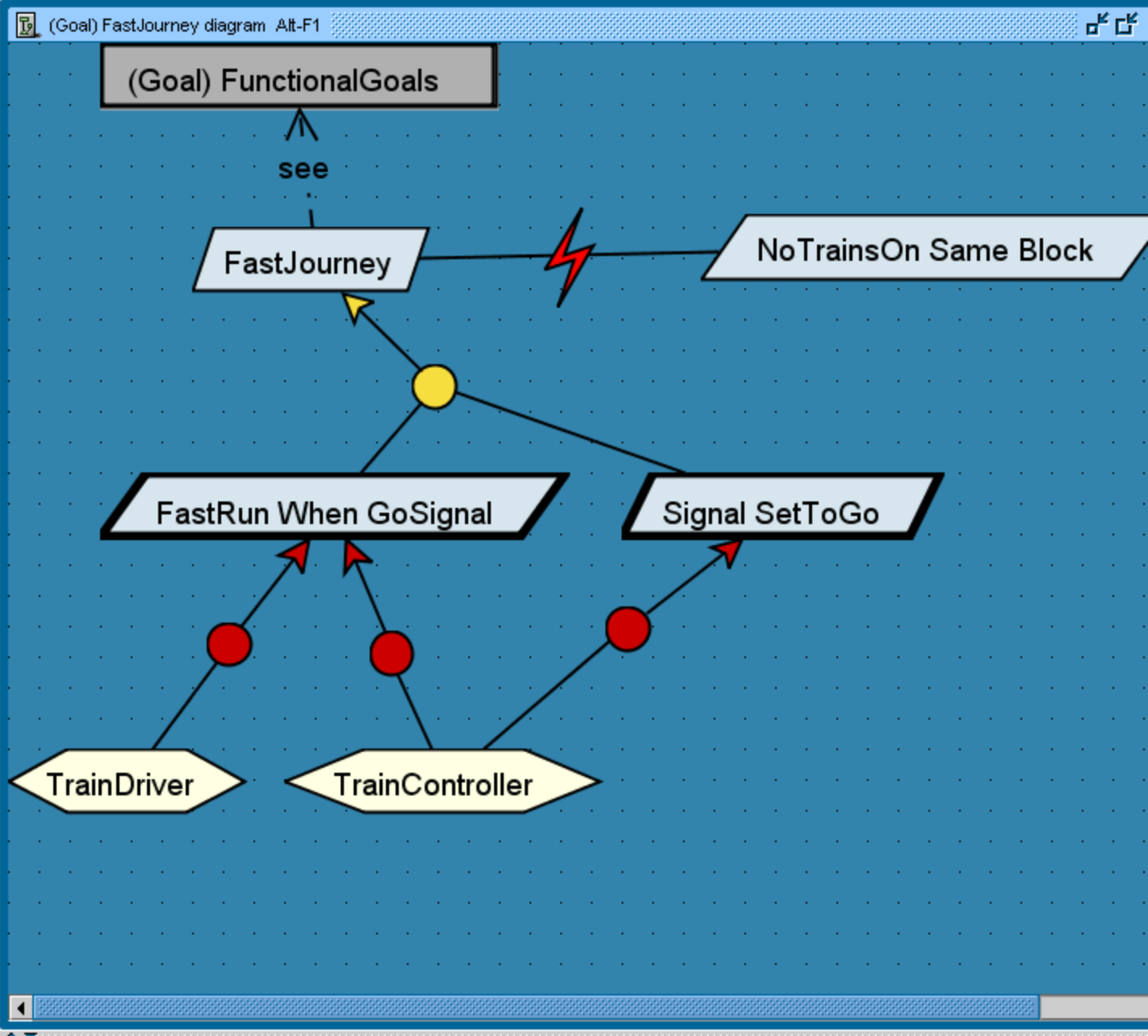
- 0-ForDemos
- 1-TrainSystemModel
  - SourceDocuments
    - (Goal) FastJourney diagram
    - (Goal) FunctionalGoals
    - (Goal) High-level goals
    - (Goal) NoTrainsOn Same Block di
    - (Goal) Operationalization
    - (Goal) QoS-Goals
    - (Goal) SafetyGoals
    - (Obstacle) Obstacles to train stop
  - ClassDiagram
  - FastJourney diagram (Text Expla
  - BlockSpeedLimited
  - BlockSpeedLimited "Concerns" Tr
  - BlockSpeedLimited "Responsibility
  - BrakeSystemDown
  - DoorClosed WhileMoving
  - DoorClosed WhileMoving "Refiner
  - DoorsClosedIFFnonZeroSpeedMe
  - DoorsClosedIFFnonZeroSpeedMe
  - DoorsClosedIFFnonZeroSpeedMe
  - DriverUnresponsive

(Goal) FastJourney diagram [Diagram]

Neighborhood Documents

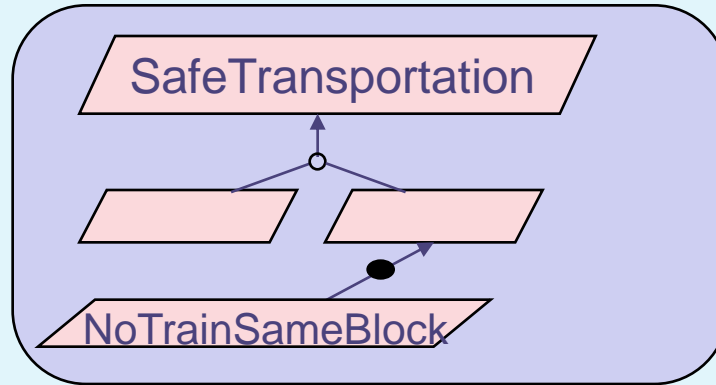
Properties

Name	Value
FastJourney diagram	...
SType	<input type="checkbox"/>

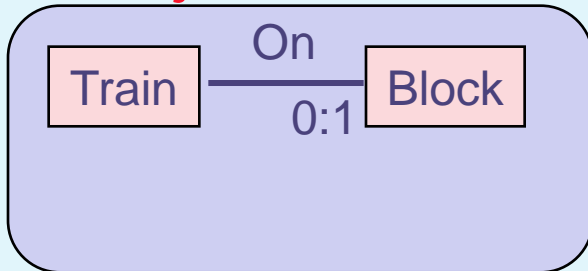


# Model building in KAOS

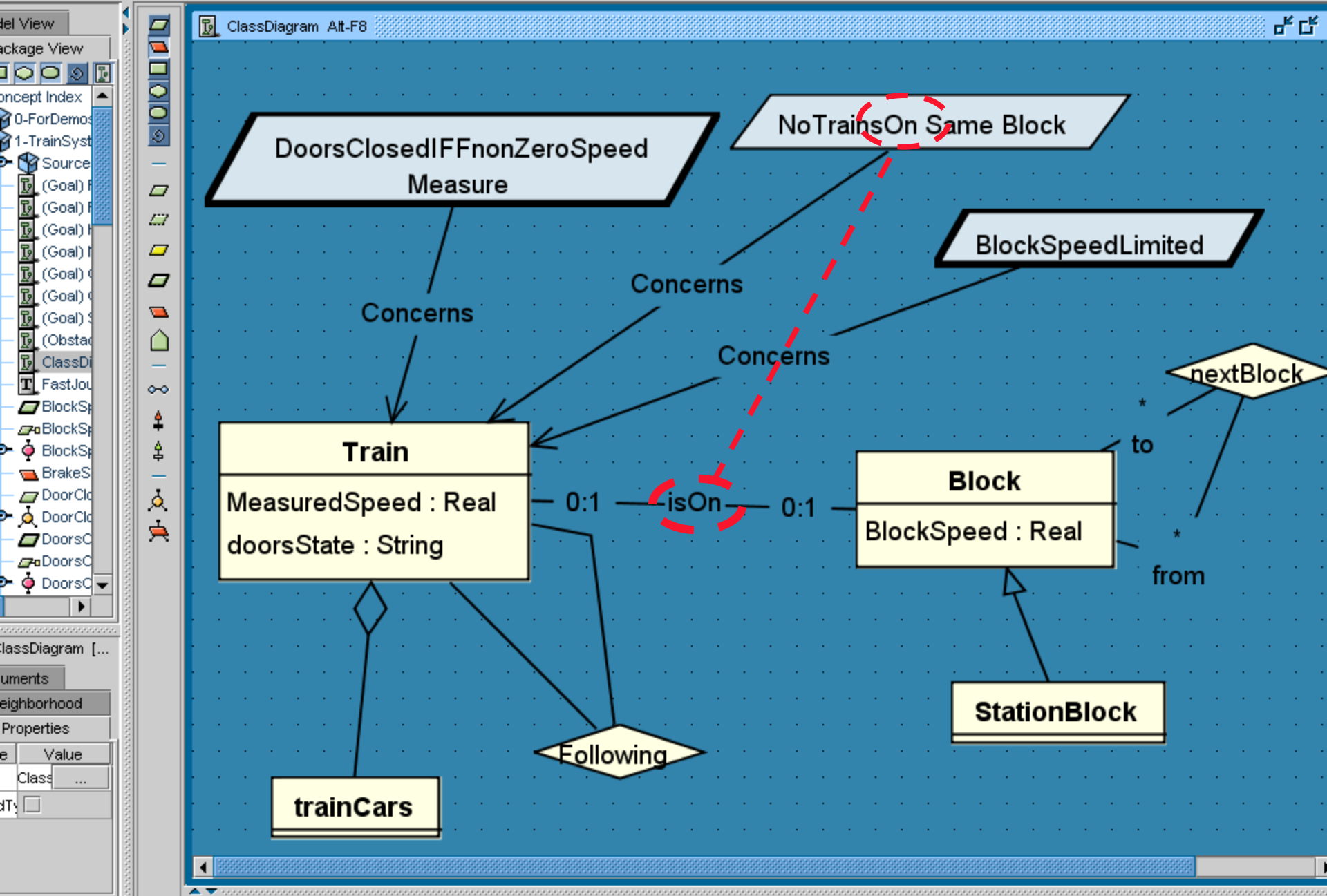
1. Domain analysis:  
refine/abstract goals



2. Domain analysis:  
derive/structure  
objects



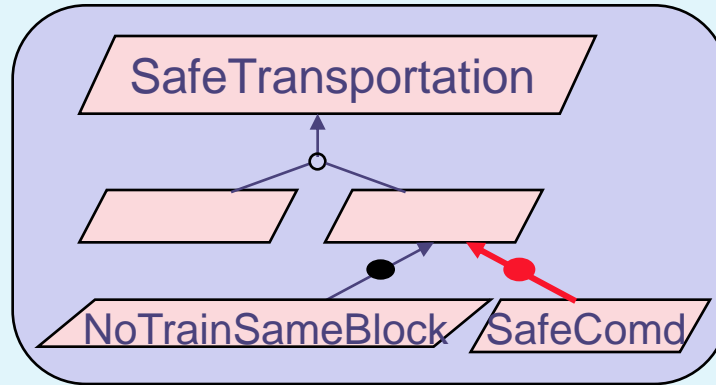




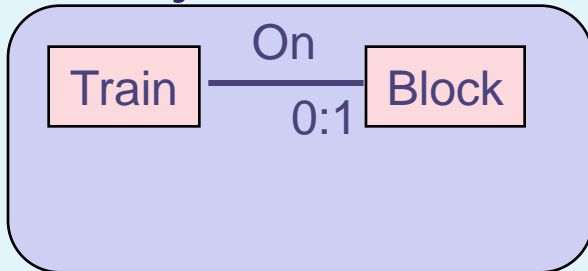
# Model building in KAOS

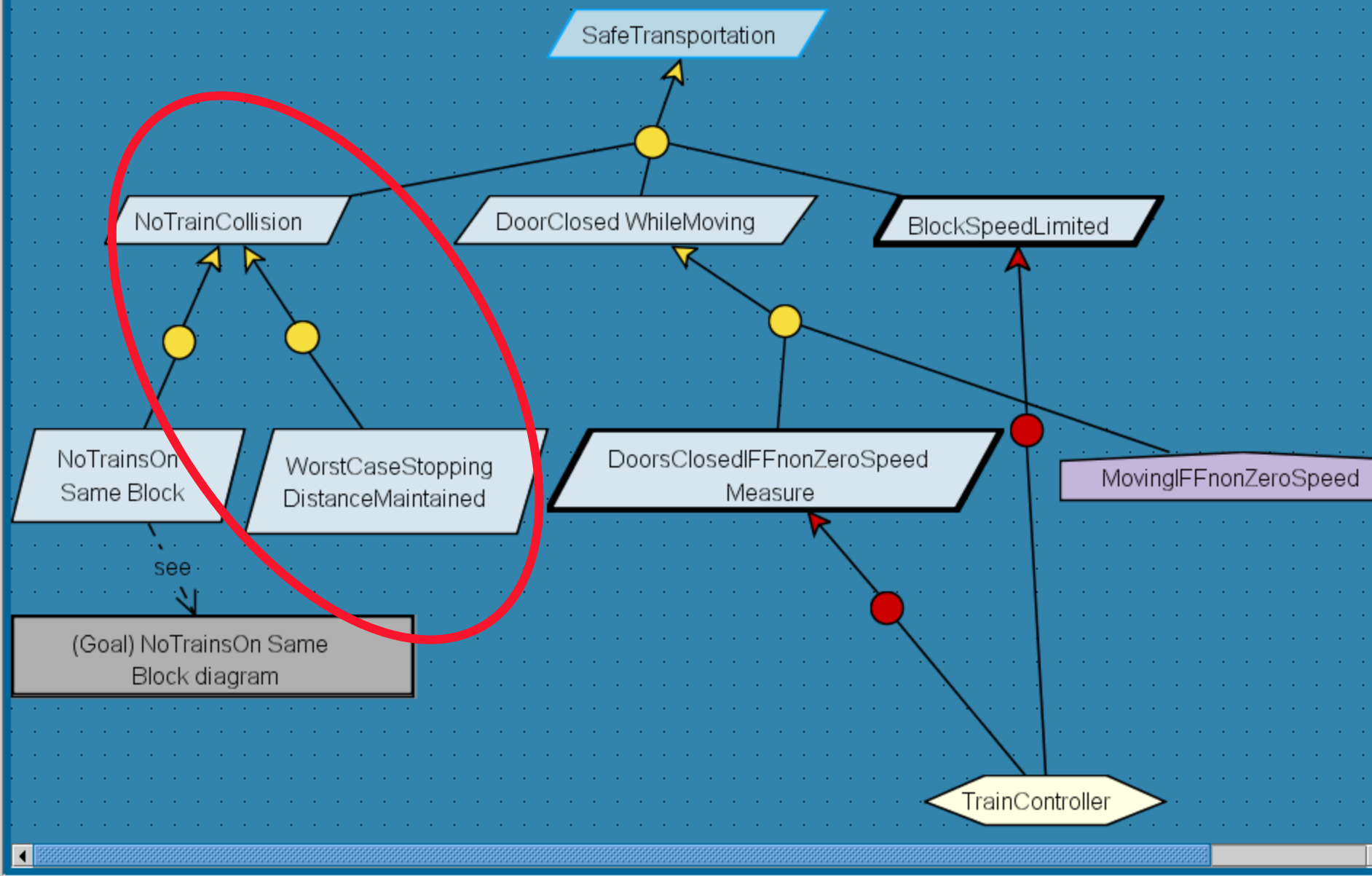
1. Domain analysis:  
refine/abstract goals

2. Domain analysis:  
derive/structure  
objects



3. S2B analysis:  
enriched goals  
(alternatives)

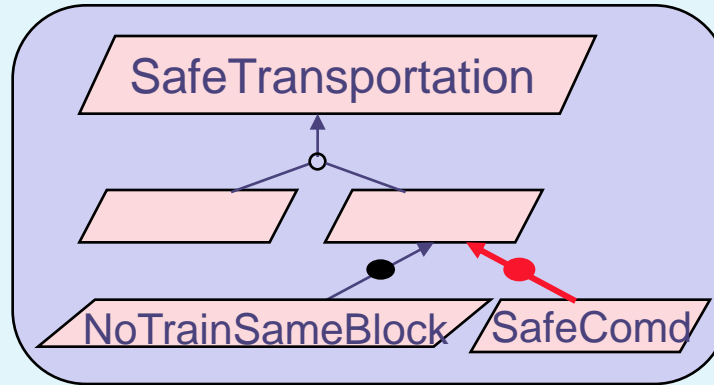




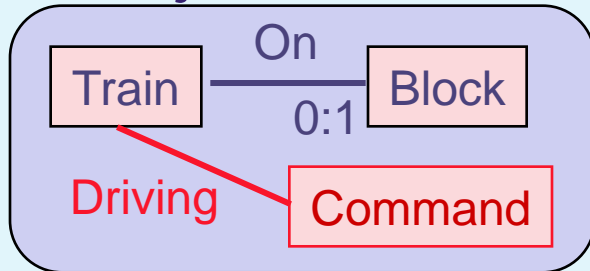
# Model building in KAOS

1. Domain analysis:  
refine/abstract goals

2. Domain analysis:  
derive/structure  
objects



3. S2B analysis:  
enriched goals  
(alternatives)



4. S2B analysis:  
enriched objects  
from new goals

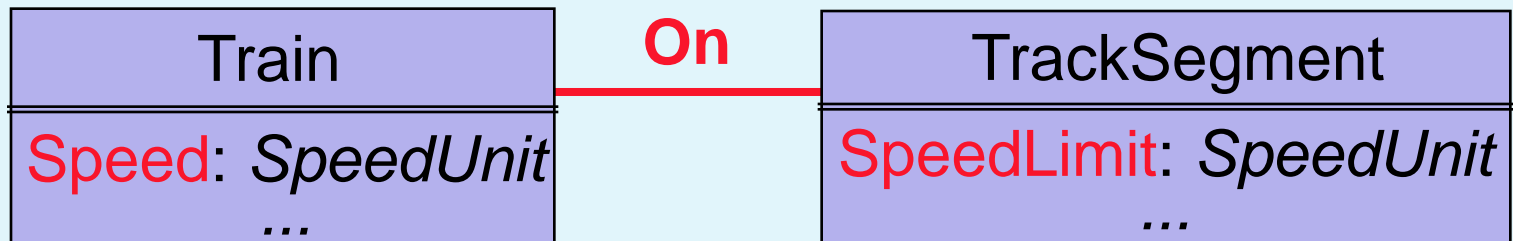
# The object model is derivable from the goal model

Goal Maintain [BlockSpeedLimited]

InformalDef *A Train should stay below the max speed the block can handle*

FormalDef  $\forall tr: Train, ts: TrackSegment$

**On**  $(tr, ts) \Rightarrow tr.Speed \leq ts.SpeedLimit$



Systematic, no "hocus pocus" (confessed by UML gurus)

⇒ completeness & pertinence of object model

# Object model derivation: more formally ... (2)

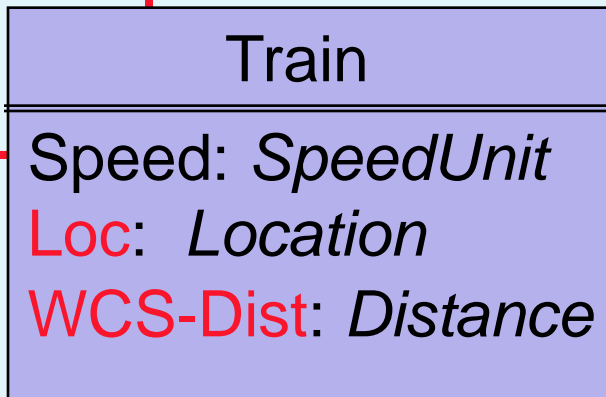
**Goal** Maintain [WC-SafeDistanceBetwTrains]

**InformalDef** *A Train should stay sufficiently far to avoid hitting the train in front in case of sudden stop*

**FormalDef**  $\forall tr1, tr2: Train$

**Following**  $(tr1, tr2) \Rightarrow tr1.Loc - tr2.Loc > tr1.WCS-Dist$

**Following**

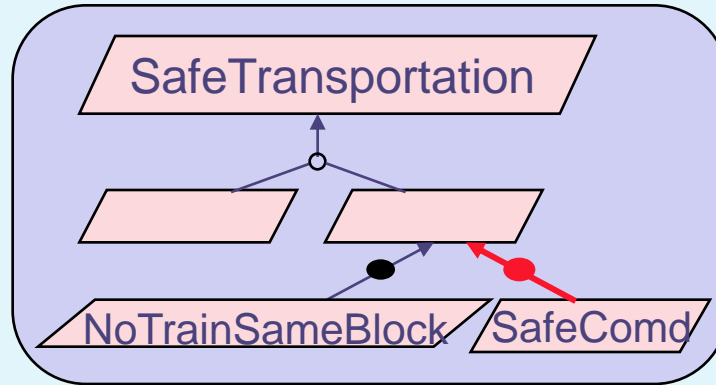


**On**



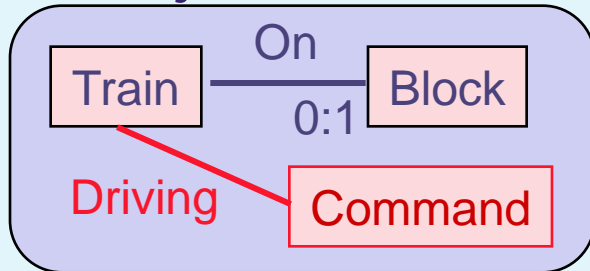
# Model building in KAOS

1. Domain analysis:  
refine/abstract goals

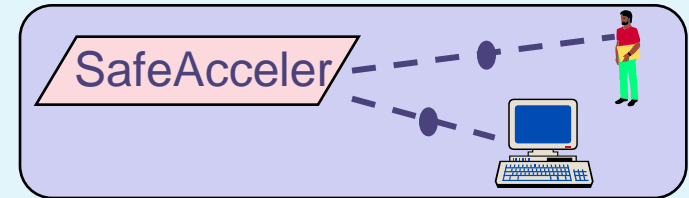


3. S2B analysis:  
enriched goals  
(alternatives)

2. Domain analysis:  
derive/structure  
objects



4. S2B analysis:  
enriched objects  
from new goals

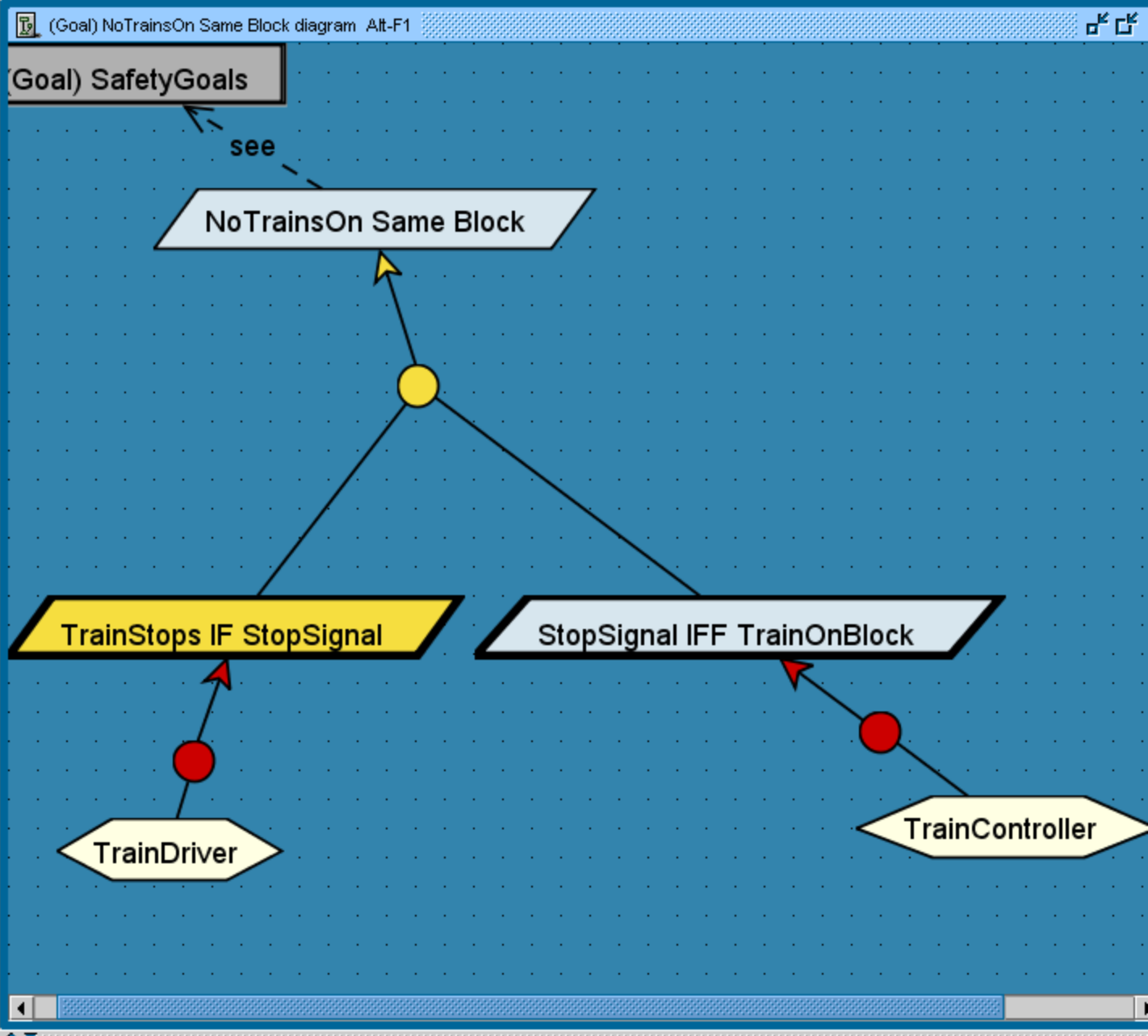


5. Responsibility analysis:  
agent OR-assignment

Package View Model View

Index

- Demos
- SystemModel
- SourceDocuments
- Goal) FastJourney diagram
- Goal) FunctionalGoals
- Goal) High-level goals
- Goal) NoTrainsOn Same Block diagram
- Goal) Operationalization
- Goal) QoS-Goals
- Goal) SafetyGoals
- Obstacle) Obstacles to train stops
- ClassDiagram
- FastJourney diagram (Text Explanation)
- LockSpeedLimited
- LockSpeedLimited "Concerns" Train
- LockSpeedLimited "Responsibility" Train
- TakeSystemDown
- DoorClosed WhileMoving
- DoorClosed WhileMoving "Refinement" D
- DoorsClosedIFFnonZeroSpeedMeasure
- DoorsClosedIFFnonZeroSpeedMeasure
- DoorsClosedIFFnonZeroSpeedMeasure
- DriverUnresponsive



Goal) NoTrainsOn Same Block diagram ...

Neighborhood Documents

Properties

Name	Value
Same Block diagram	...
SType	<input type="checkbox"/>



# Context diagrams can be derived from goals

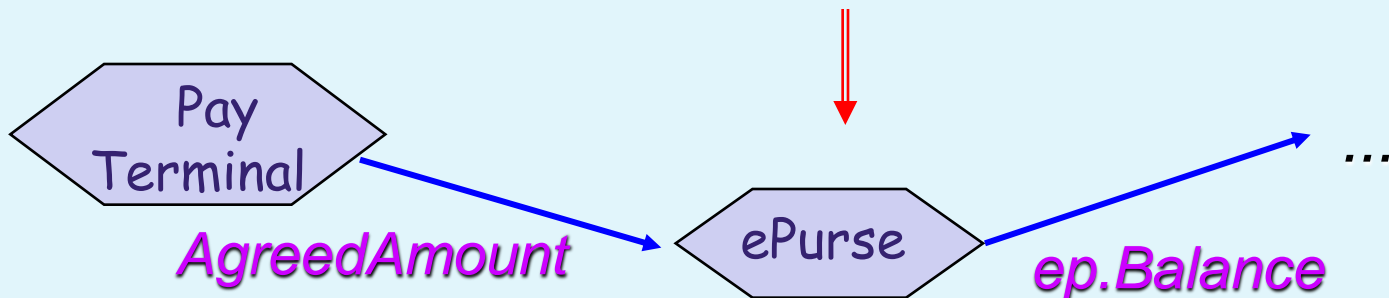
Many behavioral goals take the form

**G:** CurrentCondition [monitoredVariables]

⇒ [sooner-or-later/always]

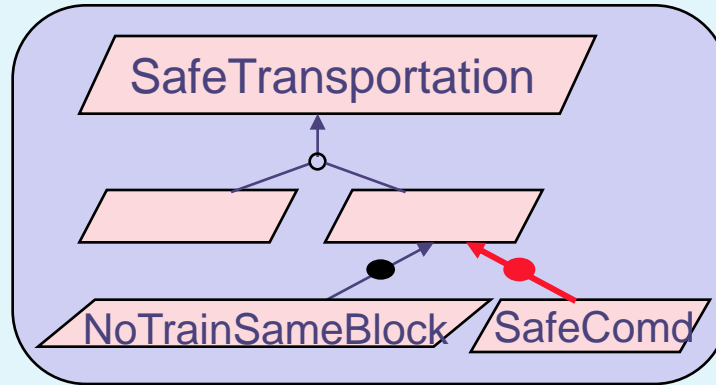
TargetCondition [controlledVariables]

$\text{AgreedAmount} \leq \text{ep.Balance}$   
⇒  $\text{ep.Balance} = \text{ep.Balance} - \text{AgreedAmount}$



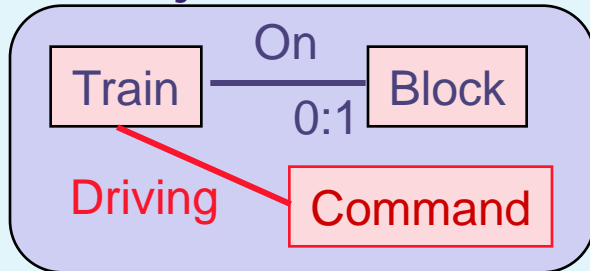
# Model building in KAOS

1. Domain analysis:  
refine/abstract goals



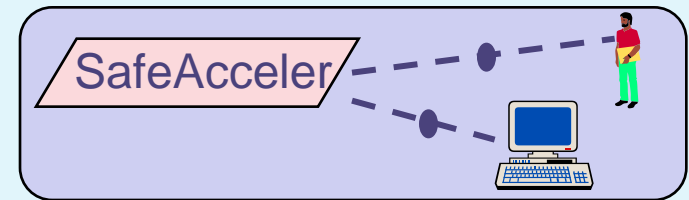
3. S2B analysis:  
enriched goals  
(alternatives)

2. Domain analysis:  
derive/structure  
objects

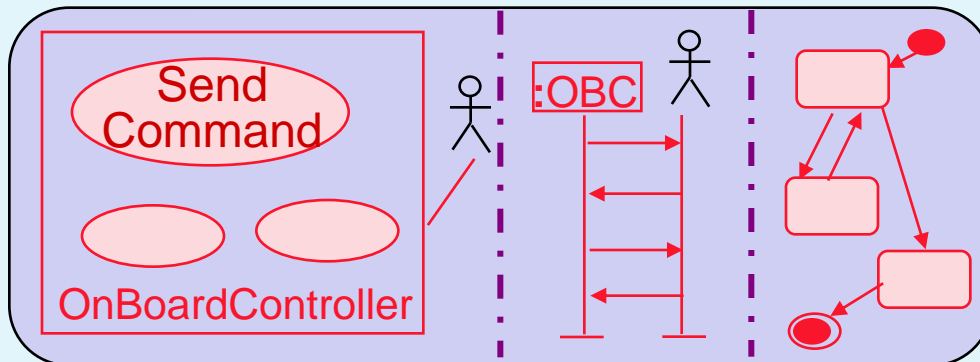


1-5. Obstacle & conflict  
analysis

4. S2B analysis:  
enriched objects  
from new goals



5. Responsibility analysis:  
agent OR-assignment



6. Operationalization  
& behavior analysis



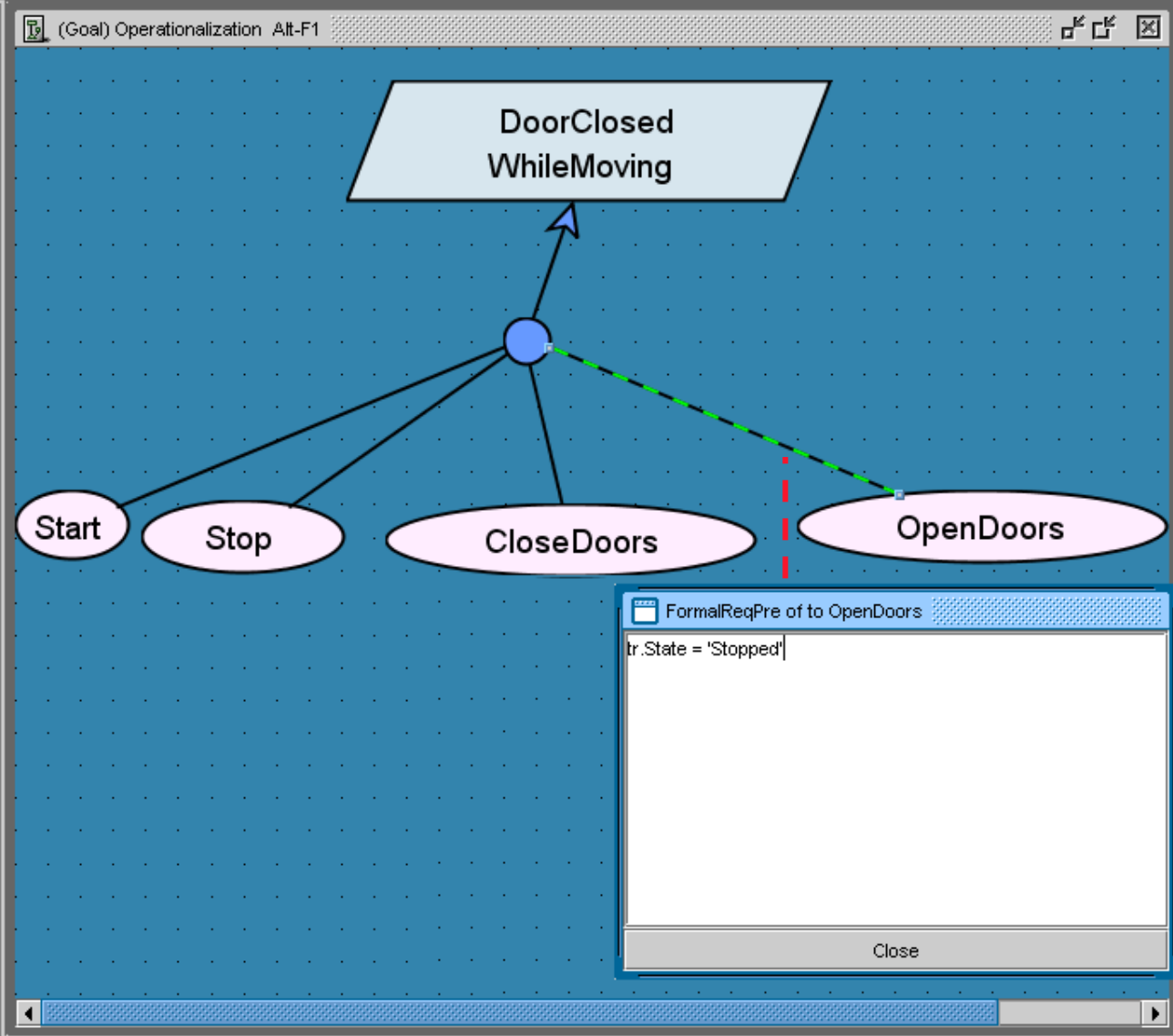
Package View Model View

- 1-TrainSystemModel
  - SourceDocuments
    - (Agent) TrainController (Responsibility Diagram)
    - (Agent) TrainDriver (Responsibility Diagram)
    - (Goal) FastJourney diagram
    - (Goal) FunctionalGoals
    - (Goal) High-level goals
    - (Goal) NoTrainsOn Same Block diagram
    - (Goal) Operationalization
    - (Goal) QoS-Goals
    - (Goal) SafetyGoals
    - (Obstacle) Obstacles to train stops
    - ClassDiagram
    - FastJourney diagram (Text Explanation)
    - BlockSpeedLimited
    - BlockSpeedLimited "Concerns" Train
    - BlockSpeedLimited "Responsibility" TrainC
    - BrakeSystemDown
    - DoorClosed WhileMoving
    - DoorClosed WhileMoving "Refinement" Doc
    - DoorsClosedIFFnonZeroSpeedMeasure
    - DoorsClosedIFFnonZeroSpeedMeasure "C
    - DoorsClosedIFFnonZeroSpeedMeasure "R
    - DriverUnresponsive

to OpenDoors [OperationalizationActionSon]

Properties Neighbors Documents

Name	Value
FormalReqPost	
FormalReqTrig	...
FormalReqPre	tr.State = 'Stopped'
ReqPost	...
ReqTrig	...
ReqPre	...




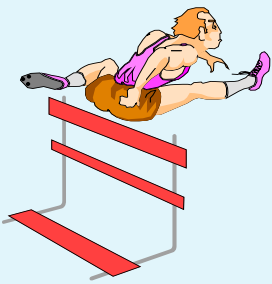
FormalReqPre of to OpenDoors

```
tr.State = 'Stopped'
```

Close

# Course outline

- ◆ Goal-oriented RE for high-assurance applications
  - Modeling goals, objects, agents, operations, behaviors
  - A goal-oriented model building method in action
  -  - Obstacle analysis for high assurance
  - Formal reasoning about models
- ◆ Engineering security requirements
  - Security goals and their specification
  - Threat analysis for model consolidation
  - Analyzing conflicts among security goals
  - Model checking against confidentiality requirements



# Modeling what could go wrong: obstacle analysis

- ◆ Problem: goals are often too ideal, will be violated  
(unexpected or malicious agent behaviors)

- ◆ Obstacle = condition on system for goal violation

$\{ O, \text{Dom} \} \models \neg G$  *obstruction*

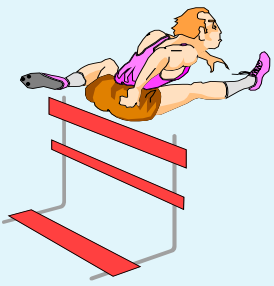
$\text{Dom} \models \neg O$  *domain consistency*

exists system behavior  $S$  s.t.  $S \models O$  *feasibility*

- ◆ Particular cases

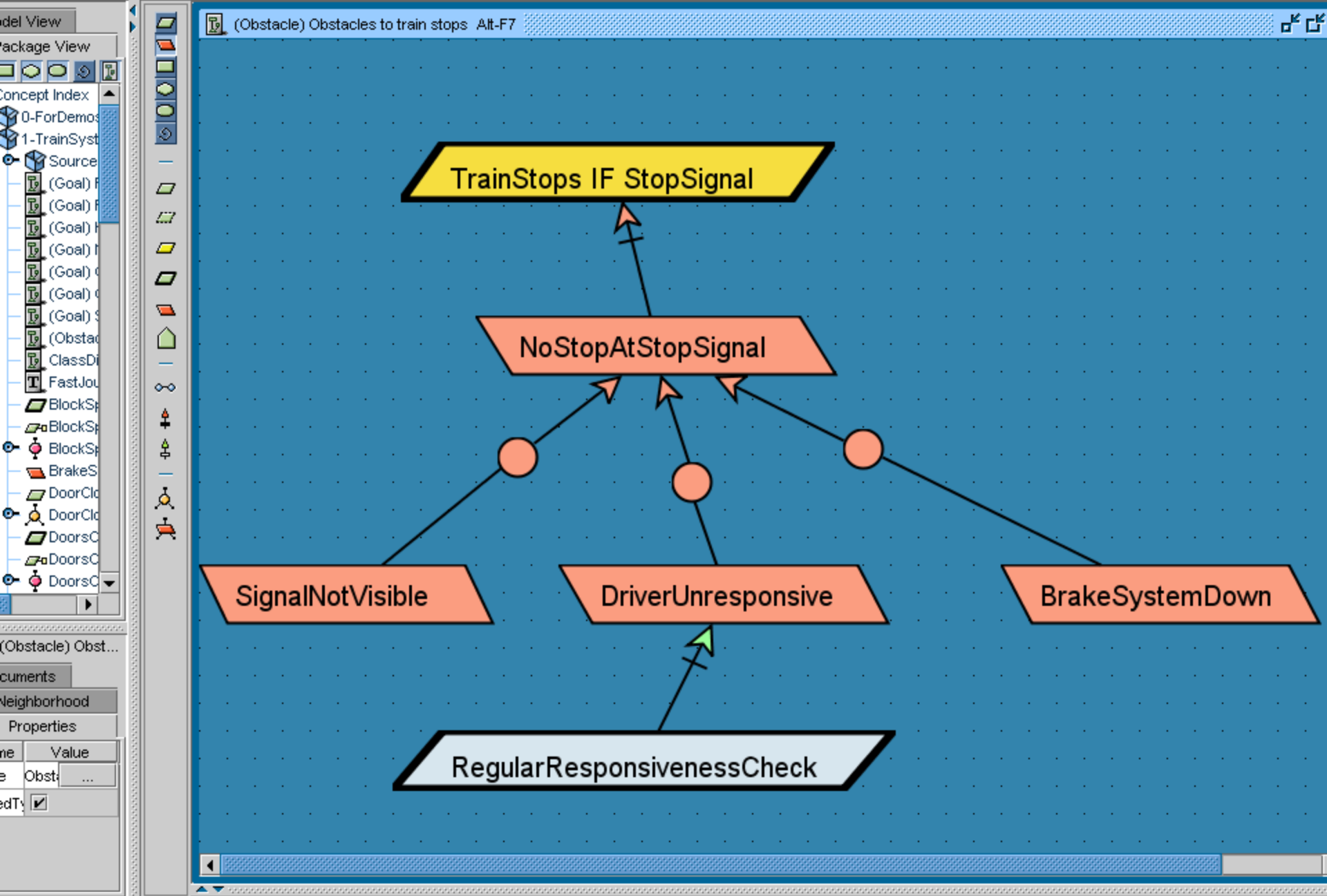
obstruction of safety goal: obstacle = hazard

obstruction of security goal: obstacle = threat



# Obstacle analysis for increased reliability & security

- ◆ Anticipate obstacles ...
  - ⇒ new goals (countermeasures), deidealized model
  - ⇒ more complete, realistic requirements
  - ⇒ more robust system



Model View

Package View

Concept Index

- 0-ForDemos
- 1-TrainSystem
- Source
- (Goal) F
- (Goal) F
- (Goal) H
- (Goal) M
- (Goal) C
- (Goal) C
- (Goal) S
- (Obsta
- ClassD
- FastJou
- BlockSp
- BlockSp
- BlockSp
- BrakeS
- DoorCl
- DoorCl
- DoorsC
- DoorsC
- DoorsC

(Obstacle) Obst...

Documents

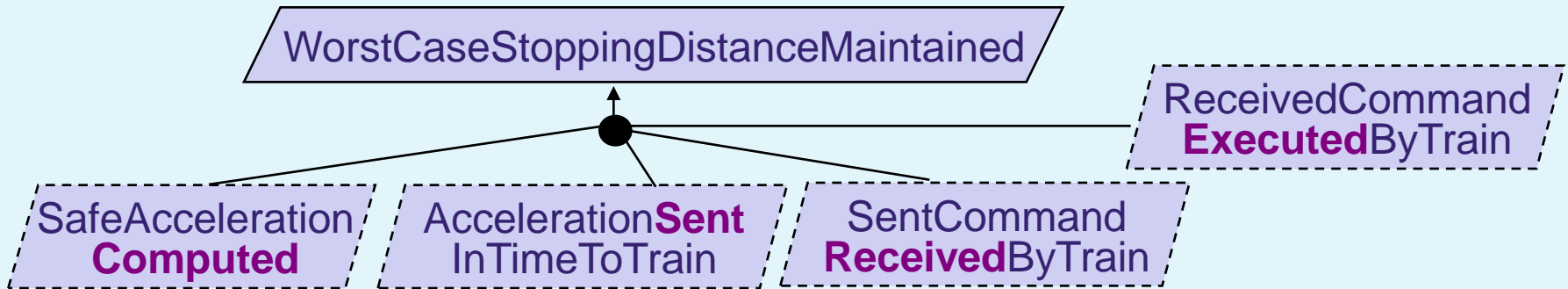
Neighborhood

Properties

Name	Value
Obst:	...

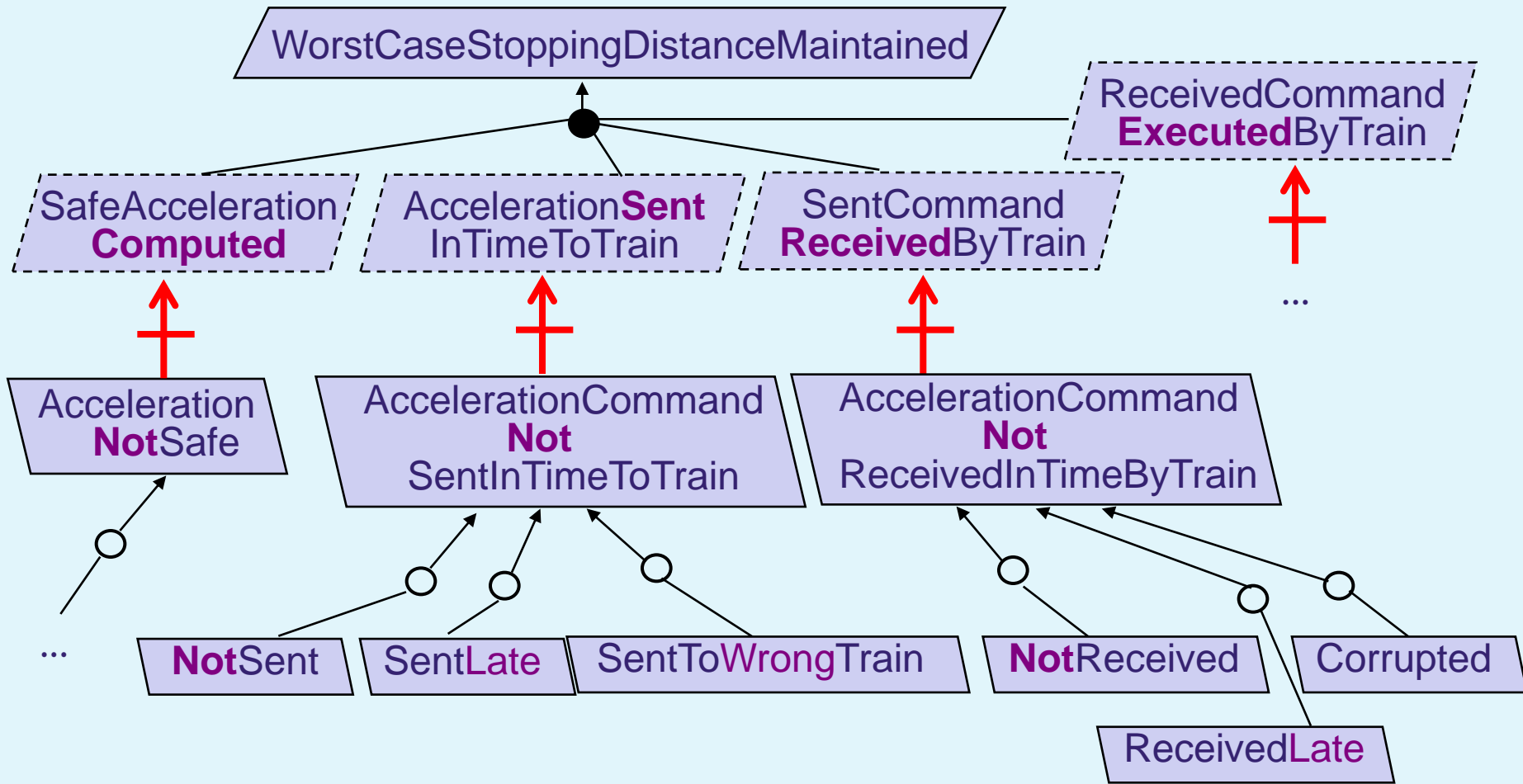
edT:

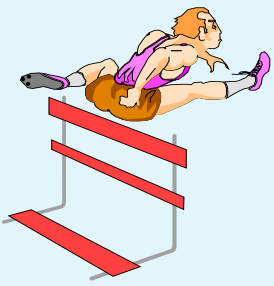
# Obstacle models as goal-anchored fault trees





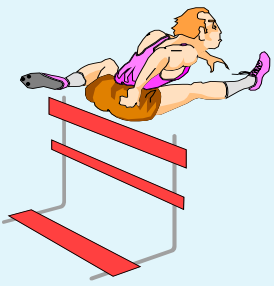
# Obstacle models as goal-anchored fault trees





# Obstacle analysis

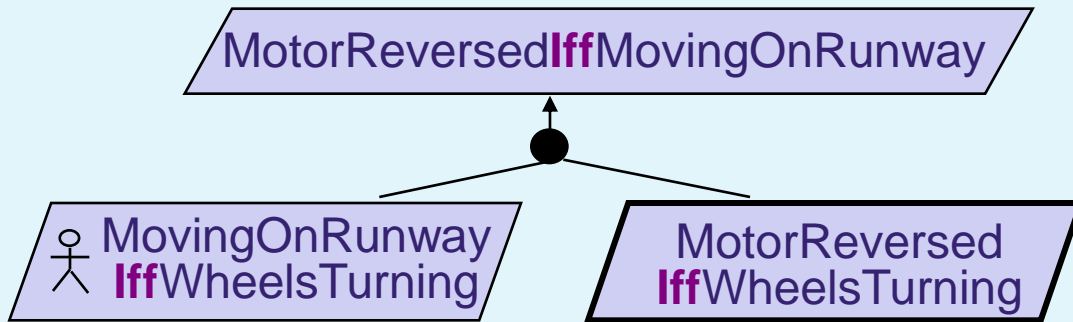
- ◆ For every leaf goal in refinement graph (requirement or expectation):
  - **identify** as many obstacles to it as possible
  - **assess** their likelihood & severity
  - **resolve** them according to likelihood/severity



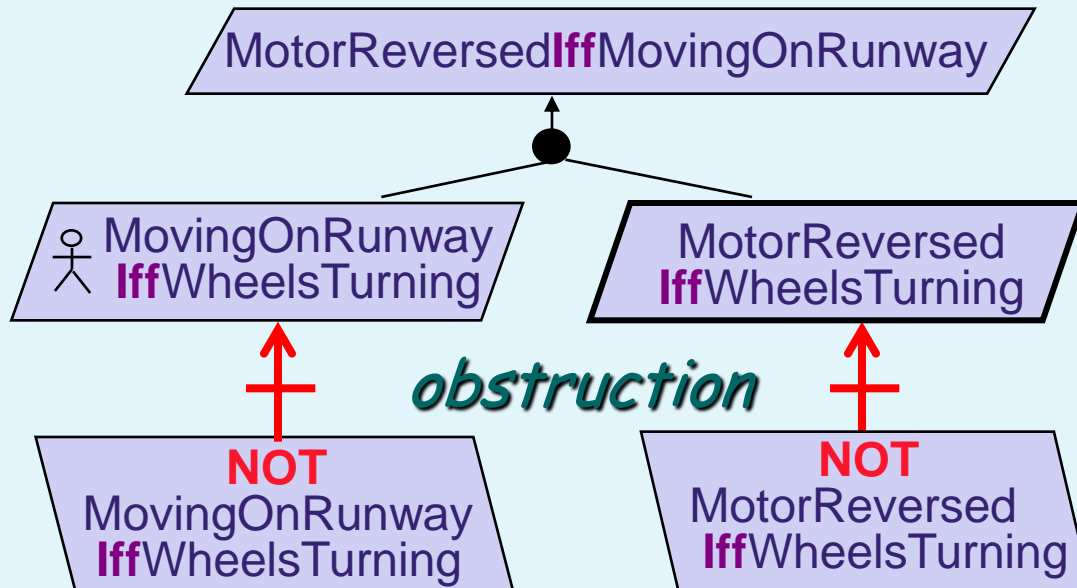
# Obstacle identification

- ◆ For obstacle to goal  $G$ :
    - negate  $G$ ;
    - find as many AND/OR refinements of  $\neg G$  as possible in view of domain properties ...
    - ... until reaching obstruction preconditions that are *feasible* (through a system scenario)
- = *goal-anchored* fault-tree construction

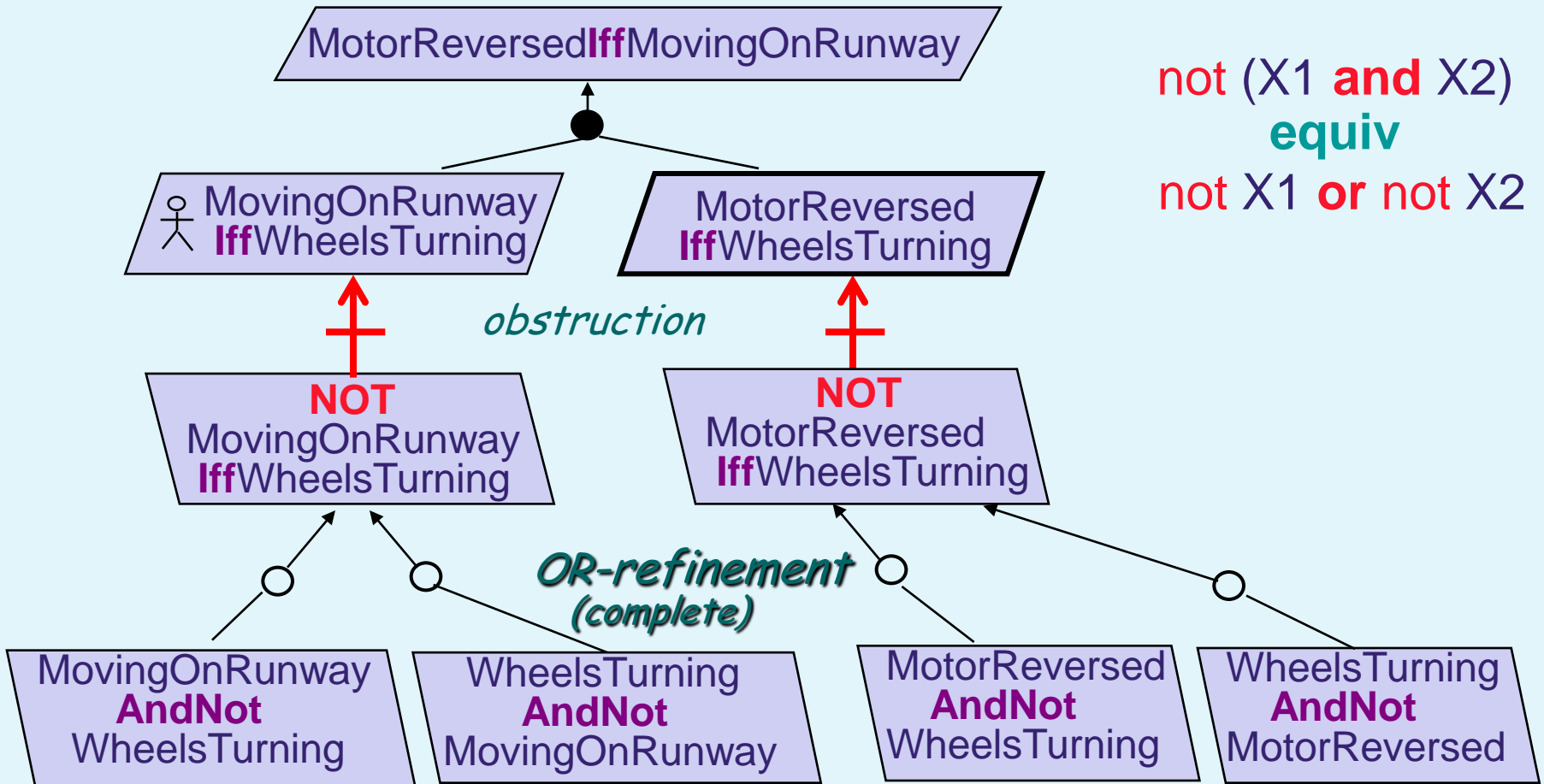
# Obstacle identification: example



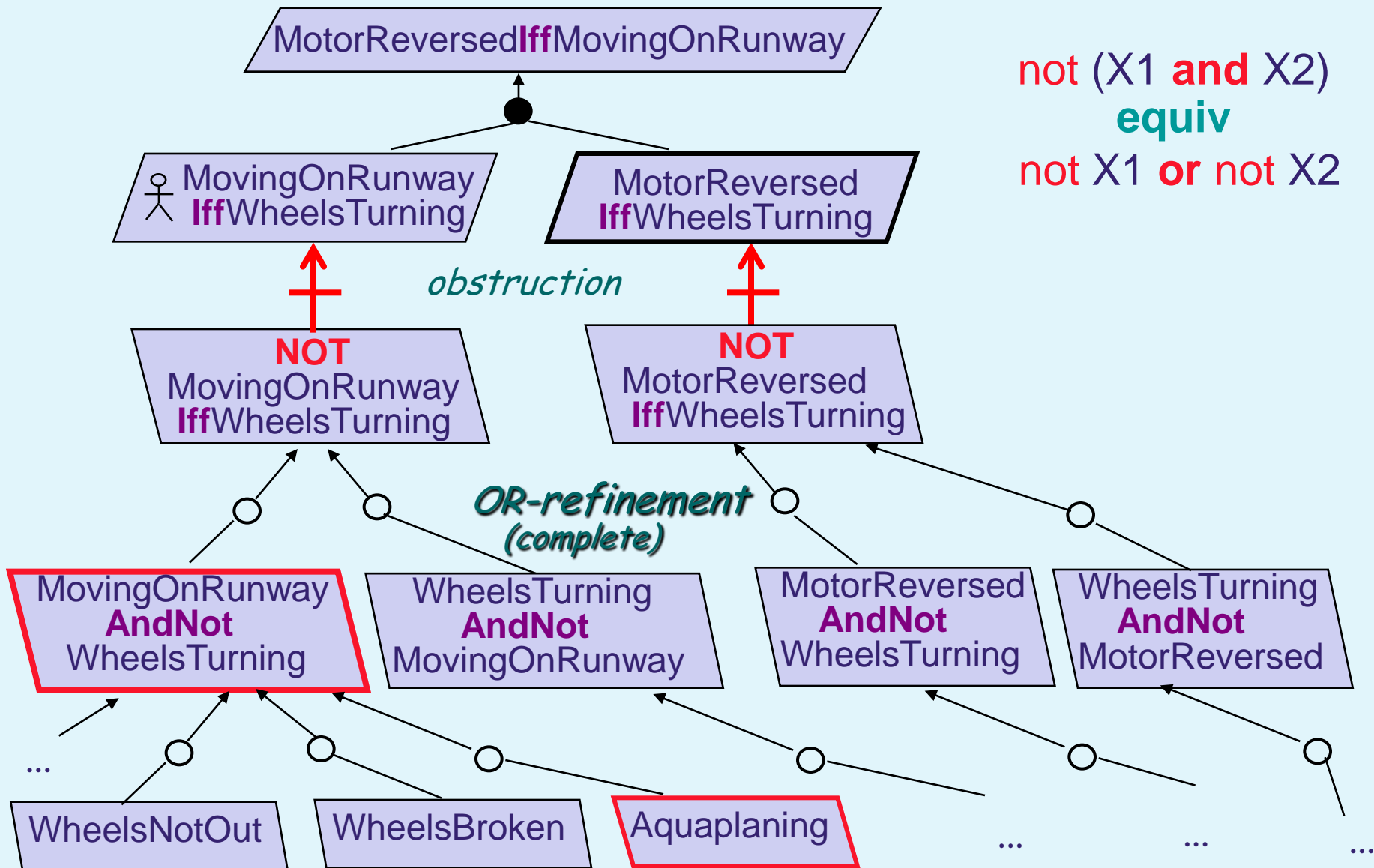
# Obstacle identification: example



# Obstacle identification: example



# Obstacle identification: example



# Obstacle assessment & resolution

- ◆ To *assess* likelihood & severity of identified obstacle: cfr. risk management techniques
- ◆ To *resolve* identified obstacle:
  - *at RE time*: model transformation
    - generate *alternative* resolutions
    - select "best" resolution based on ...
      - likelihood/severity of obstacle
      - other non-functional/quality goals
  - *at run-time* (for non-severe, occasional obstacles):  
obstacle monitoring, run-time resolution  
(cf. specification-based intrusion detection)




# Generating obstacle resolutions

- ◆ Use of *model transformation operators* encoding resolution tactics
  - **Goal substitution:** consider alternative refinement of parent goal to avoid obstruction of child goal
    - MotorReversed **Iff** WheelsTurning
      - MotorReversed **Iff** *PlaneWeightSensed*
  - **Agent substitution:** consider altern. responsibilities
    - OnBoardTrainController → *VitalStationComputer*
  - **Goal weakening**
    - TrafficControllerOnDutyOnSector →  
TrafficControllerOnDutyOnSector **or** *WarningToNextSector*

# Generating obstacle resolutions (2)

- ◆ Model transformation operators (cont'd):
  - **Goal restoration:** enforce target condition at obstacle occurrence
    - ResourceNotReturnedInTime → *ReminderSent*
    - WheelsNotOut → *WheelsAlarmGenerated*
  - **Obstacle prevention:** new *Avoid* goal
    - AccelerationCommandCorrupted
      - *Avoid [AccelerationCommandCorrupted]*
  - **Obstacle mitigation:** tolerate obstacle but mitigate its effects
    - OutdatedSpeed/PositionEstimates
      - *Avoid [TrainCollisionWhenOutDatedTrainInfo]*

# Course outline

- ◆ Goal-oriented RE for high-assurance applications
  - Modeling goals, objects, agents, operations, behaviors
  - A goal-oriented model building method in action
  - Obstacle analysis for high assurance
  -  Formal reasoning about models
- ◆ Engineering security requirements
  - Security goals and their specification
  - Threat analysis for model consolidation
  - Analyzing conflicts among security goals
  - Model checking against confidentiality requirements

# Formal reasoning about system models ...

- ◆ To support more accurate analysis & derivations
  - Checking refinements & operationalizations
  - Generating obstacles to goals
  - Generating attack graphs
  - Analyzing conflicts
  - Synthesizing behavior models from scenarios & goals
  - Goal-oriented model animation
- ◆ Optional "button": *only when & where needed*
- ◆ Requires formal specifications to annotate models

# Some bits of real-time linear temporal logic

- P: P shall hold in the next state
- P: P shall hold in every future state
- P ~~W~~ N: P shall hold in every future state *unless* N holds
- ◇P: P shall hold in some future state
- <sub>≤T</sub>P: P shall hold in every future state up to T time units
- ◇<sub>≤T</sub>P: P shall hold within T time units
- + *past operators*: ●P, ■P, ◆P, ...

$$P \Rightarrow Q : \square (P \rightarrow Q)$$

$$@P : \bullet (\neg P) \wedge P$$

# Specifying goals in RT-LTL

Goal *Maintain* [DoorsClosedUntilNextStation]

FormalSpec  $\forall tr: \text{Train}, s: \text{Station}$

$\text{At}(tr, st) \wedge \circ \neg \text{At}(tr, st) \Rightarrow$

$tr.\text{Doors} = \text{"closed"} \mathcal{W} \text{At}(tr, \text{next}(st))$

Goal *Achieve* [FastJourneyBetweenStations]

FormalSpec  $\forall tr: \text{Train}, s: \text{Station}$

$\text{At}(tr, st) \Rightarrow \diamond_{\leq T} \text{At}(tr, \text{next}(st))$

*Achieve P, Cease P*

*Maintain P, Avoid P* : goal specification patterns

# Goal-oriented spec of operations

Operation SendCommand

Input  $tr, tr'$ : Train

Output  $cm$ : CommandMsg

DomPre  $\neg \text{Sent}(cm, tr)$

DomPost  $\text{Sent}(cm, tr)$

ReqPost for *SafeCommandMsg*

Following  $(tr, tr') \rightarrow$

$cm.\text{Accel} \leq F(tr, tr') \wedge cm.\text{Speed} > G(tr)$

ReqTrig for *CommandMsgSentInTime*

$\blacksquare_{\leq 0.5 \text{ sec}} \neg \exists cm': \text{Sent}(cm', tr)$

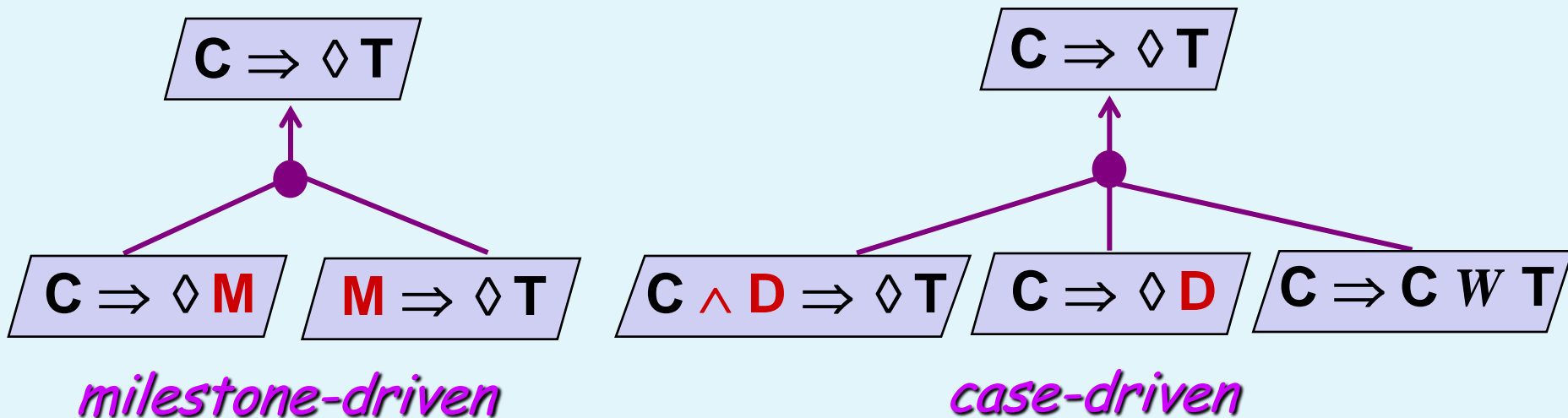
# Formal reasoning: refinement checking

- ◆ A set of assertions  $\{A_1, \dots, A_n\}$  correctly refines assertion  $A$  in domain theory  $Dom$  iff
  - $\{A_1, \dots, A_n, Dom\} \models A$  *completeness*
  - $\{A_1, \dots, A_n, Dom\} \not\models \text{false}$  *consistency*
  - $\{\bigwedge_{j \neq i} A_j, Dom\} \not\models A$  for each  $i \in [1..n]$  *minimality*
- ◆ Refinement checking =
  - Check that a refinement is correct
  - If not, suggest missing sub-assertions  $A_i$
- ◆ Can be used for checking goal models, obstacle models, anti-goal models; and reveal missing subgoals, subobstacles, vulnerabilities (completeness is essential!)



# Refinement checking: using refinement patterns

- ◆ Build catalogue of refinement patterns that encode *refinement tactics*
- ◆ Prove patterns formally, once for all
- ◆ Reuse through instantiation, in matching situation
- ◆ Some frequent patterns:



# Checking a goal refinement with patterns

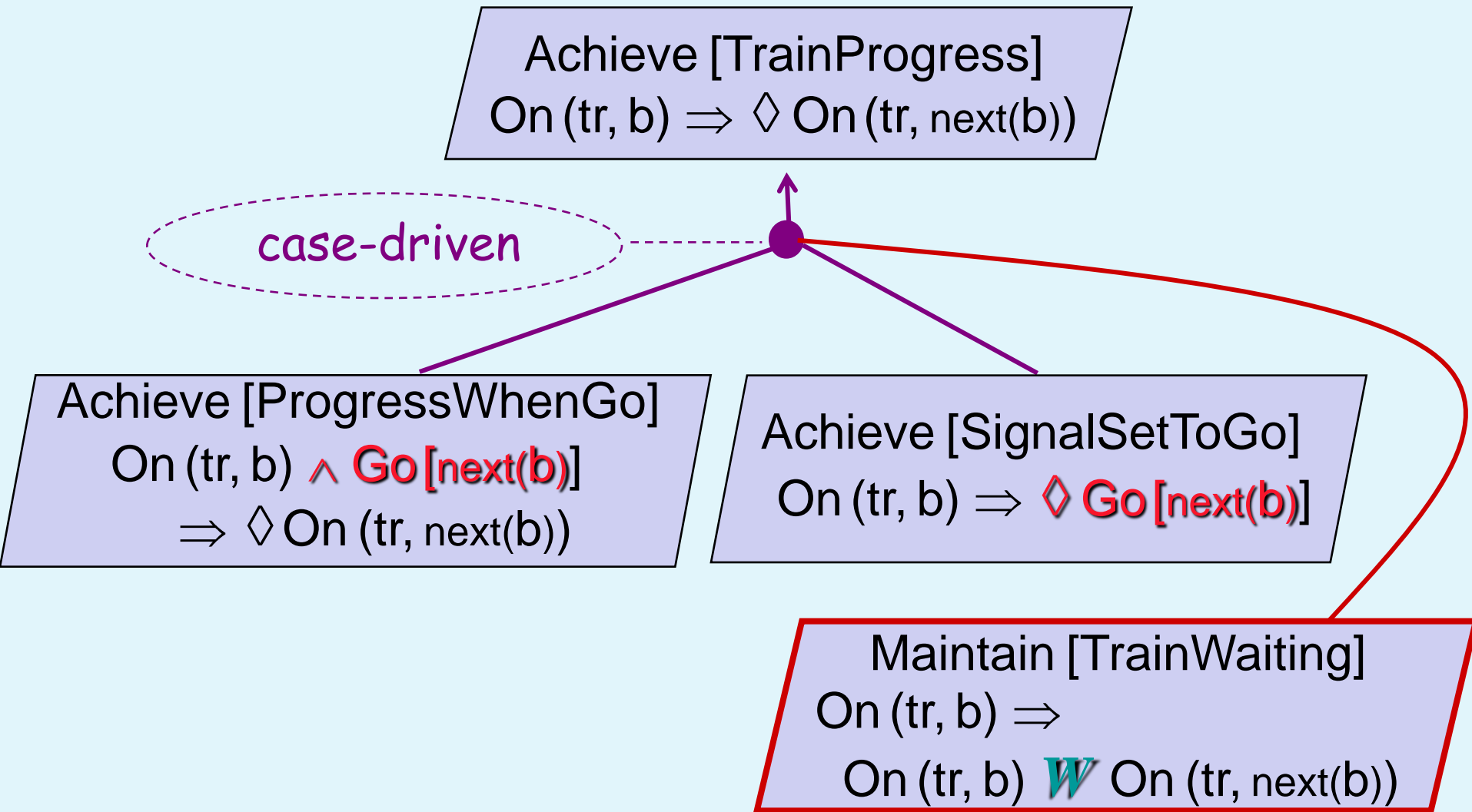
Achieve [TrainProgress]  
 $\text{On}(\text{tr}, b) \Rightarrow \diamond \text{On}(\text{tr}, \text{next}(b))$

*missing subgoal !!  
detectable automatically*

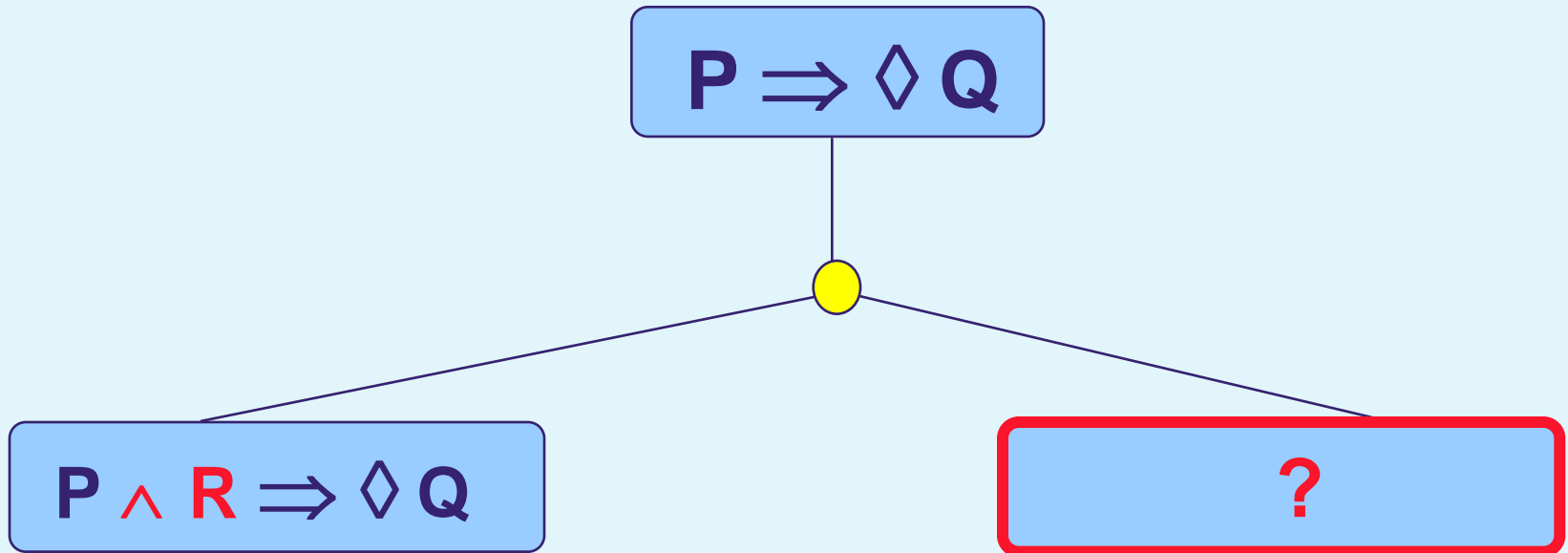
Achieve [ProgressWhenGo]  
 $\text{On}(\text{tr}, b) \wedge \text{Go}[\text{next}(b)]$   
 $\Rightarrow \diamond \text{On}(\text{tr}, \text{next}(b))$

Achieve [SignalSetToGo]  
 $\text{On}(\text{tr}, b) \Rightarrow \diamond \text{Go}[\text{next}(b)]$

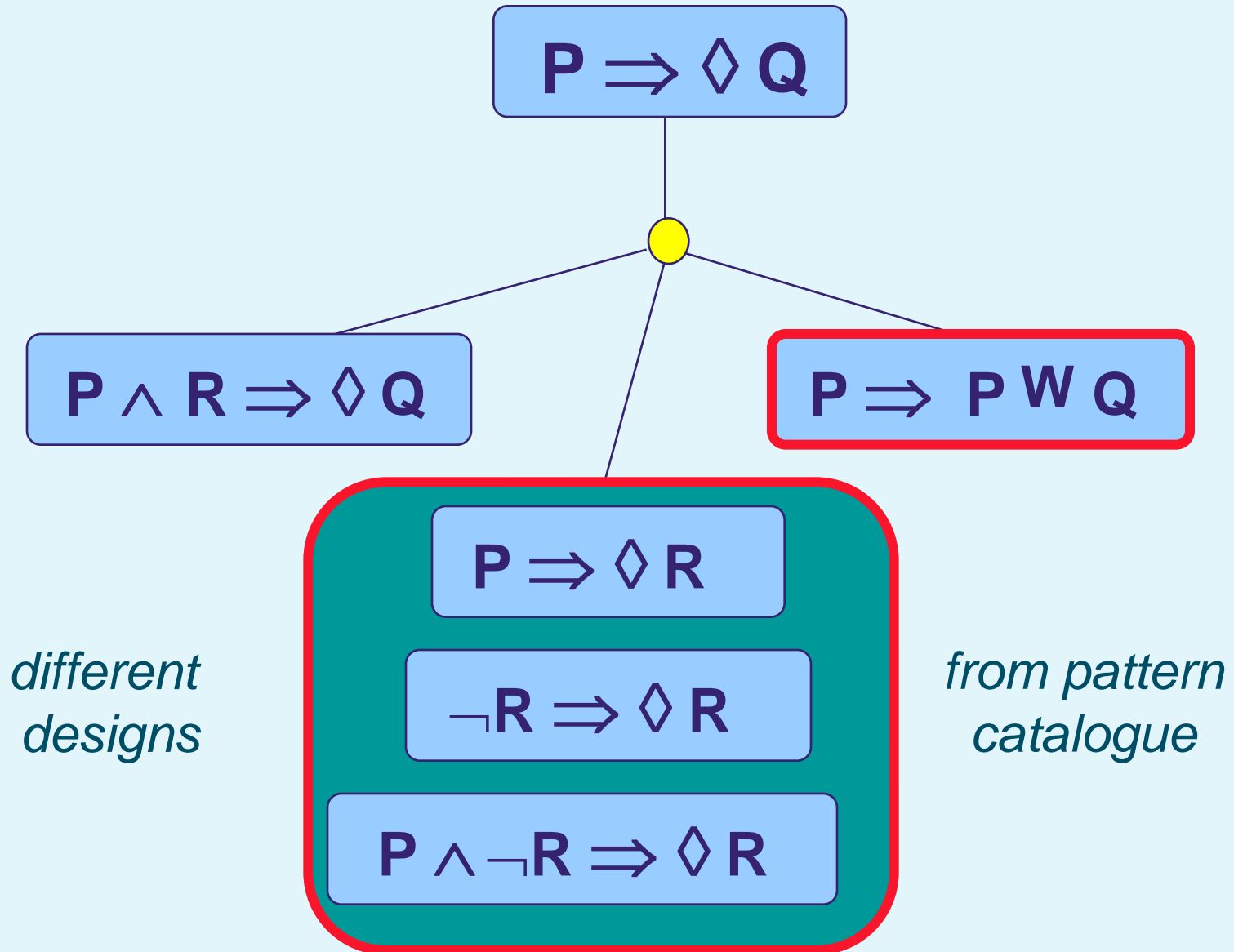
# Checking goal refinements with patterns



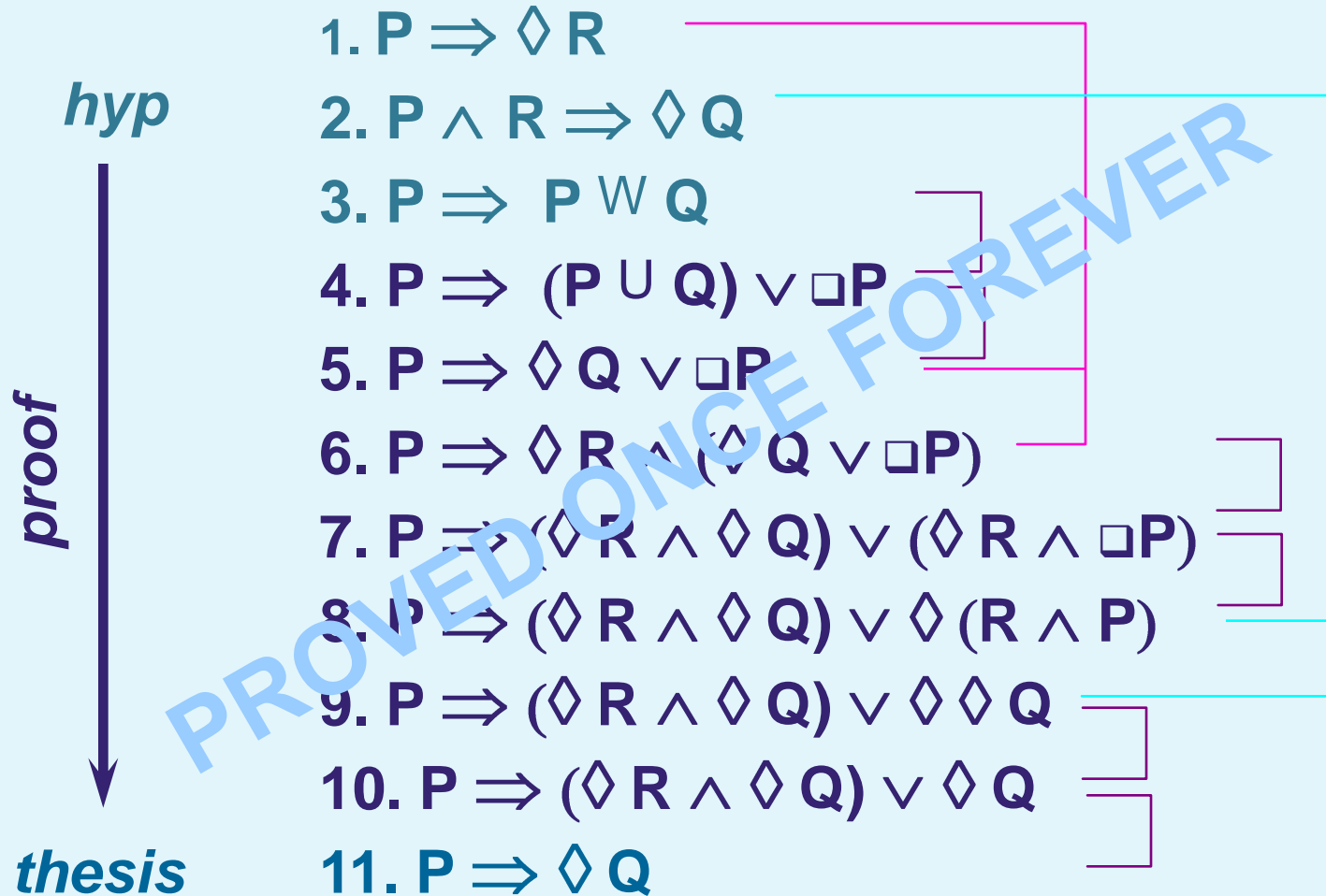
# Patterns provide guidance in formal refinement



# Patterns provide guidance in formal refinement (2)

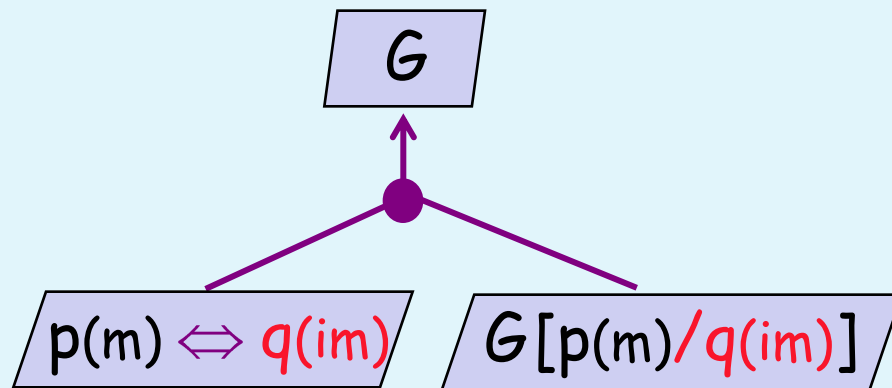


# Use formal pattern => reuse formal proof



# Resolving goal unrealizability: the *Introduce Accuracy* goal pattern

- ◆ WHEN:  
agent **ag** cannot monitor variable **m** to realize  $G[m]$
- ◆ WHAT:
  - introduce *monitorable image* **im** of **m**
  - generate refinement :



# Generating refinements & assignments

Introduce *Accuracy* goal: example

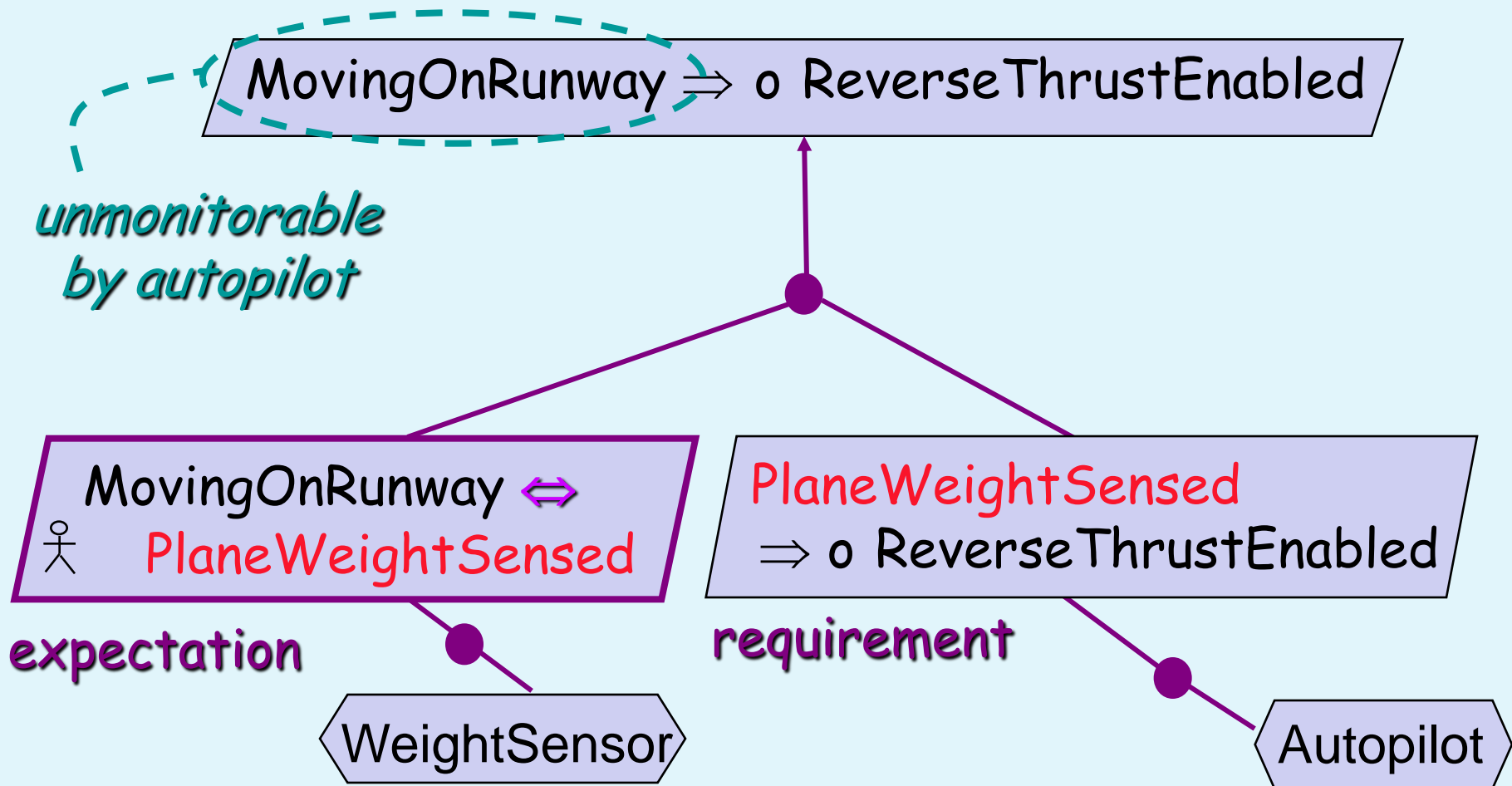
MovingOnRunway  $\Rightarrow$  0 ReverseThrustEnabled

*unmonitorable  
by autopilot*



# Generating refinements & assignments

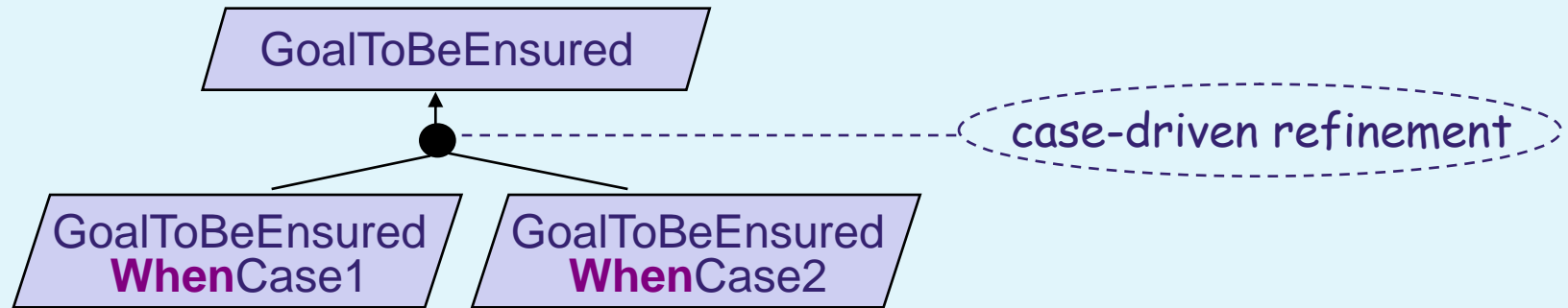
Introduce *Accuracy* goal: example



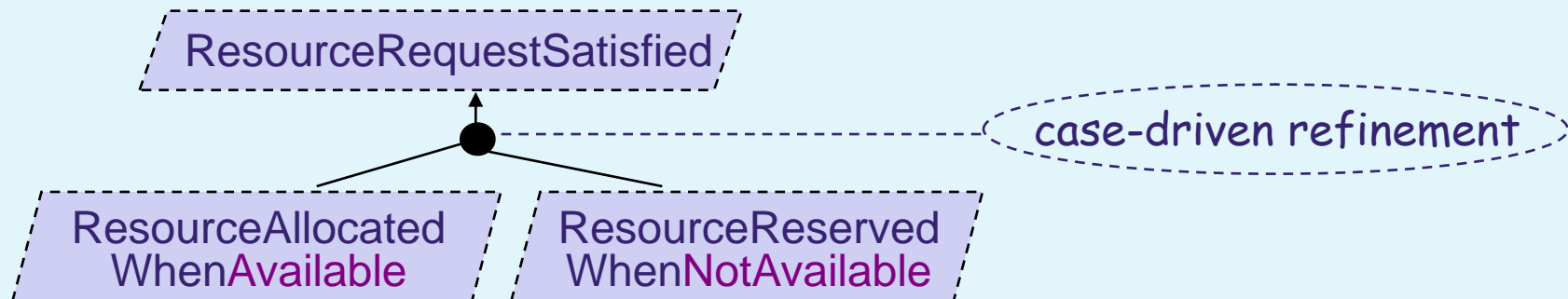
# Formal refinement patterns can be used informally

## ◆ Refinement by case

- Applicable when goal achievement space can be *partitioned into cases*



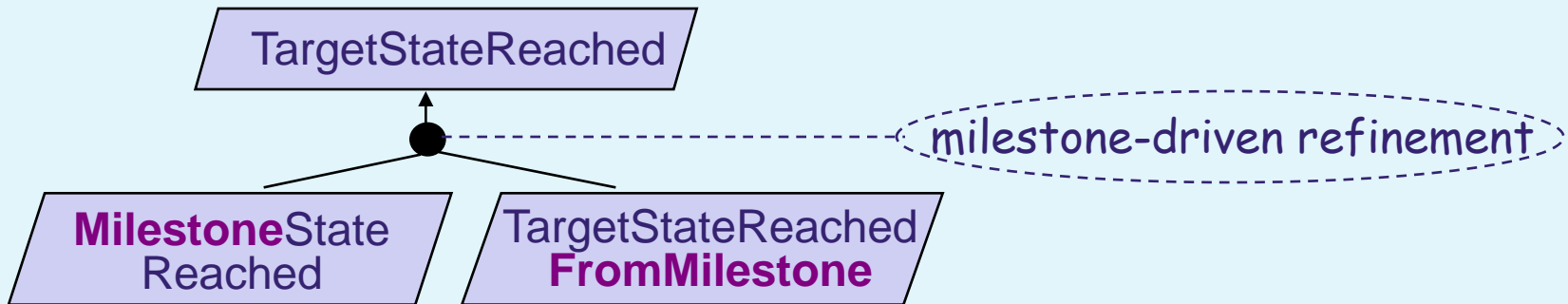
## - Example of use:



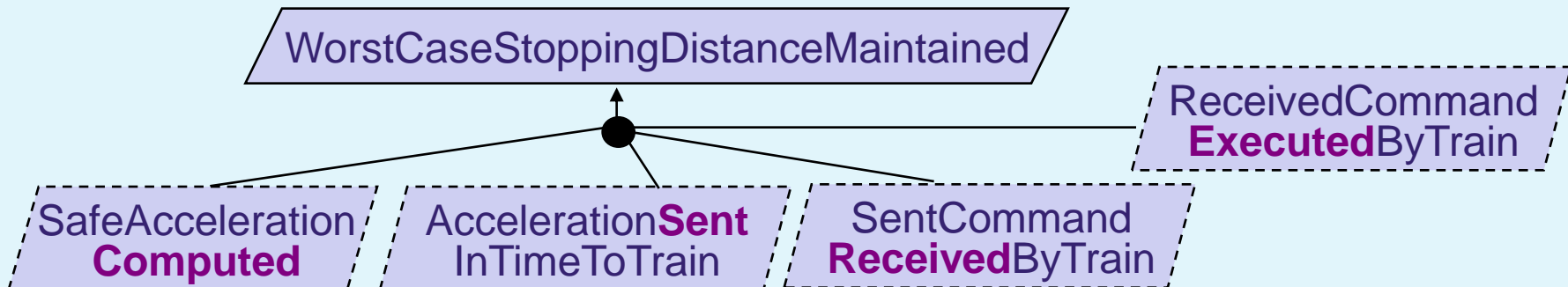
# Formal patterns can be used informally (2)

## ◆ Refinement by milestone

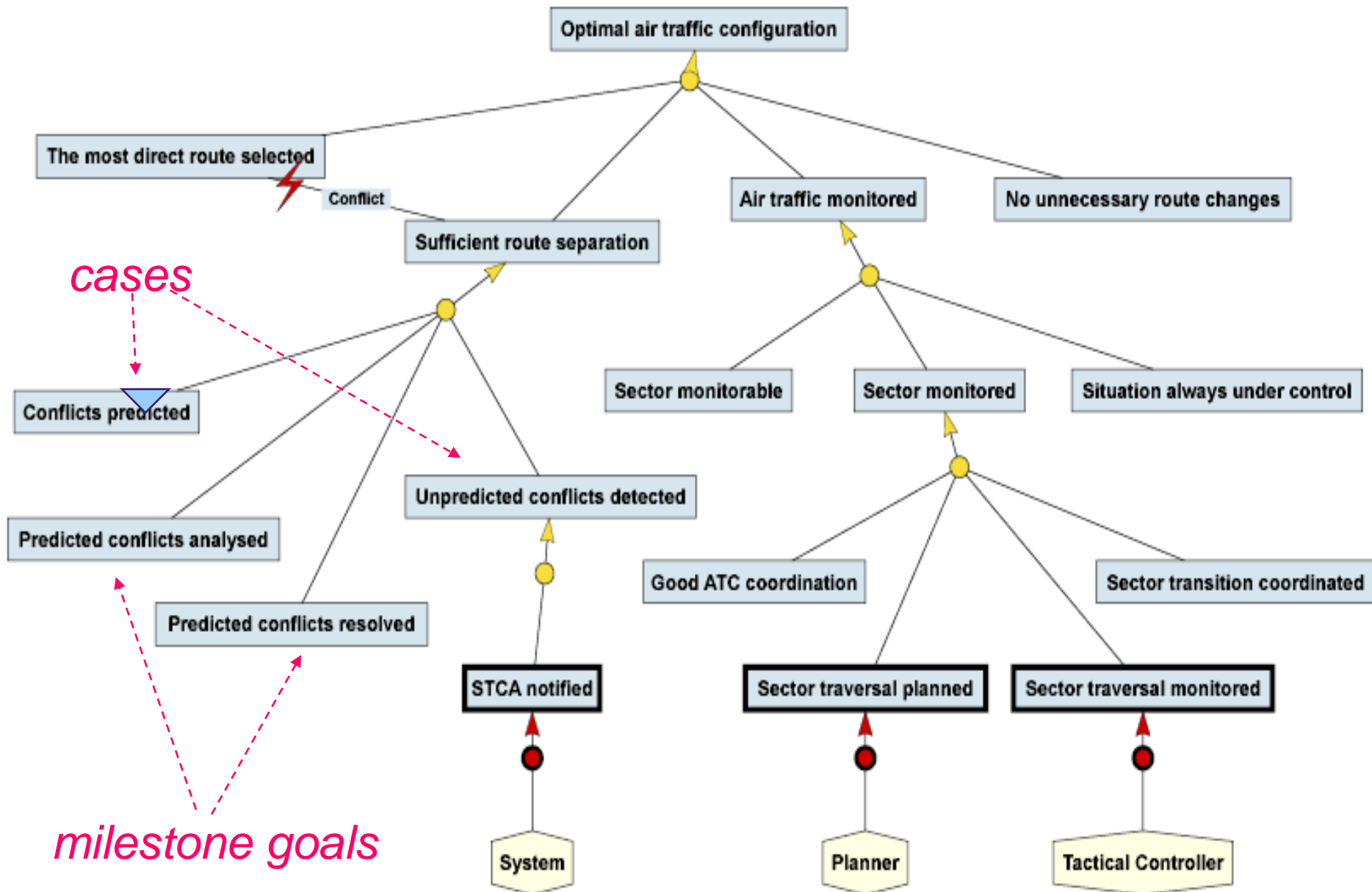
- Applicable when *milestone states* can be identified on the way to the goal's target condition



- Example of use:

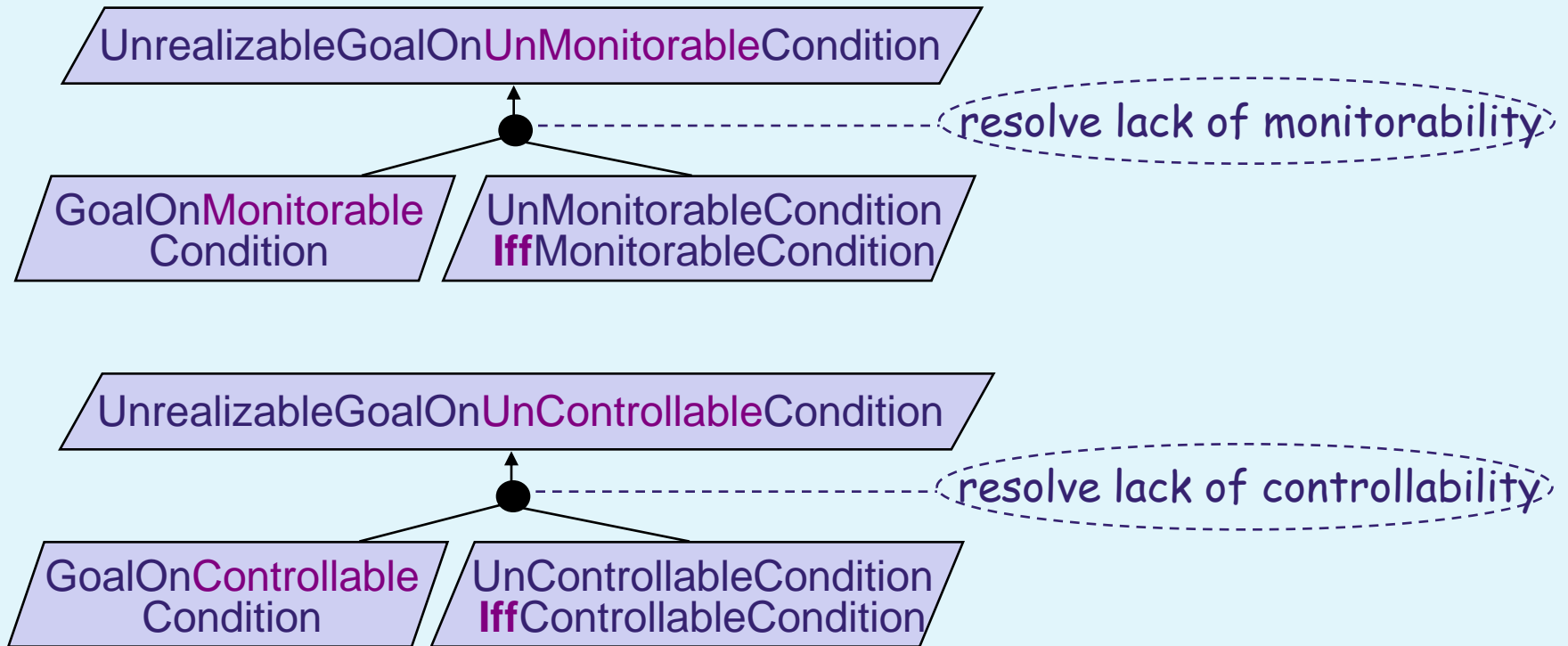


# Informal use of patterns can reveal errors



# Formal patterns can be used informally (3)

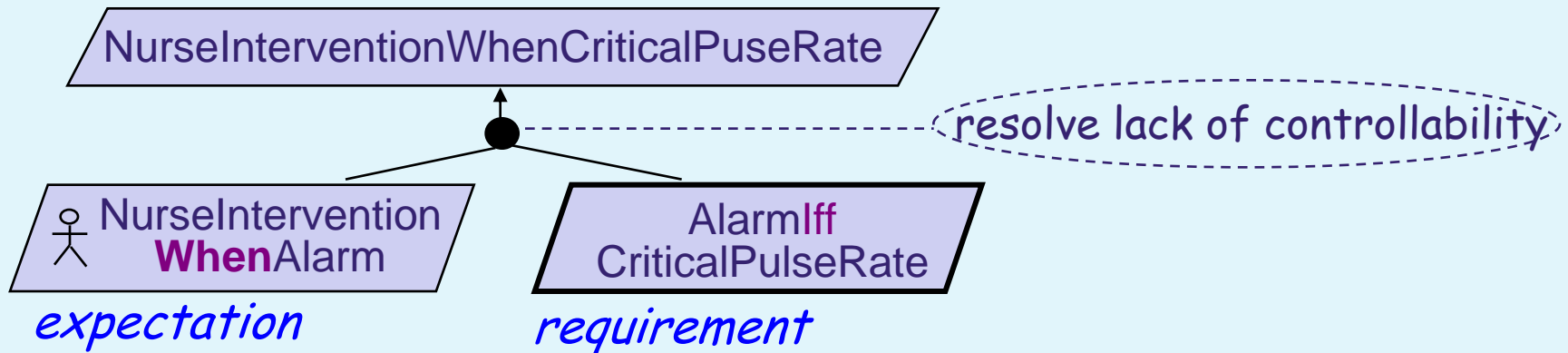
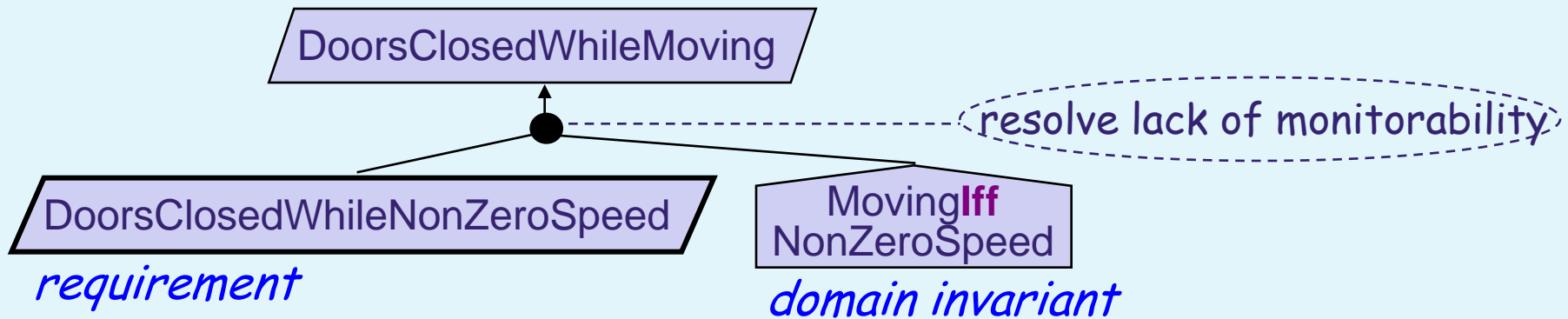
## ◆ Refinement towards goal realizability



child node may be goal (incl. requirement, expectation)  
or domain property (invariant/hypothesis)

# Formal patterns can be used informally (4)

Refinement towards goal realizability: example of use



# Refinement checking: roundtrip use of bounded SAT solver

- ◆ Incremental check/debug of model fragments
- ◆ On selected object instances (*propositionalization*)
- ◆ With bounded traces (to be given)
- ◆ Output:
  - OK (no counterexample found within trace bound)
  - KO + counter-example scenario satisfying

$$G_1 \wedge \dots \wedge G_n \wedge \text{Dom} \wedge \neg G$$



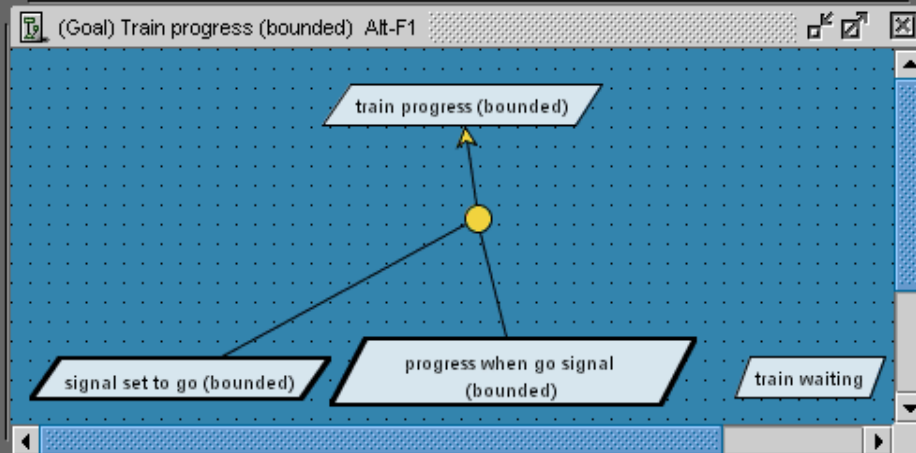
Package View Model View

- Train progress
- Instances
- Objects
- (Goal) Train progress (bounde
- (Goal) Train progress (refinem
- (Goal) Train progress (unbound
- (Object) Train progress
- Train progress (bounded) (ops
- move train to next block
- move train to next block "Output
- progress when go signal (bound
- progress when go signal (bound
- progress when go signal (unb
- progress when go signal (unb
- set to go signal
- set to go signal "Output" Block
- signal set to go (bounded)
- signal set to go (bounded) "Op
- signal set to go (unbounded)
- signal set to go (unbounded) "F
- Train "Input" move train to next
- Train "Input" set to go signal
- train progress (bounded)
- train progress (bounded) "Refi

Documents

Properties Neighborhood

Name	Value
Pattern	...
AltName	...
Complete	<input type="checkbox"/>



FormalDef (formula) Alt-F2

**b** **i** **u** default Styles

// FormalDef of **train progress (bounded)**  
 All tr: **Train**, b: **Block**  
**nextBlock( On(tr) , b )**  
 $\implies \Leftrightarrow [ = < 4 \text{ steps} ] \text{ On}(tr) = b$

New concept

FormalDef (formula) Alt-F4

**b** **i** **u** default Styles

// FormalDef of **signal set to go (bounded)**  
 All tr: **Train**, b: **Block**  
**nextBlock( On( tr ) , b )**  
 $\implies \Leftrightarrow [ = < 2 \text{ steps} ] \text{ go signal} ( b ) = \text{green}()$

FormalDef (formula) Alt-F5

**b** **i** **u** default Styles

// FormalDef of **progress when go signal (bounded)**  
 All tr: **Train**, b: **Block**  
**nextBlock( On(tr) , b )  $\wedge$  go signal ( b ) = green()**  
 $\implies \Leftrightarrow [ = < 2 \text{ steps} ] \text{ On}(tr) = b$

New concept Reference

Attributes and Check of the refinement (dependents values) Alt-F3

**b** **i** **u**

// STATE 0 LOOP path : states repeating for ever in this order  
**On(Train [1]()) = Block [2]()**  
**go signal(Block [1]()) = red()**  
**go signal(Block [3]()) = red()**  
**go signal(Block [2]()) = green()**  
**nextBlock(Block [1](),Block [2]())** is True  
**nextBlock(Block [3](),Block [1]())** is True  
**nextBlock(Block [2](),Block [3]())** is True

// STATE 1 (still within loop)  
**On(Train [1]()) = Block [1]()**  
**go signal(Block [3]()) = green()**  
**go signal(Block [2]()) = red()**

Sep 19, 2004 11:02:59 AM INFO: Scenario found.

Sep 19, 2004 11:03:00 AM INFO: Request FormalCheckAnalysisOfRefinement result has been received.

Sep 19, 2004 11:03:00 AM INFO: Request FormalCheckAnalysisOfRefinement result has been received.

Sep 19, 2004 11:03:00 AM INFO: Request FormalCheckAnalysisOfRefinement result has been received.

# Refinement checker



# Formal reasoning: abductive generation of obstacles

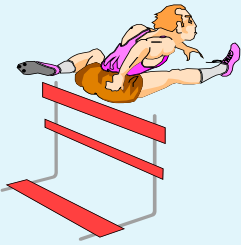
- ◆ Aim: Find  $O$  such that

$$O, \text{Dom} \Vdash \neg G, \text{Dom} \not\models \neg O$$

- ◆ Approach 1: Use precondition calculus to get  $\neg G$  from  $\text{Dom}$

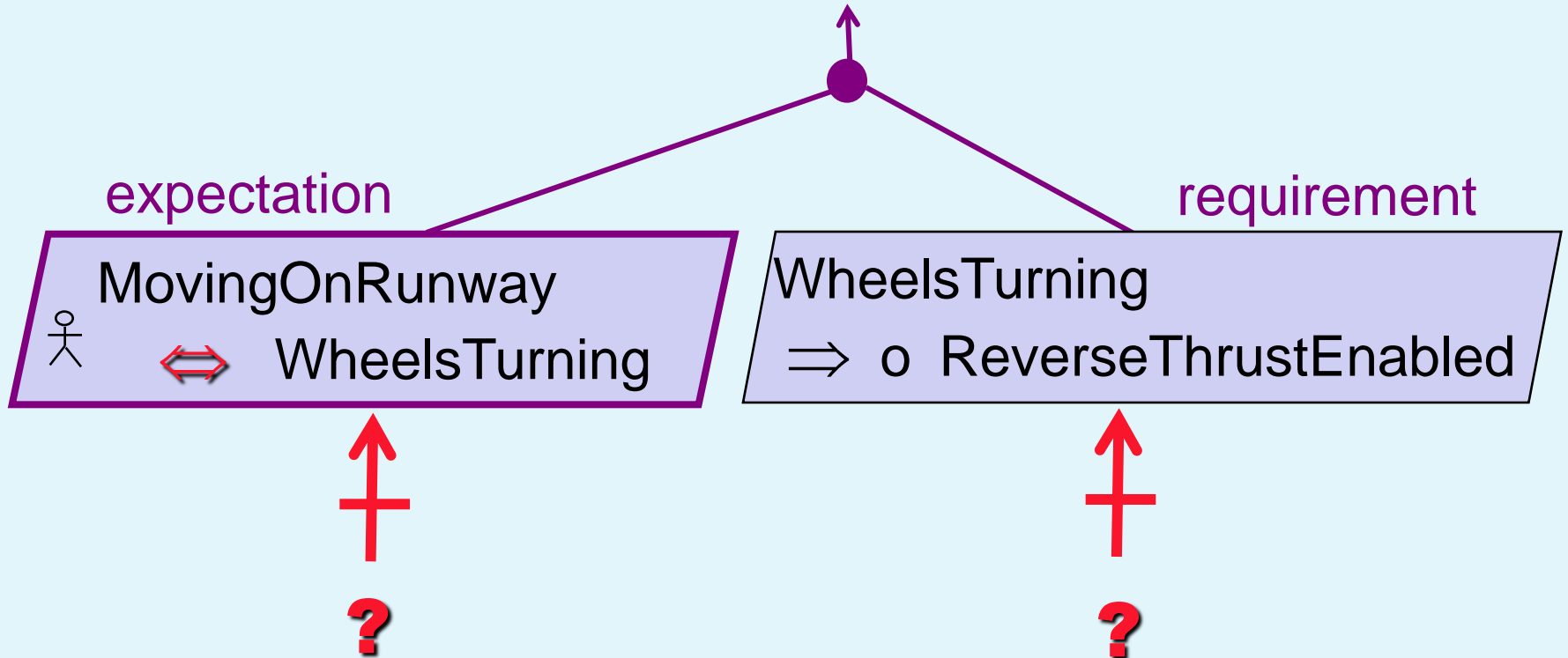
= regression of goal negation through domain theory

- ◆ Approach 2: Use **formal obstruction patterns**



# Generating obstacles by regression

MovingOnRunway  $\Rightarrow$  o ReverseThrustEnabled



# Generating obstacles by regression

Find precondition for obstruction of ...

MovingOnRunway  $\Rightarrow$  WheelsTurning

# Generating obstacles by regression

Find precondition for obstruction of ...

$\text{MovingOnRunway} \Rightarrow \text{WheelsTurning}$

→ goal negation:

◇  $\text{MovingOnRunway} \wedge \neg \text{WheelsTurning}$

# Generating obstacles by regression

Find precondition for obstruction of ...

$\text{MovingOnRunway} \Rightarrow \text{WheelsTurning}$

→ goal negation:

◇  $\text{MovingOnRunway} \wedge \neg \text{WheelsTurning}$

→ regress through Dom:

? *necessary conditions for wheels turning?*

$\text{WheelsTurning} \Rightarrow \neg \text{Aquaplaning}$

i.e.  $\text{Aquaplaning} \Rightarrow \neg \text{WheelsTurning}$

# Generating obstacles by regression

Find precondition for obstruction of ...

$\text{MovingOnRunway} \Rightarrow \text{WheelsTurning}$

→ goal negation:

◇  $\text{MovingOnRunway} \wedge \neg \text{WheelsTurning}$

→ regress through Dom:

? *necessary conditions for wheels turning?*

$\text{WheelsTurning} \Rightarrow \neg \text{Aquaplaning}$

i.e.  $\text{Aquaplaning} \Rightarrow \neg \text{WheelsTurning}$

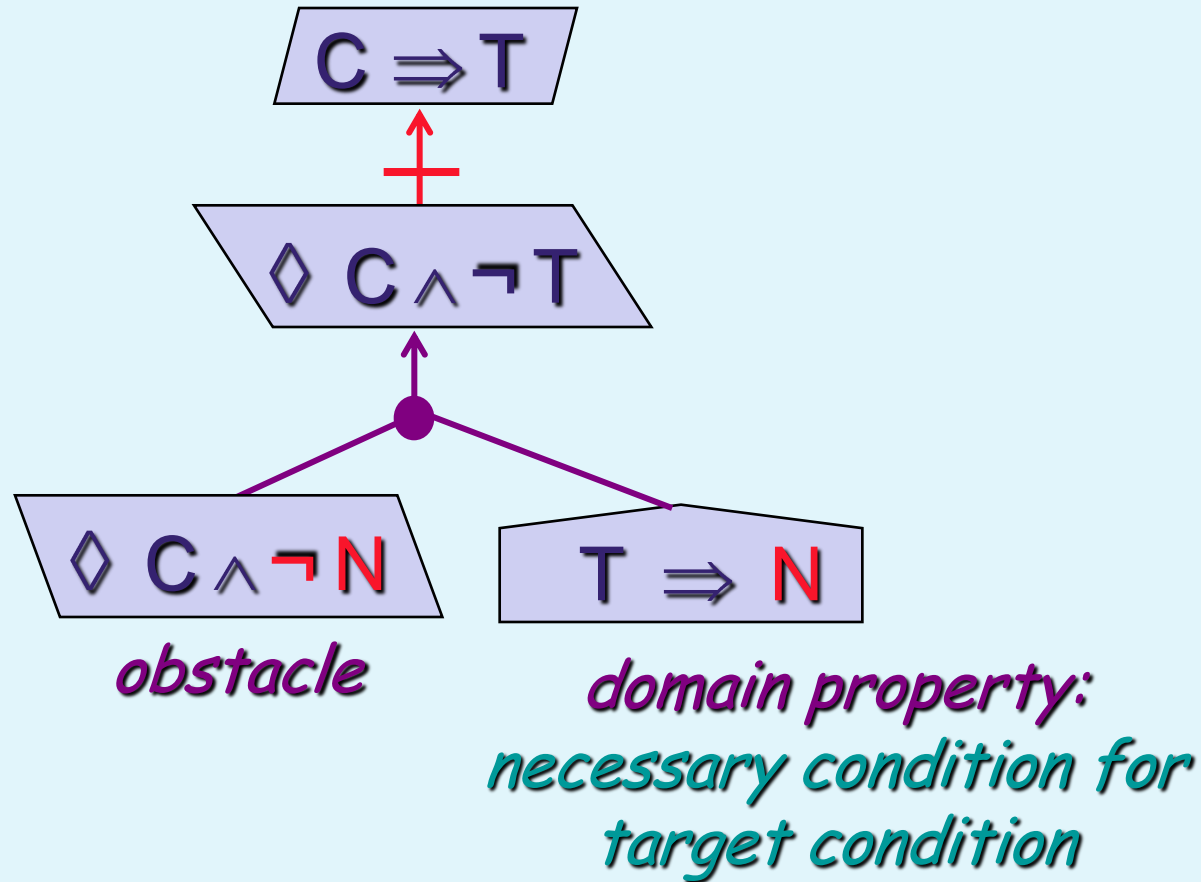
→ RHS unifiable:

◇  $\text{MovingOnRunway} \wedge \text{Aquaplaning}$

*Warsaw obstacle*

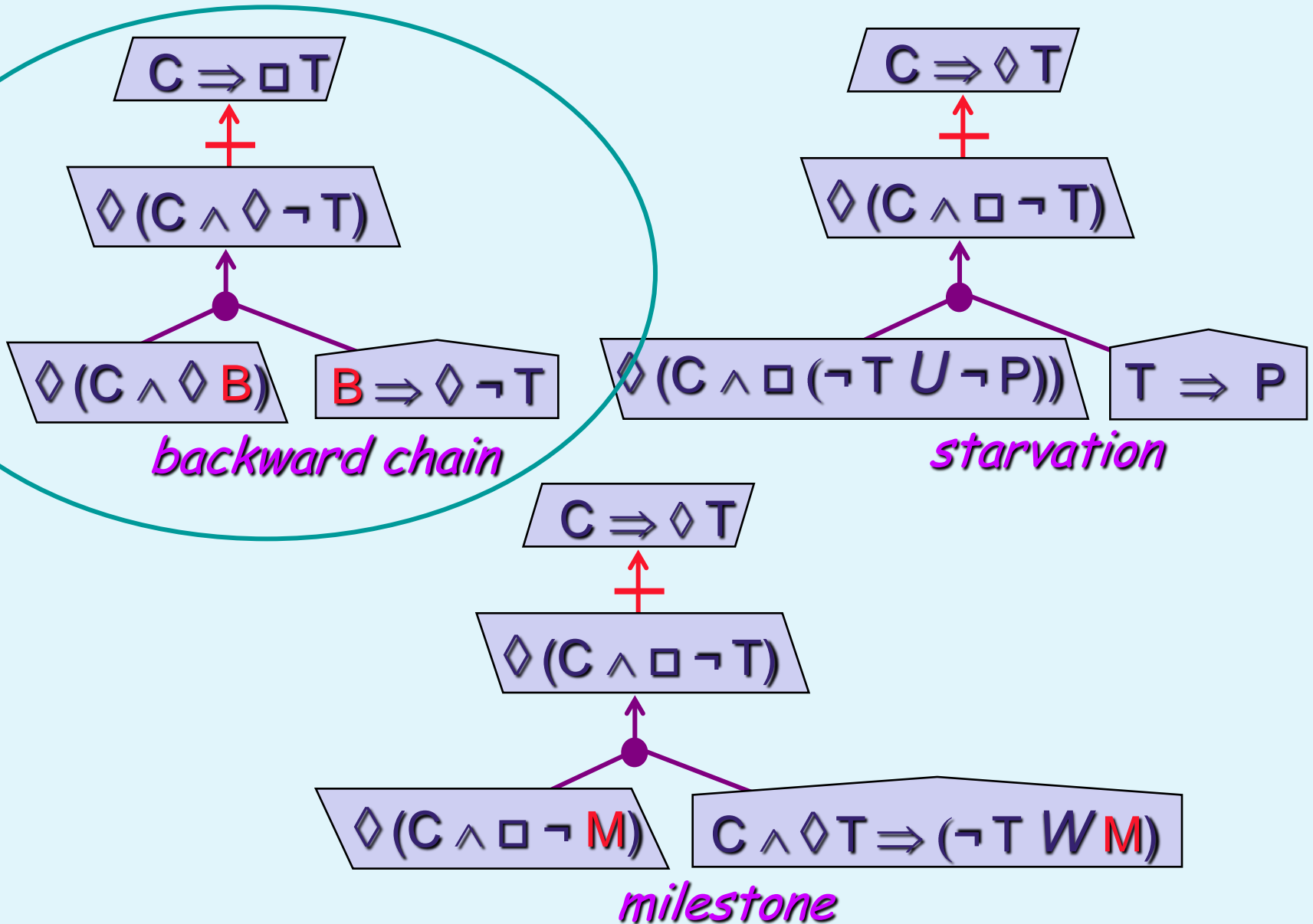
## ... or use formal obstruction patterns

- ◆ Very frequent pattern, used in this example:



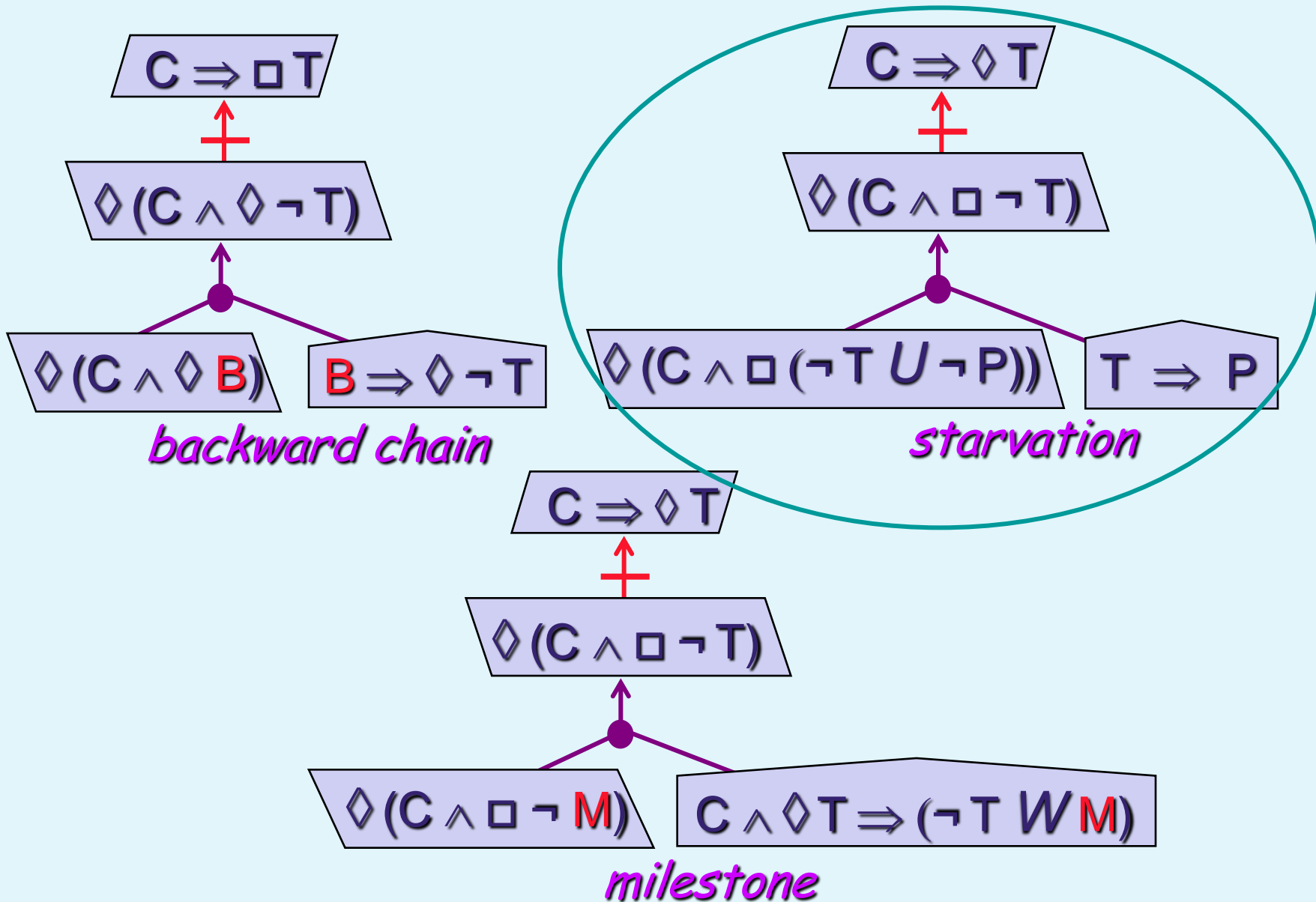
- ◆ Can be used to *elicit domain properties* as well

# Some frequent obstruction patterns

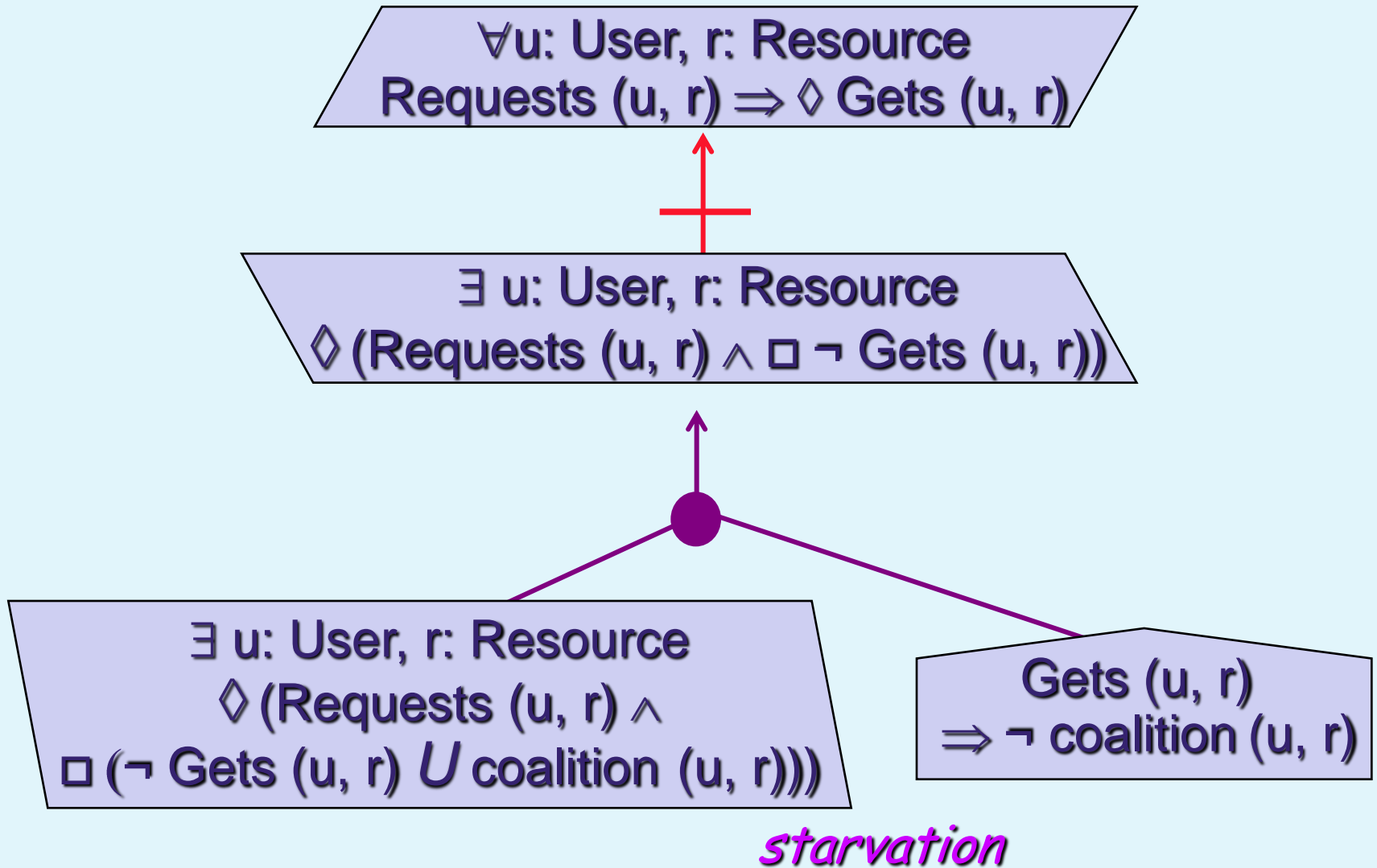




# Some frequent obstruction patterns



# Example of pattern instantiation



# Course outline

## ◆ Goal-oriented RE for high-assurance applications

- Modeling goals, objects, agents, operations, behaviors
- A goal-oriented model building method in action
- Checking goal refinements
- Obstacle analysis for high-assurance applications

## ◆ Engineering security requirements



- **Security goals and their specification**
- Threat analysis for model consolidation
- Analyzing conflicts among security goals
- Model checking against confidentiality requirements

# Application-level security

- ◆ Application is secure iff meets security goals
- ◆ Security goal refers to environment assets to be protected against undesired behaviors
  - Confidentiality, integrity, availability, privacy, accountability, non-repudiation, ...
- ◆ Threat = obstacle to security goal
- ◆ Security countermeasure = obstacle resolution

# Specification patterns for security goals

## ◆ Confidentiality goals

Avoid [SensitiveInfoKnownByUnauthorizedAgent]

$\forall ag: \text{Agent}, ob: \text{Object}$

$\neg \text{Authorized}(ag, ob.\text{Info}) \Rightarrow \neg \text{Knows}_{ag} (ob.\text{info})$

$\text{Knows}_{ag} (v) \equiv \exists x: \text{Knows}_{ag} (x = v)$

$\text{Knows}_{ag} (P) \equiv \text{Belief}_{ag} (P) \wedge P$

↑

"P is in ag's memory"

## ◆ Other patterns for privacy, availability, integrity, authentication, non-repudiation, ...

# Application-specific instantiation of security goal patterns

Goal Avoid [SensitiveInfoKnownByUnauthorizedAgent]

$\forall ag: \text{Agent}, ob: \text{Object}$

$\neg \text{Authorized}(ag, ob.\text{Info}) \Rightarrow \neg \text{Knows}_{ag}(ob.\text{info})$

↓ **Web banking services**

Object / Account [# , PIN]

Authorized (ag, acc)  $\equiv$

Owner (ag, acc)  $\vee$  Proxy (ag, acc)  $\vee$  Manager (ag, acc)

↓

Goal Avoid [PaymentMediumKnownBy3rdParty]

$\forall p: \text{Person}, acc: \text{Account}$

$\neg [ \text{Owner}(p, acc) \vee \text{Proxy}(p, acc) \vee \text{Manager}(p, acc) ]$

$\Rightarrow \neg [ \text{Knows}_{p}(acc.\text{Acc\#}) \wedge \text{Knows}_{p}(acc.\text{PIN}) ]$

# Application-specific instantiation of security goal patterns

Goal Avoid [SensitiveInfoKnownByUnauthorizedAgent]

$\forall ag: \text{Agent}, ob: \text{Object}$

$\neg \text{Authorized}(ag, ob.\text{Info}) \Rightarrow \neg \text{Knows}_{ag}(ob.\text{info})$

↓ **Web banking services**

Object / Account [# , PIN]      *sensitive info in object model*

Authorized (ag, acc)  $\equiv$

Owner (ag, acc)  $\vee$  Proxy (ag, acc)  $\vee$  Manager (ag, acc)

↓

Goal Avoid [PaymentMediumKnownBy3rdParty]

$\forall p: \text{Person}, acc: \text{Account}$

$\neg [ \text{Owner}(p, acc) \vee \text{Proxy}(p, acc) \vee \text{Manager}(p, acc) ]$

$\Rightarrow \neg [ \text{Knows}_{p}(acc.\text{Acc\#}) \wedge \text{Knows}_{p}(acc.\text{PIN}) ]$

# Application-specific instantiation of security goal patterns

Goal Avoid [SensitiveInfoKnownByUnauthorizedAgent]

$\forall ag: \text{Agent}, ob: \text{Object}$

$\neg \text{Authorized}(ag, ob.\text{Info}) \Rightarrow \neg \text{Knows}_{ag}(ob.\text{info})$

↓ **Web banking services**

Object / Account [# , PIN]      *sensitive info in object model*

Authorized (ag, acc)  $\equiv$

Owner (ag, acc)  $\vee$  Proxy (ag, acc)  $\vee$  Manager (ag, acc)

↓

Goal Avoid [PaymentMediumKnownBy3rdParty]

$\forall p: \text{Person}, acc: \text{Account}$

$\neg [ \text{Owner}(p, acc) \vee \text{Proxy}(p, acc) \vee \text{Manager}(p, acc) ]$

$\Rightarrow \neg [ \text{Knows}_{p}(acc.\text{Acc\#}) \wedge \text{Knows}_{p}(acc.\text{PIN}) ]$

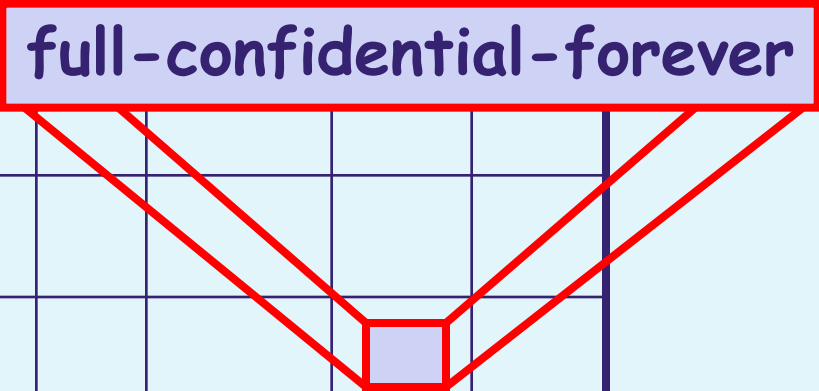


# Further patterns for confidentiality goals

- ◆ Two dimensions of confidentiality:
  - Degree of approximate knowledge to be kept confidential
  - Timing along which knowledge should be kept confidential
- ◆ Pattern catalogue
  - Provides standard specification patterns
  - Hides complicate formulas

# Specification patterns for confidentiality goals

Timing Of Knowledge	degree of knowledge					
	val	lb	ub	betw	full	Val
Now						
upTo						
Unless						
Until						
forever						



full-confidential-forever

Zooming on some patterns...

# Specification patterns: a sample

## Fully confidential value

$$\begin{aligned} \text{Full-Confidential}_{ag}(x) &\equiv \\ &\forall v \in \text{ran}(x): \neg \text{Knows}_{ag}(x \neq v) \end{aligned}$$


## Confidential forever

$$\begin{aligned} \text{Y-Confidential-forever}_{ag}(x) &\equiv \\ &\forall w: x = w \rightarrow \square \text{Y-Confidential}_{ag}(x) \\ &\text{with } Y \in \{\text{val}, \text{lb}, \text{ub}, \text{betw}, \text{full}\} \end{aligned}$$

## Specification by pattern instantiation:

$$\begin{aligned} &\forall ep: ePurse, ag: Agent \\ &\quad \neg \text{Owns}(ag, ep) \wedge ag \neq ep \\ &\quad \Rightarrow \text{full-Confidential-forever}_{ag}(ep.\text{balance}) \end{aligned}$$

# Course outline

- ◆ Goal-oriented RE for high-assurance applications
  - Modeling goals, objects, agents, operations, behaviors
  - A goal-oriented model building method in action
  - Checking goal refinements
  - Obstacle analysis for high-assurance applications
- ◆ Engineering security requirements
  - Security goals and their specification
  -  Threat analysis for model consolidation
  - Analyzing conflicts among security goals
  - Model checking against confidentiality requirements

# Threat analysis: unintentional vs. intentional threats

- ◆ Unintentional threat: inadvertent violation of security goal
  - Handled by obstacle analysis on security leaf goals
  - E.g. accidental disclosure of confidential information
- ◆ Intentional threat: proactive violation of security goal by exploitation of unprotected data & system knowledge acquired through malicious behaviors, calculations, deductive inference, etc.
  - Handled by obstacle analysis augmented with malicious agents, their anti-goals, and their capabilities
  - E.g. E-shopping: Achieve[ItemReceived**AndNotPaid**]

# Intentional threats require an *anti-model*

- ◆ The scope of the environment is extended to include malicious agents (“attackers”)
  - human insiders or outsiders of the original system, tools, fake devices, ...
- ◆ **Anti-goal** = malicious obstacle to satisfy attacker's objectives (and break security goals)
- ◆ **Anti-model** = model linking anti-goals against a goal model

## Intentional threats require an *anti-model* (2)

- ◆ An anti-model is a dual model ...
  - the software is now part of the attacker's environment
  - domain properties include software vulnerabilities
- ◆ Threat graph = refinement graph showing a plan ...
  - to achieve some anti-goal
  - in view of the attacker's capabilities

# Analyzing intentional threats: attacker's capabilities

## ◆ Capabilities = two sets of conditions:

- conditions that are monitorable by the attacker
- conditions that are controllable by the attacker

e.g. e-shopping: ItemPaidByCustomer,

PaymentNotificationReceivedBySeller

## ◆ Most Knowledgeable Attacker (MKA):

- Knows the goal model, the domain properties used in it, and the operation model

Trivially satisfied as attacker at RE time is the modeller looking for missing countermeasures

*Worst-case* threat analysis is desirable for complete exploration of security countermeasures



# Threat analysis for intentional threats

- ◆ Build threat graphs from anti-goals:
  - Get initial anti-goals to be refined/abstracted --e.g., from negations of application-specific security goal
  - Identify attackers wishing them, their capabilities
  - Build anti-goal refinement/abstraction graphs until reaching conditions that are realizable by the attackers (monitorable or controllable)
- ◆ Derive new security goals as countermeasures to counter the leaf anti-goals in threat graphs

## Step 1: Get initial anti-goals

- ◆ *Negate* security goal instantiation to application-specific “sensitive” objects ...

Goal Avoid [PaymentMediumKnownBy3rdParty]

$\forall p: \text{Person}, acc: \text{Account}$

$\neg \text{Authorized}(p, acc)$

$\Rightarrow \neg [ \text{Knows}_{V_p}(acc.Acc\#) \wedge \text{Knows}_{V_p}(acc.PIN) ]$

↓ **goal negation**

Anti-Goal Achieve [PaymentMediumKnownBy3rdParty]

$\diamond \exists p: \text{Person}, acc: \text{Account}$

$\neg \text{Authorized}(ag, acc)$

$\wedge \text{Knows}_{V_p}(acc.Acc\#) \wedge \text{Knows}_{V_p}(acc.PIN)$

## Step 1: Get initial anti-goals

- ◆ *Negate* security goal instantiation to application-specific “sensitive” objects ...

Goal Avoid [PaymentMediumKnownBy3rdParty]

$\forall p: \text{Person}, acc: \text{Account}$

$\neg \text{Authorized}(p, acc)$

$\Rightarrow \neg [ \text{Knows}_{V_p} (acc.\text{Acc\#}) \wedge \text{Knows}_{V_p} (acc.\text{PIN}) ]$

↓ **goal negation**

Anti-Goal Achieve [PaymentMediumKnownBy3rdParty]

$\diamond \exists p: \text{Person}, acc: \text{Account}$

$\neg \text{Authorized}(p, acc)$

$\wedge \text{Knows}_{V_p} (acc.\text{Acc\#}) \wedge \text{Knows}_{V_p} (acc.\text{PIN})$



## Step 2: Identify attackers wishing anti-goals

- ◆ For each initial anti-goal:
  - ask WHO might benefit from it
  - use of attacker taxonomies

Anti-Goal Achieve[PaymentMediumKnownBy3rdParty]



Insiders: Bank QA team  
Organization-specific agents

Outsiders: Thieves  
Hackers  
Terrorists, ...



## Step 3: Build threat graph

- ◆ For each (initial anti-goal, attacker): build anti-goal refinement/abstraction graph ...
  - Informally: by use of refinement patterns or by WHY/HOW questions
    - WHY  $\Rightarrow$  parent anti-goals
    - HOW  $\Rightarrow$  child anti-goals

Formally: by regression through ...

... domain properties  $P \Rightarrow AG$

$\Rightarrow$  anti-goal preconditions satisfiable *in domain*

... goal specs from attacked model

$\Rightarrow$  preconditions satisfiable *by attacked software*



## Step 3: Build threat graph

- ◆ For each (initial anti-goal, attacker): build anti-goal refinement/abstraction graph ...
  - Informally: by use of refinement patterns or by WHY/HOW questions
    - WHY  $\Rightarrow$  parent anti-goals
    - HOW  $\Rightarrow$  child anti-goals
  - Formally: by regression through ...
    - ... domain properties  $P \Rightarrow AG$ 
      - $\Rightarrow$  anti-goal preconditions satisfiable *in domain*
    - ... goal specs from attacked model
      - $\Rightarrow$  preconditions satisfiable *by attacked software*

# Anti-goal refinement by regression through domain

Anti-Goal Achieve [PaymentMediumKnownBy3rdParty]

◇ ∃ p: Person, acc: Account

¬ Authorized (p, acc) ∧ KnowsV<sub>p</sub>(Acc#) ∧ KnowsV<sub>p</sub>(PIN)

↓ *domain property as sufficient condition ?*

∀ p: Person, acc: Account

¬ Authorized (ag, acc) ∧ KnowsV<sub>p</sub>(acc.PIN)

∧ (∃ x: Acc#) (Found (p, x) ∧ Matching (acc.PIN, x))

⇒ KnowsV<sub>p</sub>(acc.Acc#) ∧ KnowsV<sub>p</sub>(acc.PIN)

↓ *anti-subgoal:*

◇ ∃ p: Person, acc: Account

¬ Authorized (ag, acc) ∧ KnowsV<sub>p</sub>(acc.PIN)

∧ (∃ x: Acc#) (Found (p, x) ∧ Matching (acc.PIN, x))

# Anti-goal refinement by regression through domain

Anti-Goal Achieve [PaymentMediumKnownBy3rdParty]

$\diamond \exists p: \text{Person}, \text{acc}: \text{Account}$

$\neg \text{Authorized}(p, \text{acc}) \wedge \text{KnowsV}_p(\text{Acc}\#) \wedge \text{KnowsV}_p(\text{PIN})$

$\downarrow$  *dom prop as sufficient condition?*

$\forall p: \text{Person}, \text{acc}: \text{Account}$

$\neg \text{Authorized}(p, \text{acc}) \wedge \text{KnowsV}_p(\text{acc.PIN})$

$\wedge (\exists x: \text{Acc}\#) (\text{Found}(p, x) \wedge \text{Matching}(\text{acc.PIN}, x))$

$\Rightarrow \text{KnowsV}_p(\text{acc.Acc}\#) \wedge \text{KnowsV}_p(\text{acc.PIN})$

$\downarrow$  *anti-subgoal:*

$\diamond \exists p: \text{Person}, \text{acc}: \text{Account}$

$\neg \text{Authorized}(ag, \text{acc}) \wedge \text{KnowsV}_p(\text{acc.PIN})$

$\wedge (\exists x: \text{Acc}\#) (\text{Found}(p, x) \wedge \text{Matching}(\text{acc.PIN}, x))$



# Anti-goal refinement by regression through domain

Anti-Goal Achieve [PaymentMediumKnownBy3rdParty]

◇ ∃ p: Person, acc: Account

¬ Authorized (ag, acc) ∧ KnowsV<sub>p</sub> (Acc#) ∧ KnowsV<sub>p</sub> (PIN)

↓ *dom prop as sufficient condition ?*

∀ p: Person, acc: Account

¬ Authorized (ag, acc) ∧ KnowsV<sub>p</sub> (acc.PIN)

∧ (∃ x: Acc#) (Found (p, x) ∧ Matching (acc.PIN, x))

⇒ KnowsV<sub>p</sub> (acc.Acc#) ∧ KnowsV<sub>p</sub> (acc.PIN)

↓ *anti-subgoal:*

◇ ∃ p: Person, acc: Account

¬ Authorized (p, acc) ∧ KnowsV<sub>p</sub> (acc.PIN)

∧ (∃ x: Acc#) (Found (p, x) ∧ Matching (acc.PIN, x))



## Build threat graph: refine until ...

- ◆ ... terminal conditions are reached ...
  - anti-requirements  
*realizable* in terms of attacker's capabilities
  - vulnerabilities of attackee  
properties of anti-domain

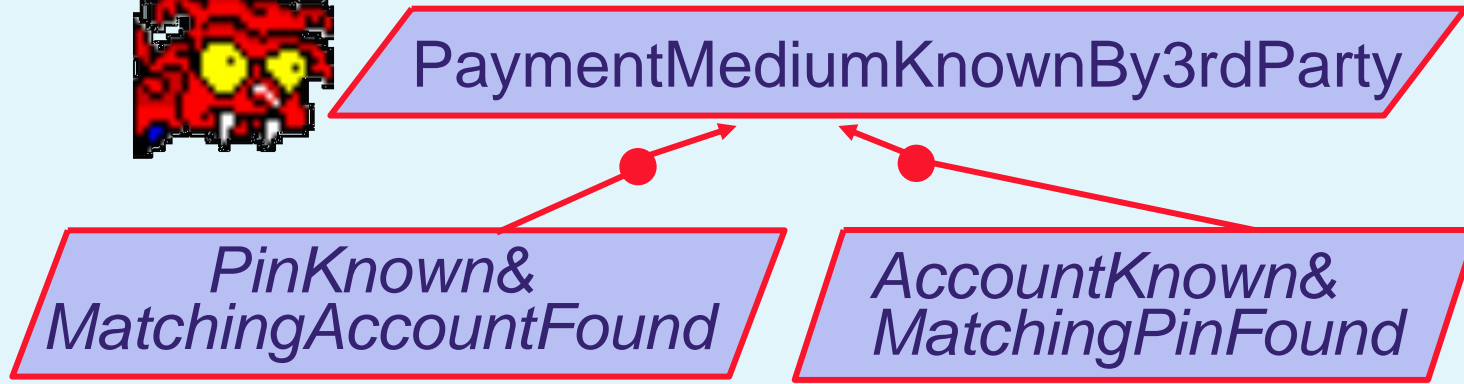
# Refinement towards realizability by attacker: a known attack



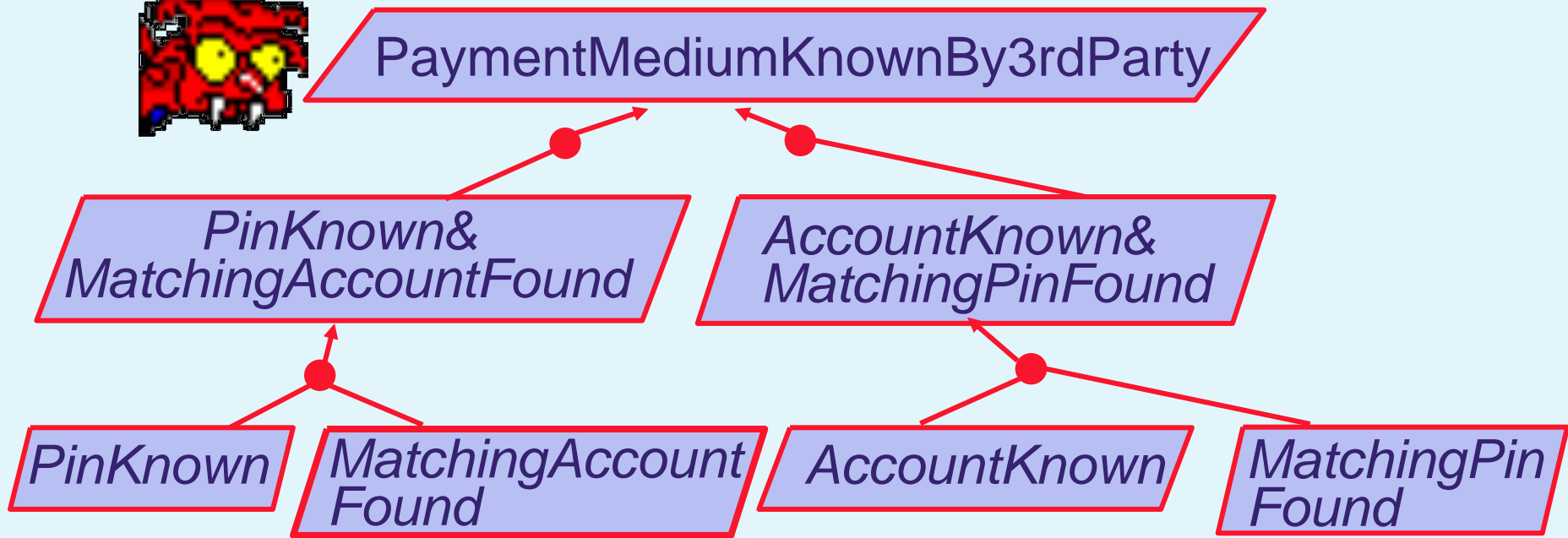
PaymentMediumKnownBy3rdParty

*PinKnown&  
MatchingAccountFound*

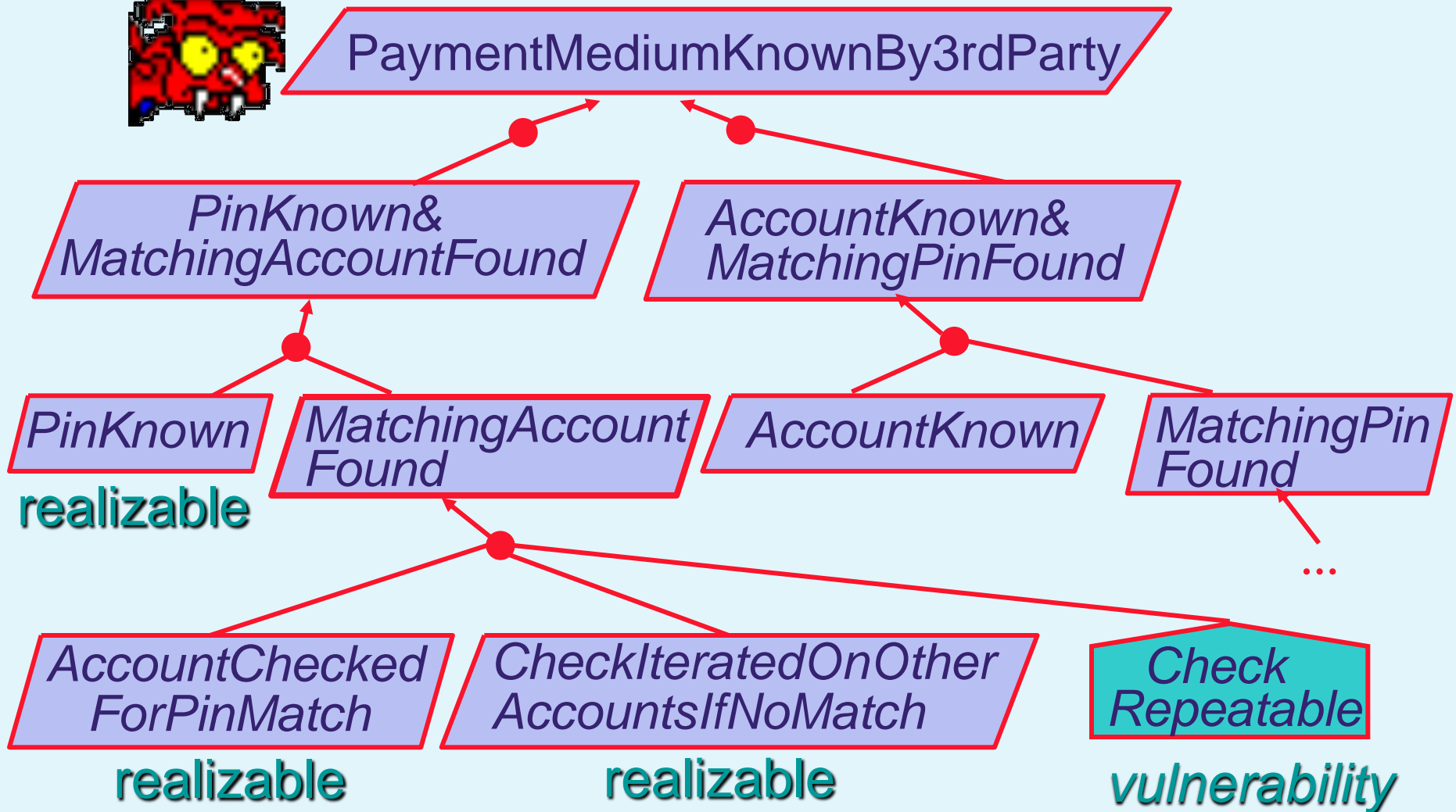
*AccountKnown&  
MatchingPinFound*



# Refinement towards realizability by attacker: a known attack



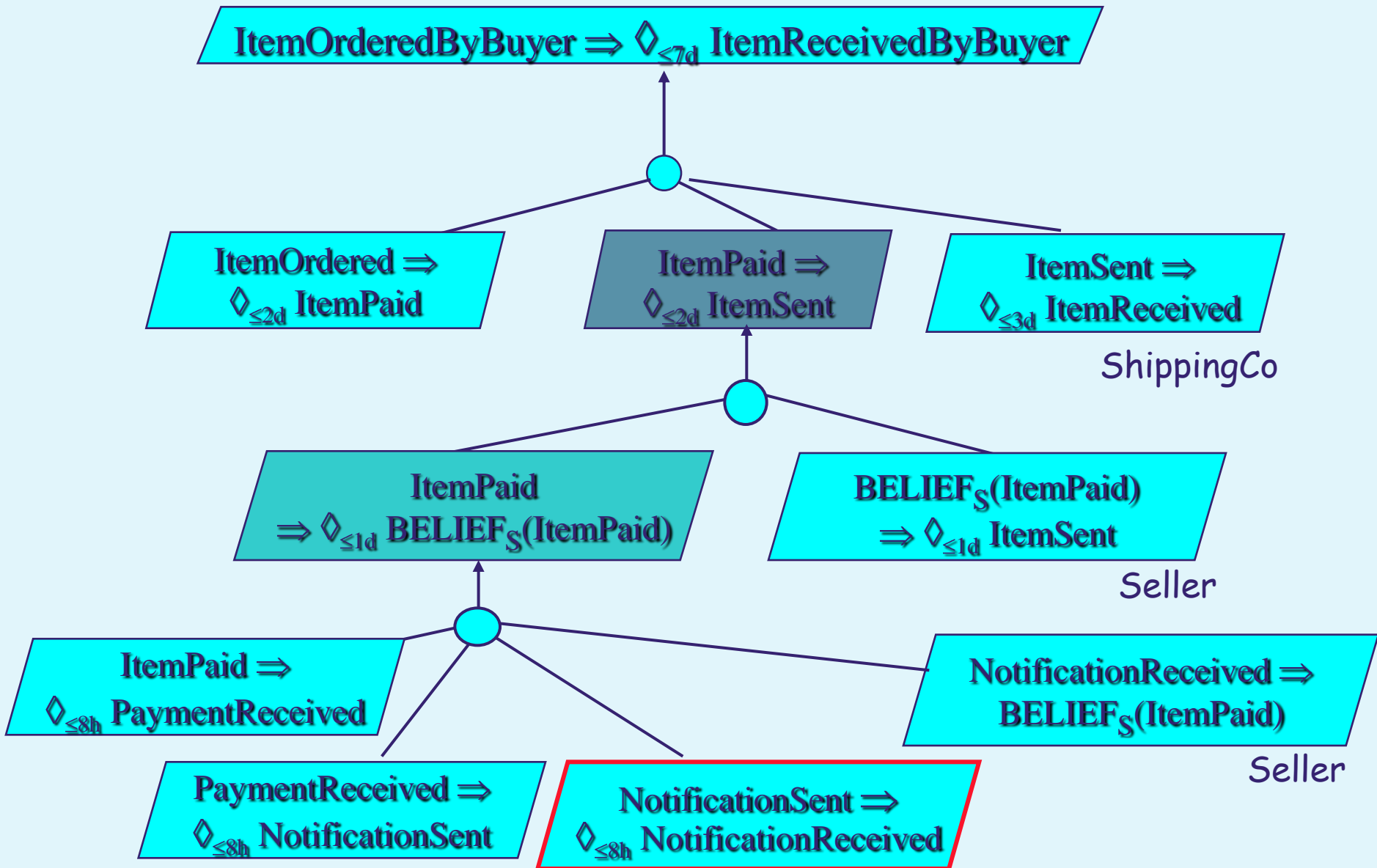
# Refinement towards realizability by attacker: a known attack



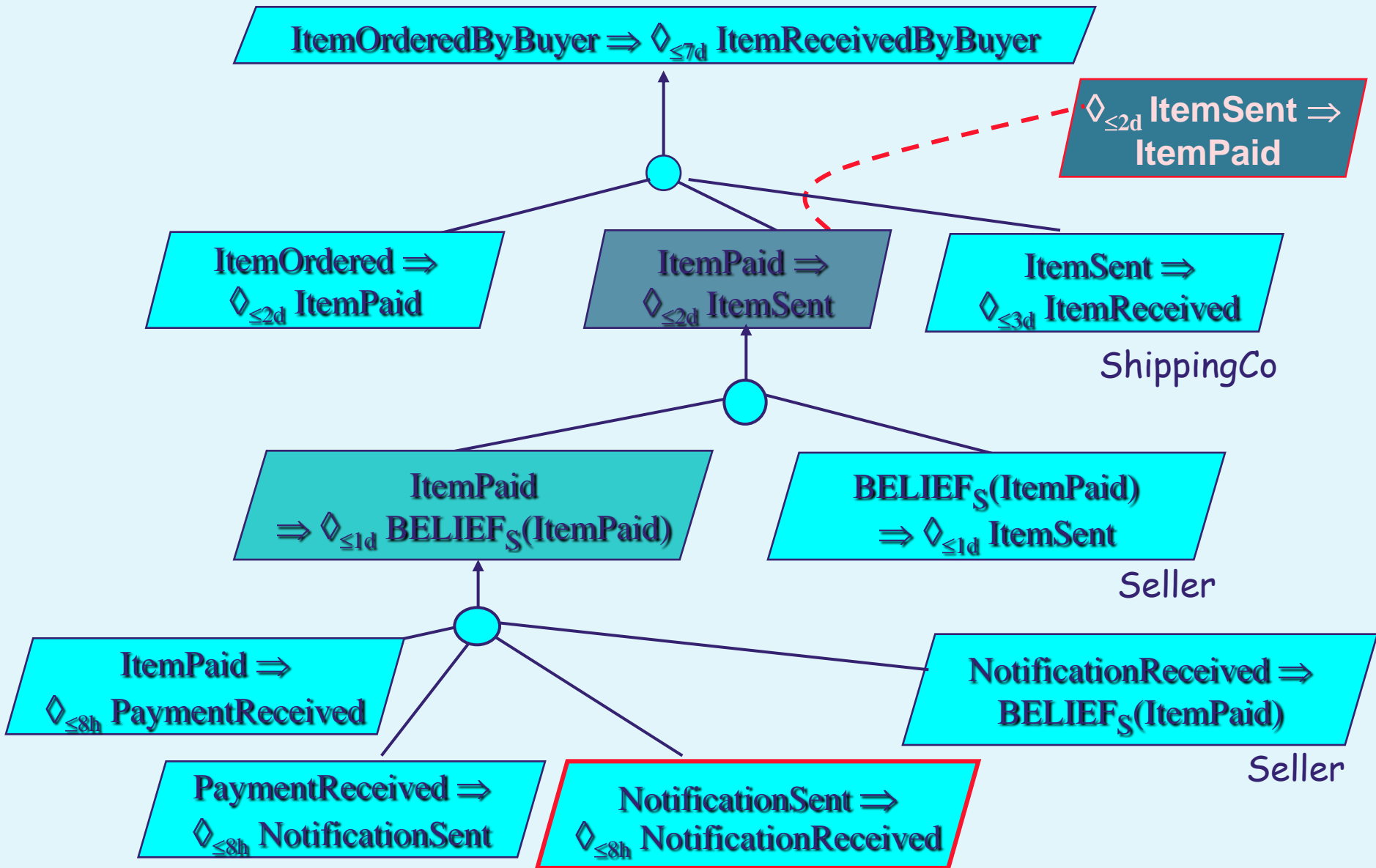
# Deriving countermeasures

- ◆ New security goals obtained by application of resolution operators, e.g.
  - *Avoid* [anti-goal]:
    - Avoid [AccountCheckRepeatableFromPin]
    - Avoid [PinCheckRepeatableFromAccount]
  - Make vulnerability condition *unmonitorable* by attacker
  - Make anti-requirement *uncontrollable* by attacker
- ◆ To be further refined along alternative OR-branches in the updated goal model

# Online shopping: functional goals

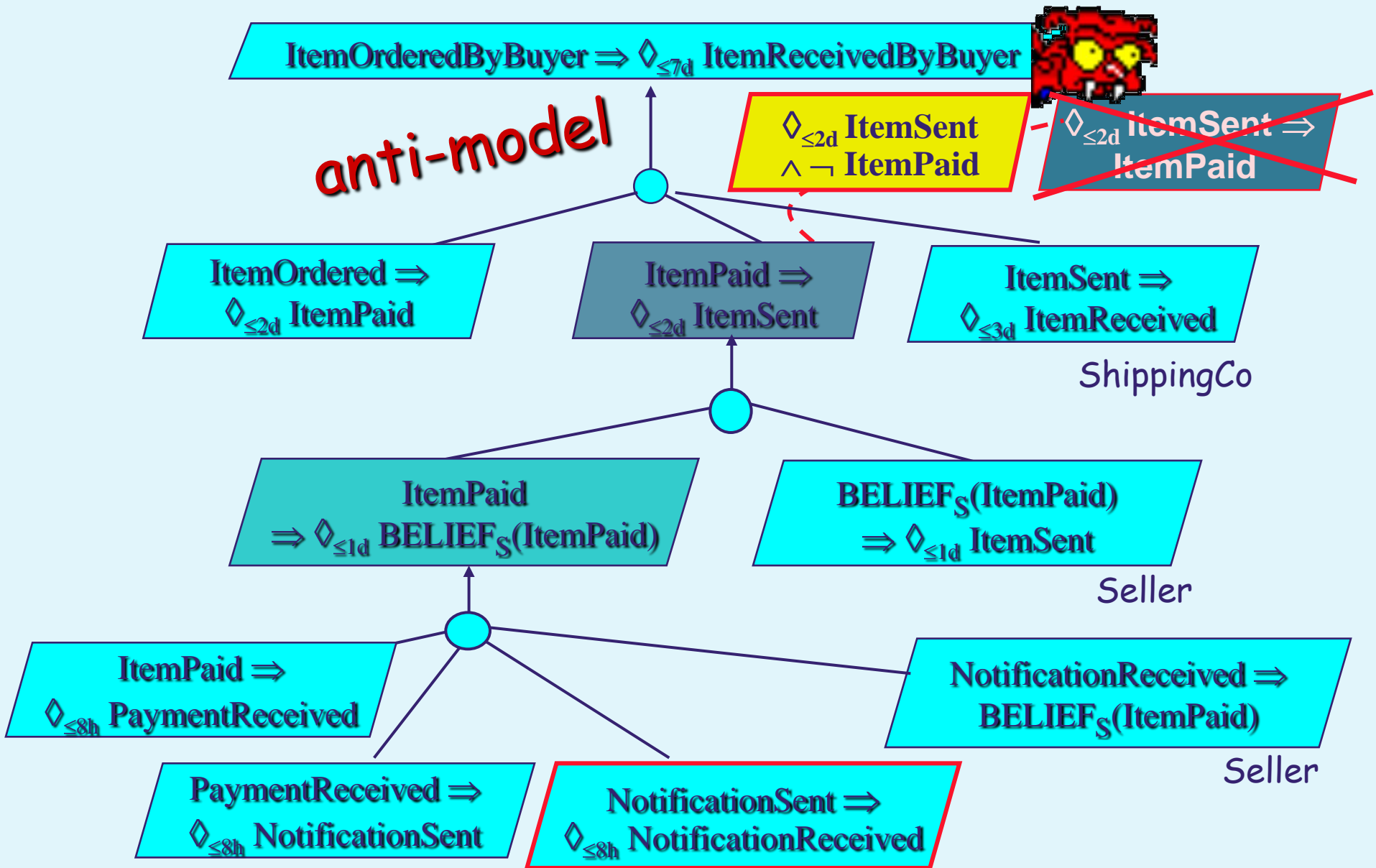


# Online shopping: a security goal

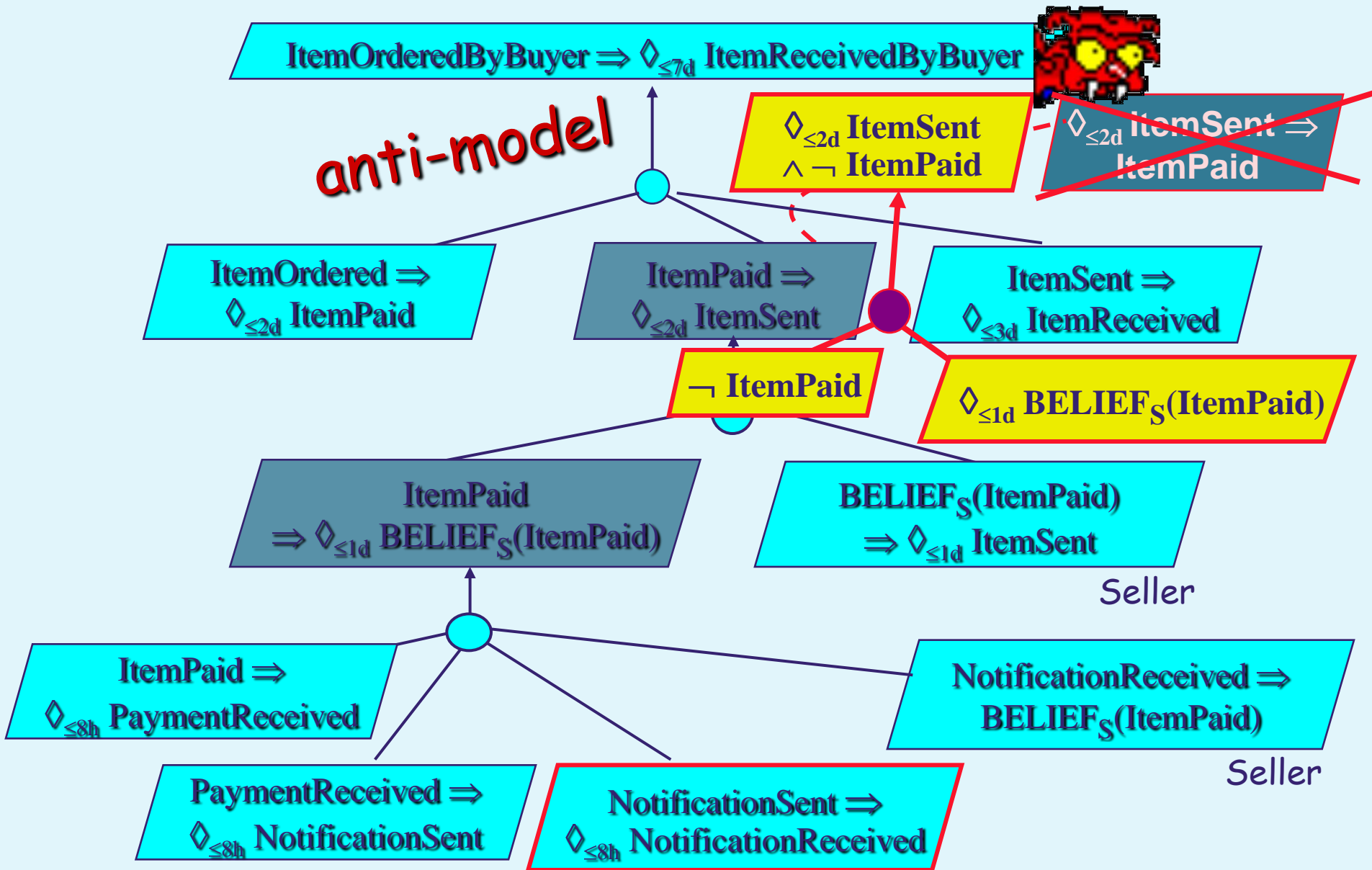




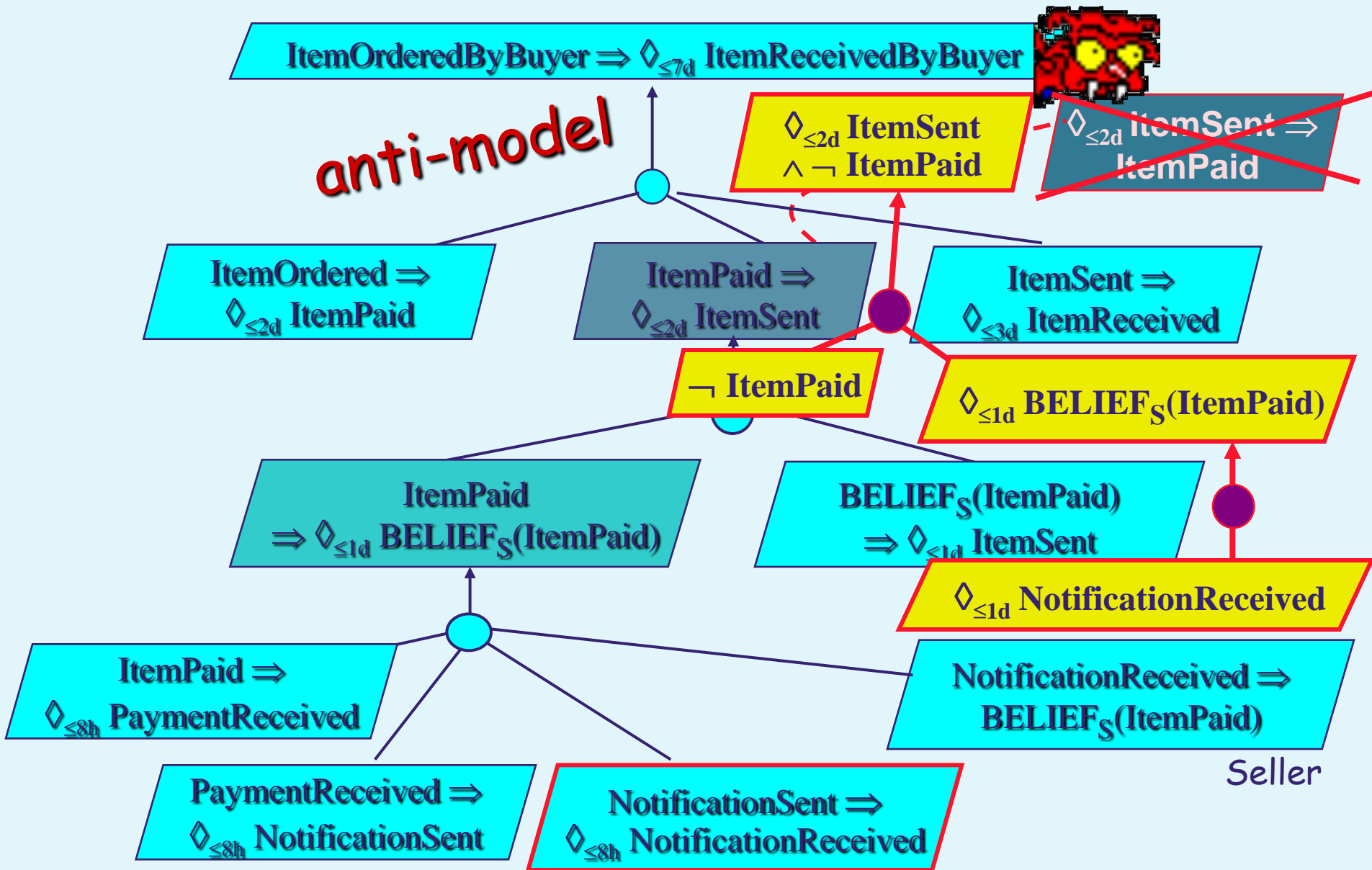
# Online shopping: anti-goal



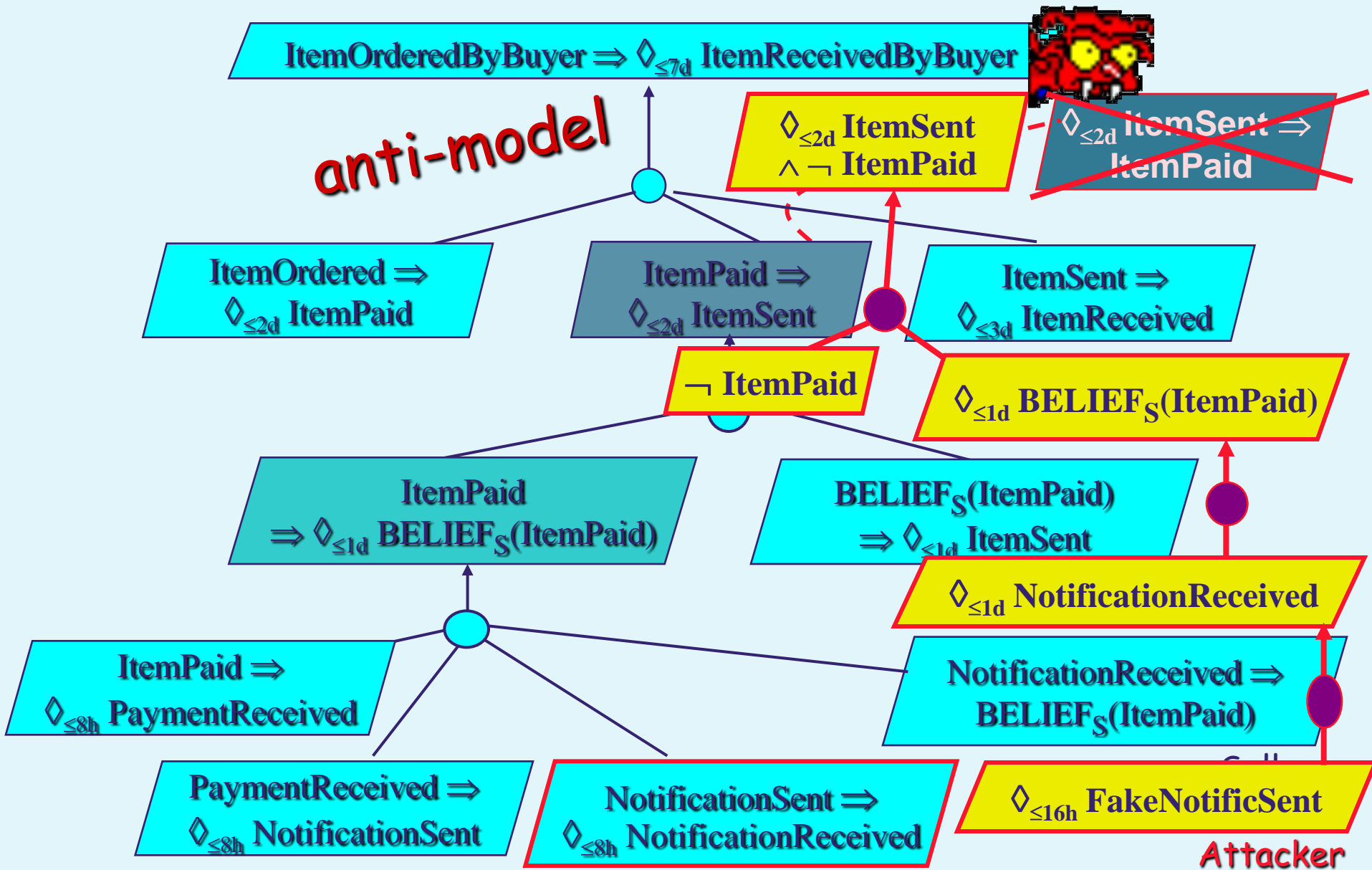
# Online shopping: anti-goal model



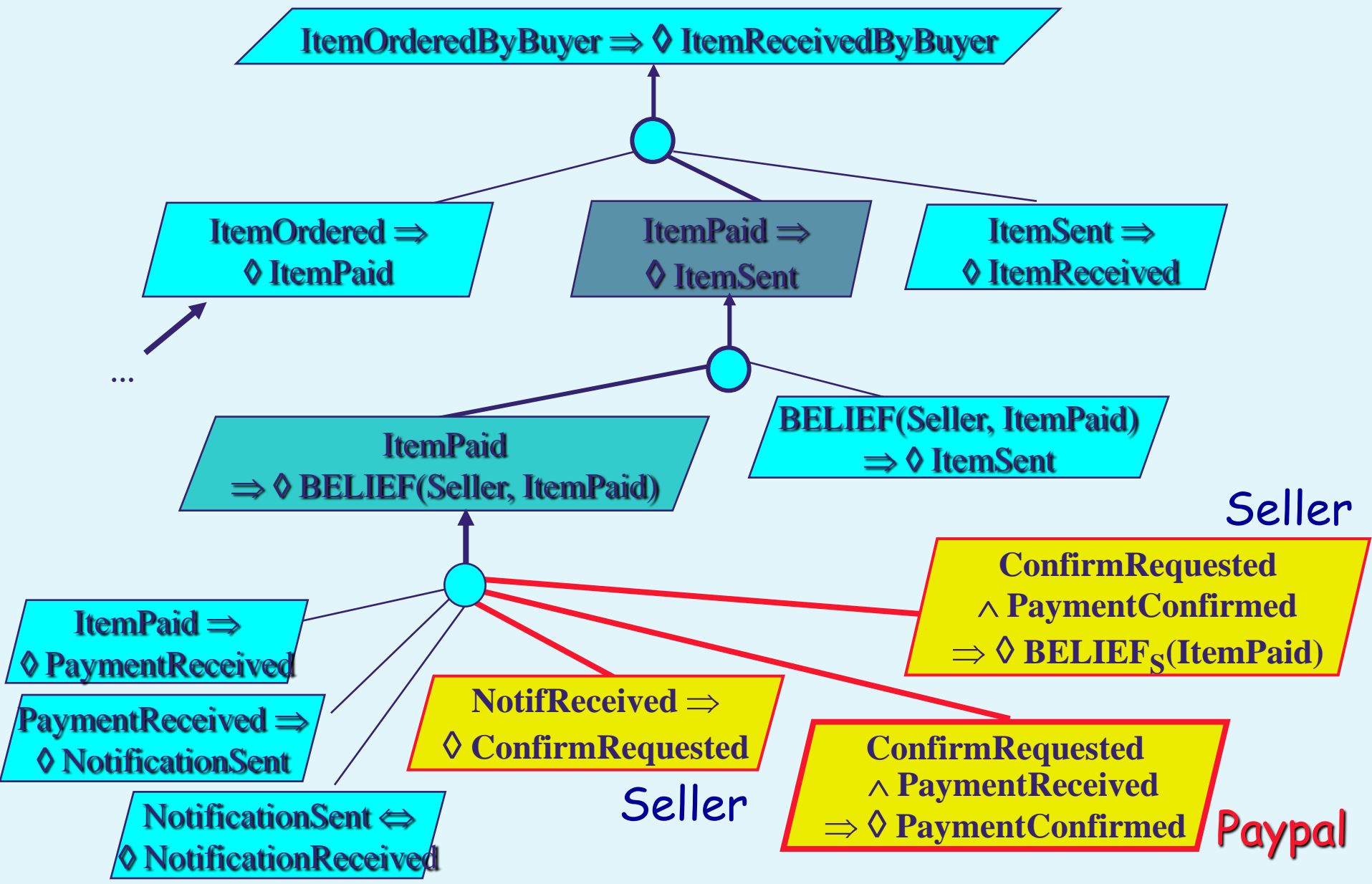
# Online shopping: anti-goal model



# Online shopping: anti-goal model



# Online shopping: goal model with countermeasures





# Application:

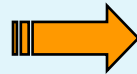
## Security of Aircraft in the Future European Environment



Threats against crew & passengers



(External threats)



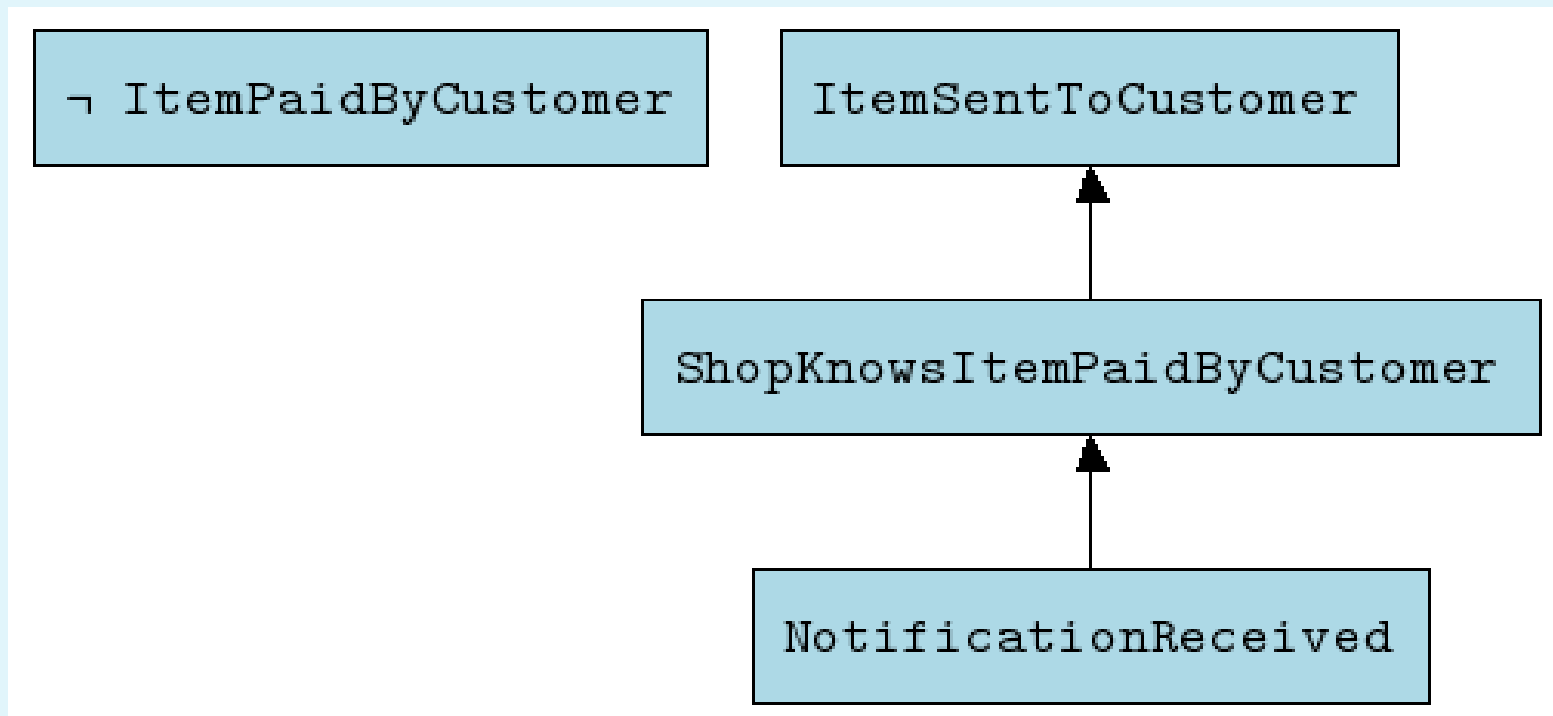
Threats from baggage area

- Modeling terrorist threats (anti-goal model)
- RE for on-board threat *detection & reaction system*

# Automated synthesis of threat graphs

- ◆ Builds a proof showing realizability of anti-goal in view of attacker's capabilities & knowledge of environment
- ◆ Capabilities = Boolean state variables (atomic conditions that are monitorable/controllable)
- ◆ Based on BDD representation of anti-goal
- ◆ Weakens powerful macro-agent by removal of capabilities, following BDD state-variable ordering

# Synthesizing attack graphs (plan generation)



Attacker anti-goal:

→  $\neg \text{ItemPaidByCustomer} \wedge \text{ItemSentToCustomer}$


Attacker capabilities:

Controls  $\text{ItemPaidByCustomer}$ ,  $\text{NotificationReceived}$

Monitors --



# Course outline

- ◆ Goal-oriented RE for high-assurance applications
  - Modeling goals, objects, agents, operations, behaviors
  - A goal-oriented model building method in action
  - Checking goal refinements
  - Obstacle analysis for high-assurance applications
- ◆ Engineering security requirements
  - Security goals and their specification
  - Threat analysis for model consolidation
  -  Analyzing conflicts among security goals
  - Model checking against confidentiality requirements

# Conflict analysis

- ◆ Divergence is most frequent case of conflicting goals, requirements or assumptions:

*potential* logical inconsistency

- ◆ Goals  $G_1, \dots, G_n$  are divergent *iff*

there exists a *boundary condition*  $B$  :

$\{B, \wedge_i G_i, \text{Dom}\} \models \text{false}$

*inconsistency*

$\{B, \wedge_{i \neq i} G_j, \text{Dom}\} \not\models \text{false}$

*minimality*

exists system behavior  $S$  s.t.  $S \models B$

*feasibility*

# Divergence frequently involves security goals

Maintain[ReviewerAnonymity]:

$\text{Reviews}(r, \text{pap}, \text{rep}) \wedge \text{AuthorOf}(a, \text{pap})$

$\Rightarrow \Box \neg \text{Knows}(a, \text{Reviews}(r, \text{pap}, \text{rep}))$

Achieve[ReviewIntegrity]:

$\text{Reviews}(r, \text{pap}, \text{rep}) \wedge \text{AuthorOf}(a, \text{pap})$

$\Rightarrow \Diamond \text{Gets}(a, \text{rep}', \text{pap}, r) \wedge \text{rep}' = \text{rep}$

Boundary condition:  $\Diamond \exists r, \text{pap}, a, \text{rep}, \text{rep}'$

$\text{Reviews}(r, \text{pap}, \text{rep}) \wedge \text{AuthorOf}(a, \text{pap})$

$\wedge \Diamond \text{Gets}(a, \text{rep}', \text{pap}, r) \wedge \text{rep}' = \text{rep}$

$\wedge \text{French}(r) \wedge \neg \exists r' \neq r: \text{Expert}(r') \wedge \text{French}(r')$

# Divergence frequently involves security goals

Maintain[ReviewerAnonymity]:

$\text{Reviews}(r, \text{pap}, \text{rep}) \wedge \text{AuthorOf}(a, \text{pap})$   
 $\Rightarrow \Box \neg \text{Knows}(a, \text{Reviews}[r, \text{pap}, \text{rep}])$

Achieve[ReviewIntegrity]:

$\text{Reviews}(r, \text{pap}, \text{rep}) \wedge \text{AuthorOf}(a, \text{pap})$   
 $\Rightarrow \Diamond \text{Gets}(a, \text{rep}', \text{pap}, r) \wedge \text{rep}' = \text{rep}$

Boundary condition:  $\Diamond \exists r, \text{pap}, a, \text{rep}, \text{rep}'$

$\text{Reviews}(r, \text{pap}, \text{rep}) \wedge \text{AuthorOf}(a, \text{pap})$   
 $\wedge \Diamond \text{Gets}(a, \text{rep}', \text{pap}, r) \wedge \text{rep}' = \text{rep}$   
 $\wedge \text{French}(r) \wedge \neg \exists r' \neq r: \text{Expert}(r') \wedge \text{French}(r')$

## Conflict analysis (2)

### ◆ Detecting divergence:

- by regression: derive  $B$  as precondition for  $\neg G_i$  from  $\{\bigwedge_{i \neq j} G_j, \text{Dom}\}$
- by use of formal conflict patterns

### ◆ Resolving divergence: resolution operators

- avoid boundary condition:  $\square \neg B$
- restore divergent goals:  $B \Rightarrow \diamond \bigwedge_i G_i$
- anticipate conflict:  $P \Rightarrow \diamond_{\leq T} \neg P$
- weaken goals, specialize objects, etc.

# Deriving boundary condition for conflict

By regression:

$AtStation \wedge \circ \neg AtStation \Rightarrow DoorsClosed \ W \ AtNext$

- $( Stopped \wedge Alarm ) \Rightarrow DoorsOpen$

# Deriving boundary condition for conflict

By regression:

$AtStation \wedge o \neg AtStation \Rightarrow DoorsClosed \ W \ AtNext$

•  $( Stopped \wedge Alarm ) \Rightarrow DoorsOpen$

→ negate G1:

$AtStation \wedge o \neg AtStation \wedge$

$\neg AtNext \ U \ ( DoorsOpen \wedge \neg AtNext )$

# Deriving boundary condition for conflict

By regression:

$AtStation \wedge o \neg AtStation \Rightarrow DoorsClosed \ W \ AtNext$

•  $( Stopped \wedge Alarm ) \Rightarrow DoorsOpen$

→ negate G1:

$AtStation \wedge o \neg AtStation \wedge$   
 $\neg AtNext \ U \ ( DoorsOpen \wedge \neg AtNext )$

→ regress  $\neg G1$  through G2:

$AtStation \wedge o \neg AtStation$   
 $\wedge \neg AtNext \ U \ ( \bullet Stopped \wedge \bullet Alarm \wedge \neg AtNext )$

*boundary condition for conflict*



# Course outline

- ◆ Goal-oriented RE for high-assurance applications
  - Modeling goals, objects, agents, operations, behaviors
  - A goal-oriented model building method in action
  - Checking goal refinements
  - Obstacle analysis for high-assurance applications
- ◆ Engineering security requirements
  - Security goals and their specification
  - Threat analysis for model consolidation
  - Analyzing conflicts among security goals
  - Model checking against confidentiality requirements



# CONCHITA: checking requirements models against confidentiality claims

## ◆ Given ...

- an object model (entities, associations, agents)
  - a list of requirements
  - assumed confidentiality requirements
  - claimed confidentiality requirements
- } specified with patterns

## ◆ Find a finite trace ...

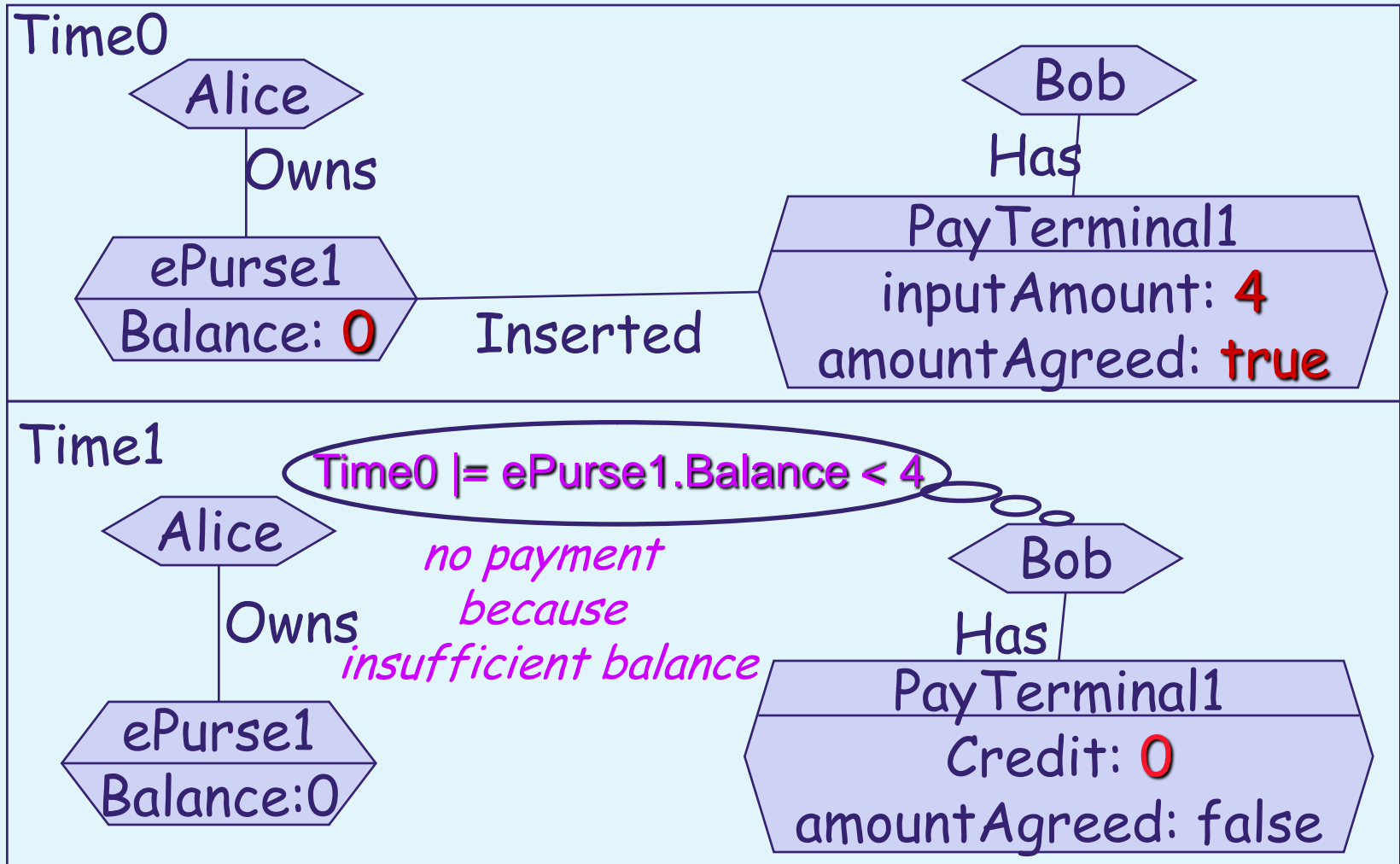
- satisfying the requirements
- where an agent instance can acquire knowledge that violates one of the confidentiality claims

## + Explain how the agent acquired this knowledge

### Implementation:

Bounded Model Checking, Finite instantiation,  
CSP solver (efficient arithmetic and search space pruning)

# Running CONCHITA on e-Purse system: trace leading to information disclosure



+ explanation = knowledge fragments used in the deduction

# Example of axioms about unauthorized agent (UA)

**Maximal Input** *at any time, UA knows the value of every non confidential variable*

**Ex:** seller knows the amount that is entered in the terminal

# Example of axioms about unauthorized agent (UA)

**Maximal Input** *at any time, UA knows the value of every non confidential variable*

**Perfect System knowledge** *UA knows all the requirements the software implements and all the properties of the domain.*

**Ex:** the seller knows that payment is denied in case of insufficient balance.

# Example of axioms about unauthorized agent (UA)

**Maximal Input** *at any time, UA know the value of every non confidential variable*

**Perfect System knowledge** *UAs know all the requirements the software implements and all the properties of the domain.*

**Perfect Recall** *UAs always remember facts and properties they used to know in the past.*

**Ex:** at time1, the seller remembers the entered amount, the insertion of the e-Purse, ...

# Conclusion

- ◆ Rich models are essential for HA applications
  - multiple dimensions: intentional, structural, responsibility, operational, behavioral
  - software + environment (e.g., humans, devices, other software, mother Nature, attacker, attackee)
    - start thinking about high assurance at RE time*
  - alternative refinements, assignments, resolutions
  - seamless transition from high-level concerns to operational requirements

## Conclusion (2)

- ◆ The building of such models is hard & critical; should therefore be guided by methods...
  - systematic
  - top-down + bottom-up
  - incremental
  - supporting the analysis of partial models



## Conclusion (3)

- ◆ **Goal-based** reasoning is central for...
  - model building & elaboration of requirements
  - exploration & evaluation of alternatives
  - conflict management
  - anticipation of hazards and threats  
(requirements-level exception handling)

## Conclusion (4)

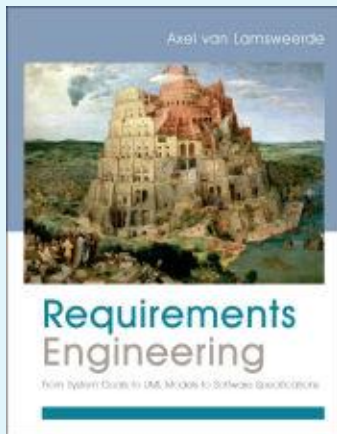
- ◆ Goal completeness can be achieved through multiple means ...
  - refinement checking => missing subgoals, subobstacles, threats/vulnerabilities
  - obstacle/threat analysis => countermeasure goals
  - animation (not discussed here)

## Conclusion (5)

- ◆ Be pessimistic from beginning about software *and environment*
  - hazards, threats, conflicts
- ◆ Benefits of multi-button framework
  - semi-formal ...
    - for modeling, navigation, traceability
  - formal, when and where needed ...
    - for precise, incremental reasoning on model pieces

## Thanks ...

- ◆ To the KAOS crew at *UCL, CETIC & RESPECT-IT* as *researchers, consultants, or tool developers*  
C. Damas, A. Dardenne, R. Darimont,  
R. De Landtsheer, E. Delor, B. Lambeau, E. Letier,  
P. Massonet, C. Ponsard, A. Rifaut, H. Tran Van
- ◆ To Steve Fickas and his group at Univ. Oregon
- ◆ To the EU & Region of Wallonia for significant funding of those efforts



## More information available ...

- ◆ ... on the method & associated techniques in:

*A. van Lamsweerde, Requirements Engineering - From System Goals to UML Models to Software Specifications. Wiley, 2008.*

[www.info.ucl.ac.be/~avl](http://www.info.ucl.ac.be/~avl)

- ◆ ... on tools at:

<http://www.objectiver.com>

<http://faust.cetic.be>

# Relevant papers

- A. van Lamsweerde, "Requirements Engineering in the Year 00: A Research Perspective". *Keynote Paper, Proc. ICSE'2000 - Intl Conf on Software Engineering*, June 2000, IEEE CS Press, pp. 5-19.
- R. Darimont & A. van Lamsweerde, "Formal Refinement Patterns for Goal-Driven Requirements Elaboration". *Proc. FSE-4 - Fourth ACM Conf on Foundations of Software Engineering*, San Francisco, Oct. 1996, 179-190.
- E. Letier & A. van Lamsweerde, "Agent-Based Tactics for Goal-Oriented Requirements Elaboration", *Proc. ICSE'2002 - 24th Intl Conf on Software Engineering*, Orlando, May 2002, IEEE CS Press, 83-93.
- A. van Lamsweerde & E. Letier, "Handling Obstacles in Goal-Oriented Requirements Engineering", *IEEE Transactions on Software Engineering, Special Issue on Exception Handling*, Vol. 26, No. 10, October 2000.
- E. Letier & A. van Lamsweerde, "Deriving Operational Software Specifications from System Goals", *Proc FSE'2002 - 10th ACM Conf on the Foundations of Software Engineering*, Charleston (South Carolina), November 2002.
- E. Letier and A. van Lamsweerde, "Reasoning about Partial Goal Satisfaction for Requirements and Design Engineering", *Proc FSE'04, 12th ACM Intl Symp. Foundations of Software Engineering*, Newport Beach (CA), Nov. 2004.

## Relevant papers (2)

- A. van Lamsweerde, "Elaborating Security Requirements by Construction of Intentional Anti-Models", *Proc ICSE'04 - 26th Intl Conf on Software Engineering*, Edinburgh, May. 2004, ACM-IEEE, 148-157.
- R. De Landtsheer & A. van Lamsweerde, "Reasoning about Confidentiality at Requirements Engineering Time", *Proc. ESEC/FSE'05, 13th ACM Intl Symp. on the Foundations of Software Engineering*, Lisbon, Sept. 2005, 41-49.
- A. van Lamsweerde, R. Darimont & E. Letier, Managing Conflicts in Goal-Driven Requirements Engineering, *IEEE Transactions on Software Engineering*, Vol. 24 No. 11, November 1998, pp. 908 - 926.
- C. Damas, B. Lambeau, P. Dupont & A. van Lamsweerde, "Generating Annotated Behavior Models from End-User Scenarios", *IEEE Transactions on Software Engineering*, Vol. 31, No. 12, December 2005, 1056-1073.
- H. Tran Van, A. van Lamsweerde, P. Massonet, Ch. Ponsard, "Goal-Oriented Requirements Animation", *Proc RE'04, 12th IEEE Joint Intl Requirements Engineering Conference*, Kyoto, Sept. 2004, 218-228.